

Microstructures in Shape-Memory Alloys

Rigidity, Flexibility and Some Numerical Experiments

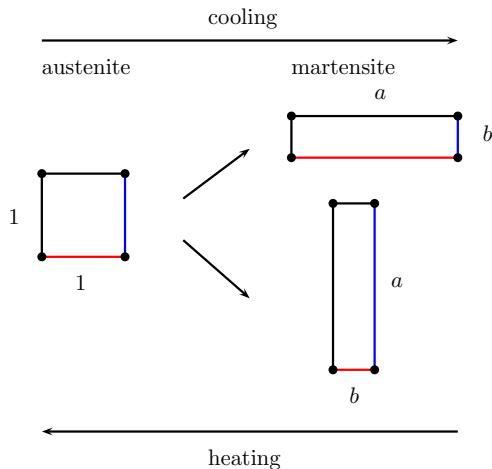
Angkana Rüland

(joint work with J. M. Taylor, Ch. Zillinger, B. Zwicknagl)



Polycrystals: Microstructure and Effective Properties Workshop
Oxford, 26-28.03.2018

Solid-Solid Phase Transformations in SMA



$$SO(2) \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}$$

$$SO(2) \begin{pmatrix} b & 0 \\ 0 & a \end{pmatrix}$$

$$SO(2) = \{2 \times 2 \text{ rotation matrices}\}$$



crossing twins

MPI MIS



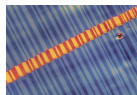
low hysteresis material



aust.-mart. interface



needles

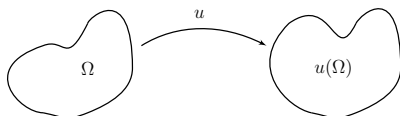


crossing twins

The Phenomenological Theory

Ball & James: Minimize

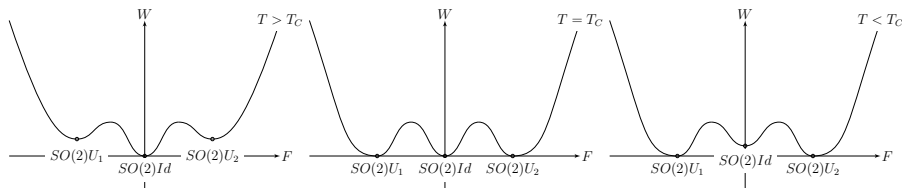
$$\mathcal{E}(\nabla u, T) = \int_{\Omega} \underbrace{W_T(\nabla u)}_{\text{energy density}} dx,$$



for deformations $u : \Omega \rightarrow \mathbb{R}^2$.

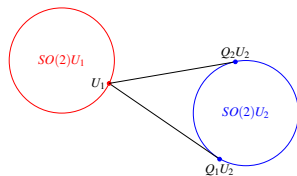
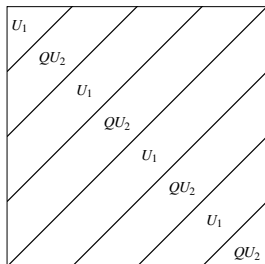
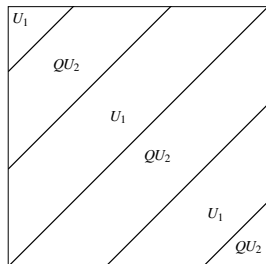
$W_T(QF) = W_T(F)$ for all rotations Q ,

$W_T(FR) = W_T(F)$ for all material symmetries R .




Differential Inclusion and Twins

$$\nabla u \in SO(2)U_1 \cup SO(2)U_2$$



rank-one connections

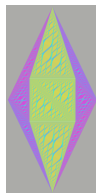
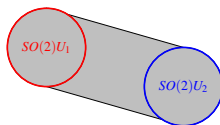
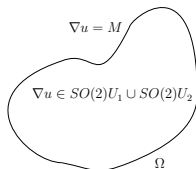

$$U_1 - Q_1U_2 = \sqrt{2} \frac{a^2 - b^2}{a^2 + b^2} \begin{pmatrix} a \\ -b \end{pmatrix} \otimes \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad Q_1 \in SO(2),$$
$$U_1 - Q_2U_2 = \sqrt{2} \frac{a^2 - b^2}{a^2 + b^2} \begin{pmatrix} a \\ b \end{pmatrix} \otimes \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \quad Q_2 \in SO(2).$$

Theorem

For any $\Omega \subset \mathbb{R}^2$ and any $M \in \text{int}(SO(2)U_1 \cup SO(2)U_2)^{lc}$ there exists a deformation u such that

$$\begin{aligned}\nabla u &\in SO(2)U_1 \cup SO(2)U_2 \text{ a.e. in } \Omega, \\ \nabla u &= M \text{ in } \mathbb{R}^2 \setminus \Omega.\end{aligned}$$

- Dacorogna-Marcellini (relaxation property & Baire category)
- Müller-Šverák (convex integration)



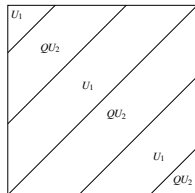
Q: Are these solutions physically relevant?

Theorem (Dolzmann-Müller, Rigidity)

Let $\Omega \subset \mathbb{R}^2$, $u : \Omega \rightarrow \mathbb{R}^2$ with $\nabla u \in BV(\Omega)$ and

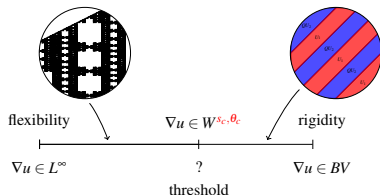
$$\nabla u \in SO(2)U_1 \cup SO(2)U_2 \text{ a.e. in } \Omega.$$

Then ∇u is (locally) a *laminate*.



Extensions:

- ▶ Dacorogna-Marcellini-Paolini ($O(2)$, $O(n)$),
- ▶ Kirchheim & Conti-Dolzmann-Kirchheim (cubic-to-tetragonal),
- ▶ R '16 (cubic-to-orthorhombic).



Q: Is there a threshold behaviour between rigidity and flexibility?

Linear vs. Non-Linear Elasticity

Stress-free states

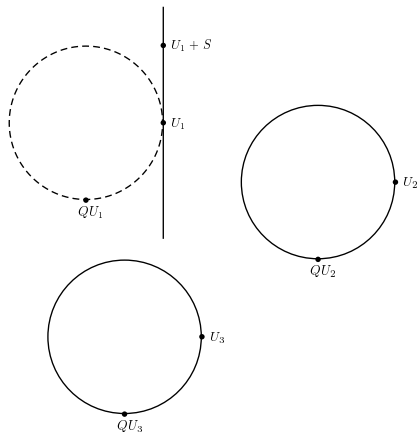
- ▶ non-linear:

$$(\nabla u)^t (\nabla u) \in \bigcup_{j=1}^k U_j^t U_j,$$

- ▶ linear:

$$e(\nabla v) := \frac{1}{2}(\nabla v + (\nabla v)^t) \\ \in \bigcup_{j=1}^k (U_j^t U_j - Id),$$

where $u(x) = x + \epsilon v(x)$.



- ▶ geometry linearises,
- ▶ material nonlinearity preserved.

Geometrically Linear m-Well Problems

- ▶ One-well problem:

$$e(\nabla v) := \frac{1}{2}(\nabla v + (\nabla v)^t) = 0 \text{ a.e. in } \Omega$$

$$\stackrel{\text{Liouville}}{\Rightarrow} \exists S \in \text{Skew}(n) : \nabla v = S \text{ a.e. in } \Omega.$$

- ▶ Two-well problem:

$$e(\nabla v) := \frac{1}{2}(\nabla v + (\nabla v)^t) \in \left\{ \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \right\} \text{ a.e. in } \Omega$$

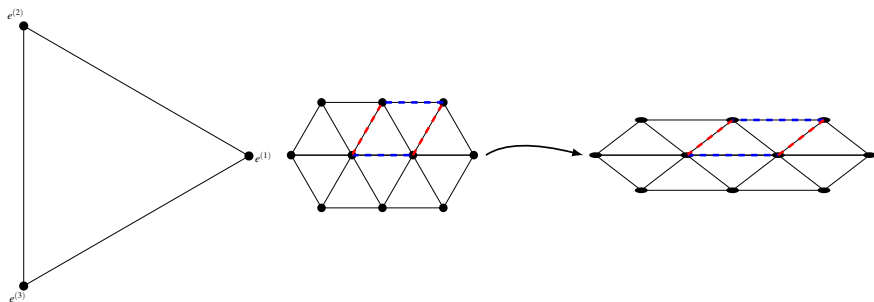
$$\stackrel{\text{Kohn}}{\Rightarrow} \exists f, g : \Omega \rightarrow \mathbb{R} \text{ s.t. } e_{11}(x_1, x_2) = f(x_1 + x_2)$$

$$\text{or } e_{11}(x_1, x_2) = g(x_1 - x_2), \quad x \in \Omega.$$

\Rightarrow Laminate.

Proof. Saint Venant compatibility: $\partial_{11}e_{22} + \partial_{22}e_{11} = \partial_{12}e_{12} \rightsquigarrow$ wave equation for e_{11} combined with two-valuedness: $e_{11} \in \{\pm 1\}$.

The Hexagonal-to-Rhombic Transformation

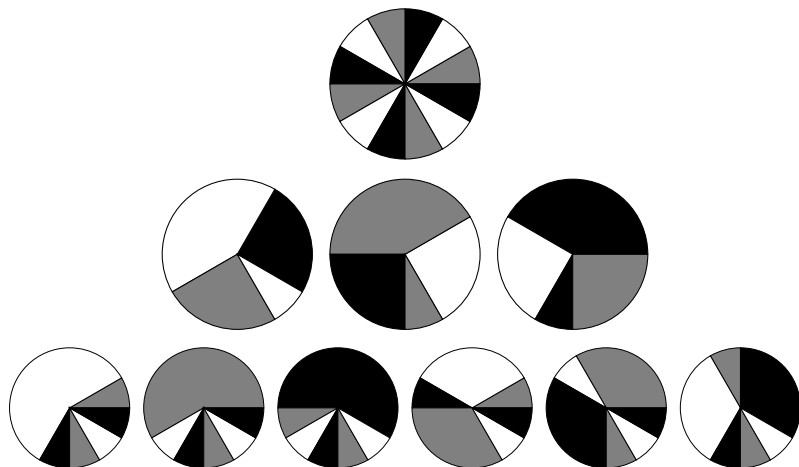


$$e(\nabla u) \in \left\{ \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \frac{1}{2} \begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}, \frac{1}{2} \begin{pmatrix} -1 & -\sqrt{3} \\ -\sqrt{3} & 1 \end{pmatrix} \right\}$$

($\text{Mg}_2\text{Al}_4\text{Si}_5\text{O}_{18}$, $\text{Pb}_3(\text{VO}_4)_2$)

Properties

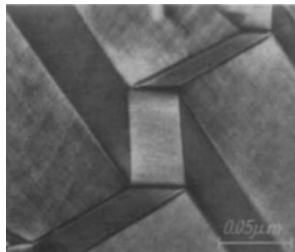
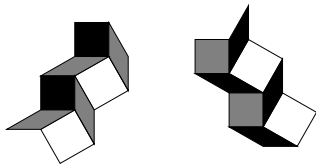
- ▶ $K^{lc} := \text{conv}\{e^{(1)}, e^{(2)}, e^{(3)}\}$ [Bhattacharya, 2D & trace-free]
- ▶ very flexible: many stress-free microstructures; **no** rigidity result known.



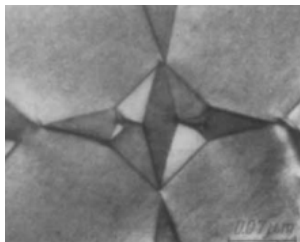
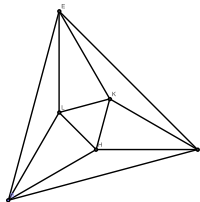
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Concatenated Microstructures

Crossing Twins:



Star Deformation:



[Kitano & Kifune]

The Main Result

Theorem (R.-Zillinger-Zwicknagl '16)

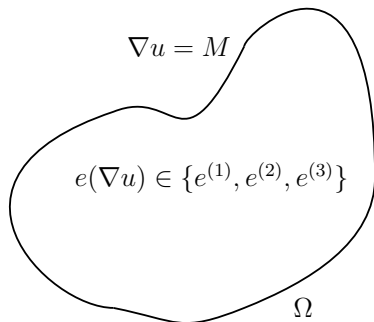
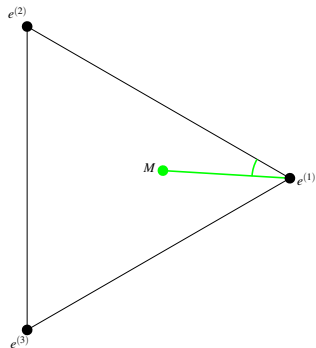
Let $\Omega \subset \mathbb{R}^2$ be a bounded Lipschitz domain. Let $K = \{e^{(1)}, e^{(2)}, e^{(3)}\}$ and let $e(M) = \frac{1}{2}(M + M^t) \in \text{intconv}(K)$. Then there exists $\theta_0 \in (0, 1)$ depending on $\frac{\text{dist}(e(M), \partial \text{conv}(K))}{\text{dist}(e(M), K)}$ and a deformation $u : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with $u \in W_{loc}^{1, \infty}(\mathbb{R}^2)$

$$\begin{aligned}\nabla u &= M \text{ a.e. in } \mathbb{R}^2 \setminus \Omega, \\ e(\nabla u) &\in K \text{ a.e. in } \Omega,\end{aligned}$$

and for all $s \in (0, 1)$, $p \in (1, \infty)$ with $0 < sp < \theta_0$

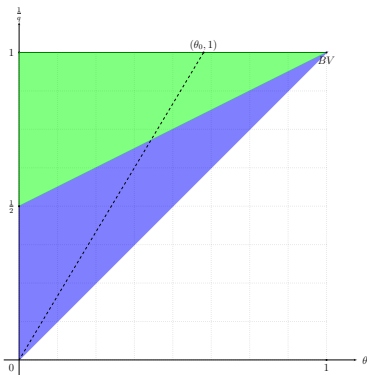
$$\nabla u \in W_{loc}^{s, p}(\mathbb{R}^2) \cap L^\infty(\mathbb{R}^2).$$

Remarks



- ▶ Solution has “fractal structure”.
- ▶ Argument exploits $2D$ structure.
- ▶ Argument exploits geometrically linear structure.
- ▶ No rigidity counterpart for this model.
- ▶ **Optimal** dependence of exponent?

Ingredients of the Proof – Interpolation



Theorem (Cohen-Dahmen-Daubechies-DeVore '03)

Let $p \in [2, \infty)$ and assume that for some $\theta \in (0, 1)$

$$\frac{1}{q} = \frac{1-\theta}{p} + \theta.$$

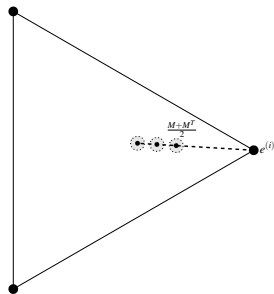
Then,

$$\|u\|_{W^{\theta,q}(\mathbb{R}^n)} \leq C \|u\|_{L^p(\mathbb{R}^n)}^{1-\theta} \|u\|_{BV(\mathbb{R}^n)}^{\theta}.$$

Remark:

- ▶ Original result in [CDDD03] formulated for Besov spaces.
- ▶ Similar (slightly weaker) result available for $p \in (1, 2)$.

Quantitative Convex Integration



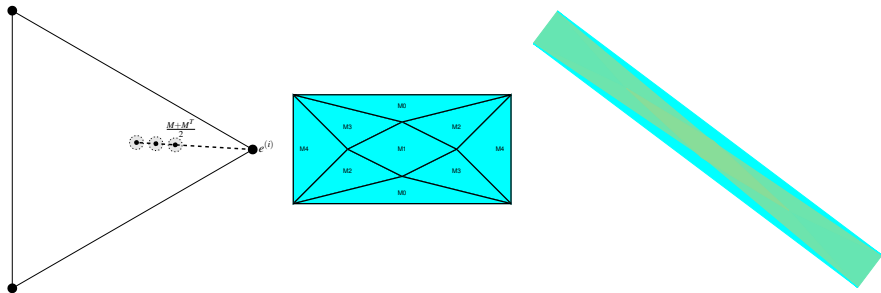
- 1 $M \in \mathbb{R}^{2 \times 2}$:
 $e(M) \in \text{intconv}(e^{(1)}, e^{(2)}, e^{(3)})$.
- 2 Replacement construction (similar to tent construction) along rank-one line (with skew control) $\rightsquigarrow M_1, M_2, M_3, M_4$.
- 3 Covering + iteration.

Proposition (Interpolation Bounds)

Let u_k be obtained from the convex integration algorithm. Then it is possible to ensure that $\|u_k\|_{W^{1,\infty}(\Omega)} \leq C$ and

$$\|\nabla u_{k+1} - \nabla u_k\|_{L^1(\mathbb{R}^2)} \leq C v_0^k,$$
$$\|\nabla u_{k+1} - \nabla u_k\|_{BV(\mathbb{R}^2)} \leq C \epsilon_0^{-k}.$$

Quantitative Convex Integration

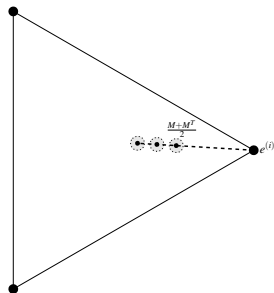


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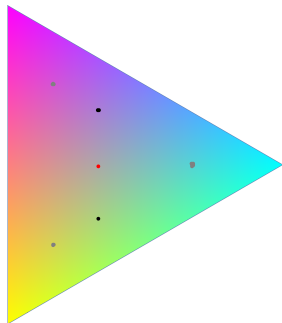
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Remarks and Improvements



Improvements in [RZZ '17]:

- ▶ Different convex integration scheme \Rightarrow **uniformity** of regularity exponent sp .
- ▶ Applies to a “general” set-up; includes **3D** geometrically linear transformations and $O(n)$ inclusions.

$$E_\epsilon = \min_{\nabla u = M \text{ a.e. in } \mathbb{R}^n \setminus \bar{\Omega}} \left\{ \int_{\Omega} \text{dist}^2(\nabla u, K) dx + \epsilon^2 \int_{\Omega} |\nabla^2 u|^2 dx \right\}.$$

Theorem (Taylor-R.-Zillinger '18)

Assume that there exist constants $C > 1$, $\mu \in (0, \frac{1}{2})$ such that for all $\epsilon \in (0, \epsilon_0)$ it holds $E_\epsilon \geq C\epsilon^{2\mu}$. Suppose that u is a solution to

$$\nabla u \in K \text{ a.e. in } \Omega, \quad \nabla u = M \text{ a.e. in } \mathbb{R}^n \setminus \bar{\Omega}.$$

If $v(x) := u(x) - Mx - b \in H^{s+1}(\mathbb{R}^n)$ for some $b \in \mathbb{R}^n$, $s \in \mathbb{R}$ and $\nabla v \in L^\infty(\mathbb{R}^n)$, then $s \leq \mu$.