

# Future stability of models of the universe

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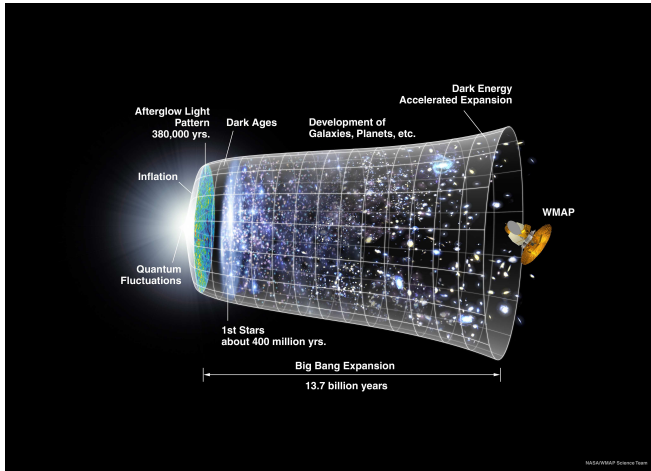
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# Introduction

The standard models of the universe

- ▶ satisfy the **cosmological principle** (i.e., they are spatially homogeneous and isotropic),
- ▶ are spatially flat,
- ▶ have matter content consisting of ordinary matter, dark matter and dark energy.

# Current model of the universe



Current model of the universe: NASA/WMAP Science Team.

## Questions

Since the universe is not exactly spatially homogeneous and isotropic, it is natural to ask: **are the standard models future stable?**

Since the assumption of spatial homogeneity and isotropy yields strong restrictions on the allowed topologies, it is also of interest to ask: **what are the restrictions on the global topology of the universe imposed by the constraint that what we observe seems to be close to a standard model?**

## Previous results

- ▶ Stability of de Sitter space in  $3 + 1$ -dimensions, etc., Helmut Friedrich, '86, '91.
- ▶ Stability of even dimensional de Sitter spaces, Michael Anderson '05.
- ▶ Stability in the non-linear scalar field case, H.R. '08.
- ▶ Einstein-Euler with a positive cosmological constant, Igor Rodnianski and Jared Speck, *preprint* '09.

# Einstein's equations

Einstein's equations:

$$G + \Lambda g = T,$$

where

- ▶  $(M, g)$  is a Lorentz manifold,
- ▶  $G = \text{Ric} - \frac{1}{2}Sg$  is the Einstein tensor,
- ▶  $\Lambda$  is the cosmological constant,
- ▶  $T$  is the stress energy tensor.

# Vlasov matter, mathematical structures

In the Vlasov setting, the relevant mathematical structures are

- ▶ the **mass shell**  $P$ ; the future directed unit timelike vectors in  $(M, g)$ ,
- ▶ the **distribution function**  $f : P \rightarrow [0, \infty)$ ,
- ▶ the **stress energy tensor**

$$T_{\alpha\beta}|_{\xi} = \int_{P_{\xi}} f p_{\alpha} p_{\beta} \mu_{P_{\xi}},$$

- ▶ the **Vlasov equation**

$$\mathcal{L}f = 0.$$

# The Einstein-Vlasov system

The Einstein-Vlasov system consists of the equations

$$\begin{aligned}G + \Lambda g &= T, \\ \mathcal{L}f &= 0\end{aligned}$$

for  $g$  and  $f$ . Note that the second equation corresponds to the requirement that  $f$  be constant along timelike geodesics.



## Induced initial data

Let  $(M, g, f)$  be a solution and  $\Sigma$  be a spacelike hypersurface in  $(M, g)$ . Then the **initial data induced on  $\Sigma$**  consist of

- ▶ the Riemannian metric induced on  $\Sigma$  by  $g$ , say  $\bar{g}$ ,
- ▶ the second fundamental form induced on  $\Sigma$  by  $g$ , say  $\bar{k}$ ,
- ▶ the induced distribution function  $\bar{f} : T\Sigma \rightarrow [0, \infty)$ .

Here

$$\bar{f} = f \circ \text{proj}_{\Sigma}^{-1},$$

where  $\text{proj}_{\Sigma} : P_{\Sigma} \rightarrow T\Sigma$  represents projection orthogonal to the normal.

## Constraint equations

Due to the fact that  $(M, g, f)$  solve the Einstein-Vlasov system,  $(\bar{g}, \bar{k}, \bar{f})$  have to solve the **constraint equations**:

$$\bar{r} - \bar{k}_{ij}\bar{k}^{ij} + (\text{tr}\bar{k})^2 = 2\Lambda + 2\rho^{\text{Vl}}, \quad (1)$$

$$\bar{\nabla}^j \bar{k}_{ji} - \bar{\nabla}_i(\text{tr}\bar{k}) = -\bar{J}_i^{\text{Vl}}. \quad (2)$$

Here

$$\rho^{\text{Vl}}(\xi) = \int_{T_\xi \Sigma} \bar{f}(\bar{\rho}) [1 + \bar{g}(\bar{\rho}, \bar{\rho})]^{1/2} \bar{\mu}_{\bar{g}, \xi}, \quad (3)$$

$$\bar{J}_i^{\text{Vl}}(\bar{X}) = \int_{T_\xi \Sigma} \bar{f}(\bar{\rho}) \bar{g}(\bar{X}, \bar{\rho}) \bar{\mu}_{\bar{g}, \xi}. \quad (4)$$

## Abstract initial data

**Abstract initial data** consist of

- ▶ an  $n$ -dimensional manifold  $\Sigma$ ,
- ▶ a Riemannian metric  $\bar{g}$  on  $\Sigma$ ,
- ▶ a symmetric covariant 2-tensor field  $\bar{k}$  on  $\Sigma$ ,
- ▶ a function  $\bar{f} : T\Sigma \rightarrow [0, \infty)$  (belonging to a suitable function space),

all assumed to be smooth and such that the constraint equations (1) and (2) are satisfied.

## Developments

Given abstract initial data, a **development** is

- ▶ a solution  $(M, g, f)$  to the Einstein-Vlasov system, and
- ▶ an embedding  $i : \Sigma \rightarrow M$

such that the initial data induced on  $i(\Sigma)$  by  $(M, g, f)$  correspond to the abstract initial data.

## Function spaces

If  $\Sigma$  is a compact manifold,  $\bar{\mathcal{D}}_\mu^\infty(T\Sigma)$  denotes the space of smooth functions  $f : T\Sigma \rightarrow \mathbb{R}$  such that

$$\begin{aligned} & \|\bar{f}\|_{H'_{V1,\mu}} \\ &= \left( \sum_{i=1}^j \sum_{|\alpha|+|\beta|\leq l} \int_{\bar{x}_i(U_i) \times \mathbb{R}^n} \langle \bar{\rho} \rangle^{2\mu+2|\beta|} \bar{\chi}_i(\bar{\xi}) (\partial_{\bar{\xi}}^\alpha \partial_{\bar{\rho}}^\beta \bar{f}_{\bar{x}_i})^2(\bar{\xi}, \bar{\rho}) d\bar{\xi} d\bar{\rho} \right)^{1/2} \end{aligned}$$

is finite for every  $l \geq 0$ .

## Bianchi initial data

Let

- ▶  $G$  be a 3-dimensional Lie group,
- ▶  $5/2 < \mu \in \mathbb{R}$ ,
- ▶  $\bar{g}$  and  $\bar{k}$  be a left invariant Riemannian metric and symmetric covariant 2-tensor field on  $G$  respectively,
- ▶  $\bar{f} \in \bar{\mathcal{D}}_{\mu}^{\infty}(TG)$  be left invariant and non-negative.

Then  $(G, \bar{g}, \bar{k}, \bar{f})$  are referred to as **Bianchi initial data** for the Einstein–Vlasov system, assuming they satisfy the constraints.

## Future stability of spatially locally homogeneous solutions

Let  $(G, \bar{g}_{\text{bg}}, \bar{k}_{\text{bg}}, \bar{f}_{\text{bg}})$  be Bianchi initial data for the Einstein–Vlasov system, where

- ▶ the universal covering group of  $G$  is not isomorphic to  $SU(2)$ ,
- ▶  $\text{tr } \bar{k}_{\text{bg}} = \bar{g}_{\text{bg}}^{ij} \bar{k}_{\text{bg},ij} > 0$ .

Assume that there is a cocompact subgroup  $\Gamma$  of the isometry group of the initial data. Let  $\Sigma$  be the compact quotient. Then there is an  $\epsilon > 0$  such that if  $(\Sigma, \bar{g}, \bar{k}, \bar{f})$  are initial data satisfying

$$\|\bar{g} - \bar{g}_{\text{bg}}\|_{H^5} + \|\bar{k} - \bar{k}_{\text{bg}}\|_{H^4} + \|\bar{f} - \bar{f}_{\text{bg}}\|_{H^4_{V1,\mu}} \leq \epsilon,$$

then the maximal Cauchy development of  $(\Sigma, \bar{g}, \bar{k}, \bar{f})$  is future causally geodesically complete.

## Question, topology

Assume that

- ▶ the observational data indicate that, to our past, the universe is well approximated by one of the standard models,
- ▶ interpreting the data in this model, we only have information concerning the universe for  $t \geq t_0$ ,
- ▶ there is a big bang,
- ▶ analogous statements apply to all observers in the universe (with the same  $t_0$ ).

The question is then: what conclusions are we allowed to draw concerning the global spatial topology of the universe?



# Ingredients

Assume we are given

- ▶ a standard model, characterised by an existence interval  $I$ , a scale factor  $a$  etc.,
- ▶ a  $t_0 \in I$ , which represents the time to the future of which we wish the approximation to be valid,
- ▶ an  $l \in \mathbb{N}$ , specifying the norm with respect to which we measure proximity to the standard model,
- ▶ an  $\epsilon > 0$ , characterising the size of the distance,
- ▶ a closed 3-manifold  $\Sigma$ .

## Construction

There is a solution  $(M, g, f)$  with the following properties:

- ▶  $(M, g, f)$  is a maximal Cauchy development,
- ▶  $(M, g)$  is future causally geodesically complete,
- ▶ there is a Cauchy hypersurface, say  $\bar{S}$ , in  $(M, g)$ , diffeomorphic to  $\Sigma$ ,
- ▶ given an observer  $\gamma$  in  $(M, g)$ , there is a neighbourhood, say  $U$ , of

$$J^-(\gamma) \cap J^+(\bar{S})$$

such that the solution in  $U$  is  $\epsilon$ -close to the standard model in a solid cylinder of the form  $[t_0, \infty) \times \bar{B}_R(0)$ ,

- ▶ all timelike geodesics in  $(M, g)$  are past incomplete,
- ▶ the solution is stable with these properties.