INTRODUCTION, DEFINITIONS CHARACTERISTIC IBVP FOR HYPERBOLIC SYSTEMS KREISS-LOPATINSKII CONDITION

CHARACTERISTIC IBVP'S AND MAGNETO-HYDRODYNAMICS

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Plan

1 INTRODUCTION, DEFINITIONS

2 Characteristic IBVP for hyperbolic systems

- Examples: Euler equations, MHD
- Anisotropic Sobolev spaces and MHD

3 Kreiss-Lopatinskii condition

• Analysis of Majda's example

KREISS-LOPATINSKII CONDITION

Consider the BVP

$$\begin{cases} Lu = F, & \text{in} \{x_1 > 0\}, \\ Mu = G, & \text{on} \{x_1 = 0\}. \end{cases}$$
(9)

- $L := \partial_t + \sum_{j=1}^n A_j \partial_{x_j}$, hyperbolic operator (with eigenvalues of constant multiplicity);
- A_j ∈ M_{N×N}, j = 1,...,n, and det A₁ ≠ 0 (i.e. non characteristic boundary);
- $M \in \mathbf{M}_{d \times N}$, $\operatorname{rank}(M) = d = \#\{\text{positive eigenvalues of } A_1\}.$

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- Let $u = u(x_1, x', t)$ $(x' = (x_2, \dots, x_n))$ be a solution to (9) for F = 0 and G = 0.
- Let û = û(x₁, η, τ) be Fourier-Laplace transform of u w.r.t. x' and t respectively (η and τ dual variables of x' and t respectively).
- \widehat{u} solves the ODE problem

$$\begin{cases} \frac{d\hat{u}}{dx_1} = \mathcal{A}(\eta, \tau)\hat{u}, & x_1 > 0, \\ M\hat{u}(0) = 0, \end{cases}$$
(10)

where
$$\mathcal{A}(\eta, \tau) := -(A_1)^{-1} \left(\tau I_n + i \sum_{j=2}^n A_j \eta_j \right).$$

Introduction, definitions Characteristic IBVP for hyperbolic systems Kreiss-Lopatinskii condition

Let $\mathcal{E}^{-}(\eta, \tau)$ be the stable subspace of (10).

• Kreiss-Lopatinskii condition (KL):

$$ker M \cap \mathcal{E}^{-}(\eta, \tau) = \{0\}, \quad \forall (\eta, \tau) \in \mathbb{R}^{n-1} \times \mathbb{C}, \, \Re \tau > 0.$$

$$\begin{aligned} & & \downarrow \\ & \forall (\eta, \tau) \in \mathbb{R}^{n-1} \times \mathbb{C}, \ \Re \tau > 0, \ \exists C = C(\eta, \tau) > 0 : \\ & |A_1 V| \le C |MV| \quad \forall V \in \mathcal{E}^-(\eta, \tau). \end{aligned}$$

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• Uniform Kreiss-Lopatinskii condition (UKL):

$$\exists C > 0 : \ \forall (\eta, \tau) \in \mathbb{R}^{n-1} \times \mathbb{C}, \ \Re \tau > 0 : |A_1 V| \le C |MV| \quad \forall V \in \mathcal{E}^-(\eta, \tau).$$

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LOPATINSKII DETERMINANT

For all (η, τ) ∈ ℝⁿ⁻¹ × C, ℜτ > 0, let {X₁(η, τ),...,X_d(η, τ)} be an orthonormal basis of E⁻(η, τ) (dim E⁻(η, τ) = rank M = d).
Constant multiplicity of the eigenvalues ⇒ X_j(η, τ), j = 1,...,d, and E⁻(η, τ) can be extended to all (η, τ) ≠ (0,0) with ℜτ = 0.

$$\Delta(\eta, \tau) := \det \left[M \left(X_1(\eta, \tau), \dots, X_d(\eta, \tau) \right) \right] \forall (\eta, \tau) \in \mathbb{R}^{n-1} \times \mathbb{C}, \ \Re \tau \ge 0.$$

$$(KL) \quad \Leftrightarrow \quad \Delta(\eta,\tau) \neq 0 \,, \quad \forall \Re \tau > 0, \forall \eta \in \mathbb{R}^{n-1} \,.$$

 $(UKL) \quad \Leftrightarrow \quad \Delta(\eta, \tau) \neq 0, \quad \forall \underline{\Re\tau \ge 0}, \forall \eta \in \mathbb{R}^{n-1}.$

Kreiss-Lopatinskii condition and well posedness

- 1. $\det A_1 \neq 0$ (i.e. non characteristic boundary)
 - NOT (KL) \Rightarrow (9) is ill posed in Hadamard's sense;
 - (UKL) $\Leftrightarrow L^2$ -strong well posedness of (9);
 - (KL) but NOT (UKL) ⇒ Weak well posedness of (9) (energy estimate with loss of regularity?).
- 2. $\det A_1 = 0$ (i.e. characteristic boundary)
 - NOT (KL) \Rightarrow (9) is ill posed in Hadamard's sense;
 - (UKL) + structural assumptions on $L \Rightarrow L^2$ -strong well posedness of (9).

STRUCTURAL ASSUMPTIONS

- [Majda & Osher, 1975]:
 - **(**) L symmetric hyperbolic, with <u>variable coefficients</u> +
 - Oniformly characteristic boundary +
 - (UKL) +
 - **(**) Several structural assumptions on L and M, among which that:

$$A(\eta) := \sum_{j=2}^{n} A_{j} \eta_{j} = \begin{pmatrix} a_{1}(\eta) & a_{2,1}(\eta)^{T} \\ a_{2,1}(\eta) & a_{2}(\eta) \end{pmatrix}$$

where $a_1(\eta)$ has only simple eigenvalues for $|\eta| = 1$. Satisfied by: strictly hyperbolic systems, MHD, Maxwell's equations, linearized shallow water equations. NOT satisfied by: 3D isotropic elasticity $(a_1(\eta) = 0_3)$.

- [Benzoni-Gavage & Serre, 2003]:
 - $\textcircled{O} L \text{ symmetric hyperbolic, with } \underline{\text{constant coefficients, }} M \text{ constant } +$
 - **2** (Uniformly) characteristic boundary, $ker A_{\nu} \subset ker M +$

(UKL) +

$$A(\boldsymbol{\eta}) = \begin{pmatrix} \mathbf{0} & a_{2,1}(\boldsymbol{\eta})^T \\ a_{2,1}(\boldsymbol{\eta}) & a_{2}(\boldsymbol{\eta}) \end{pmatrix}$$

with $a_2(\eta) = 0$.

<u>Satisfied</u> by: Maxwell's equations, linearized acoustics. NOT satisfied by: isotropic elasticity $(a_2(\eta) \neq 0)$.

• [Morando & Serre, 2005]: 2D, 3D linear isotropic elasticity.

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Majda's example

Initial-boundary value problem for the scalar wave equation:

$$\begin{cases} U_{tt} - U_{xx} - U_{yy} = 0 & \text{for } t > 0, \ x \in \mathbb{R}, \ y > 0, \\ \Gamma U_t + U_y = 0 & \text{for } y = 0, \\ i.c. & \text{for } t = 0, \end{cases}$$
(1)

where $\Gamma \in \mathbb{R}$ is a parameter.

Problem (1) was first introduced by A. Majda¹.

¹Compressible fluid flow and systems of conservation laws in several space variables, vol. 53 Appl. Math. Sciences, Springer-Verlag, NY 1984.

Energy method

Total energy

$$E(t):=\frac{1}{2}\int_{\mathbb{R}}\int_{0}^{\infty}\left(U_{t}^{2}+U_{x}^{2}+U_{y}^{2}\right)\,dxdy$$

Multiply $(1)_1$ by U_t and integrate:

$$\frac{d}{dt}E(t) = -\int_{y=0}^{\infty} U_t U_y \, dx = \Gamma \int_{y=0}^{\infty} U_t^2 \, dx$$

Then

- $\Gamma < 0$: the boundary condition removes energy (stabilizing effect)
- $\Gamma > 0$: the boundary condition adds energy (instability ???)

Boundary value problem

Reduce (1) to the boundary value problem for the scalar wave equation:

$$\begin{cases} U_{tt} - U_{xx} - U_{yy} = 0 & \text{for } t \in \mathbb{R}, \ x \in \mathbb{R}, \ y > 0, \\ \Gamma U_t + U_y = g & \text{for } y = 0. \end{cases}$$
(2)

Introduce the new unknowns:

$$v := U_t, \quad w := -U_x, \quad z := -U_y.$$

In terms of (v, w, z) problem (2) gives the **Euler-type system**

$$\begin{cases} v_t + w_x + z_y = 0, \\ w_t + v_x = 0, \\ z_t + v_y = 0, \\ \Gamma v - z = g, \\ y = 0. \end{cases}$$
(3)

In fact, we can write the system (3)

$$\begin{cases} v_t + w_x + z_y = 0, \\ w_t + v_x = 0, \\ z_t + v_y = 0, \\ \Gamma v - z = g, \\ y = 0. \end{cases}$$

in vector form as the "acoustic system"

$$\begin{cases} v_t + \operatorname{div}_{x,y} \cdot \begin{pmatrix} w \\ z \end{pmatrix} = 0, \\ \partial_t \begin{pmatrix} w \\ z \end{pmatrix} + \nabla v = 0, \quad y > 0, \\ \Gamma v - z = g \quad y = 0. \end{cases}$$

Second formulation of the problem

Let us introduce the new unknown $u = (u_1, u_2, u_3)^T$ defined by

$$u_1 = w, \quad u_2 = \frac{1}{2}(z - v), \quad u_3 = \frac{1}{2}(z + v),$$

that is

$$u_1 = -U_x, \quad u_2 = -\frac{1}{2}(U_t + U_y), \quad u_3 = \frac{1}{2}(U_t - U_y).$$

In terms of u the Euler-type problem (3) reads

$$\begin{pmatrix} \partial_t & -\partial_x & \partial_x \\ -\partial_x & 2(\partial_t - \partial_y) & 0 \\ \partial_x & 0 & 2(\partial_t + \partial_y) \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = 0 \quad \text{if } y > 0 \,,$$
(4)

$$-(\Gamma+1)u_2 + (\Gamma-1)u_3 = g$$
 if $y = 0$

Denote by \hat{u} the Laplace-Fourier transforms of u in (t, x), with dual variables $\tau = \gamma + i\delta$ and η , for $\gamma \ge 1$ and $\delta, \eta \in \mathbb{R}$. We obtain from (4)

$$\begin{pmatrix} \tau & -i\eta & i\eta \\ i\eta & 2(\frac{d}{dy} - \tau) & 0 \\ i\eta & 0 & 2(\frac{d}{dy} + \tau) \end{pmatrix} \widehat{u} = 0 \quad \text{if } y > 0 \,, \tag{5a}$$
$$\beta \widehat{u^{\text{nc}}} = \widehat{g} \quad \text{if } y = 0 \,, \tag{5b}$$

where

$$\beta = (-(\Gamma + 1), \Gamma - 1), \qquad u^{\mathrm{nc}} = (u_2, u_3)^{\mathsf{T}}.$$

From the first (algebric) equation of (5a) we express \hat{u}_1 in terms of \hat{u}_2 , \hat{u}_3 and plug the resulting expression into the other two equations of (5a).

We obtain a system of O.D.E.s:

$$\begin{cases} \frac{\mathrm{d}}{\mathrm{d}y}\widehat{u^{\mathrm{nc}}} = \mathcal{A}(\tau,\eta)\widehat{u^{\mathrm{nc}}} & \text{if } y > 0 \,, \\ \beta \widehat{u^{\mathrm{nc}}} = \widehat{g} & \text{if } y = 0 \,. \end{cases}$$
(6)

Here

$$\mathcal{A}(\tau,\eta) := \begin{pmatrix} \mu & -m \\ m & -\mu \end{pmatrix}, \qquad \mu := \tau + m, \qquad m := \frac{\eta^2}{2\tau}.$$

A(τ, η) is (positively) homogeneous of degree 1 in (τ, η). To take this homogeneity into account, we define the hemisphere:

$$\Xi_1 := \left\{ (\tau, \eta) \in \mathbb{C} \times \mathbb{R} : \operatorname{Re} \tau \ge 0, \, |\tau|^2 + \eta^2 = 1 \right\}.$$

- The poles of symbol A(τ, η) on Ξ₁ are the points (τ, η) = (0, ±1) ∈ Ξ₁ (where the coefficient of û₁ in the first equation of (5a) vanishes).
- We set

$$\Xi := (0, \infty) \cdot \Xi_1.$$

We obtain a system of O.D.E.s:

$$\begin{cases} \frac{\mathrm{d}}{\mathrm{d}y}\widehat{u^{\mathrm{nc}}} = \mathcal{A}(\tau,\eta)\widehat{u^{\mathrm{nc}}} & \text{if } y > 0 \,, \\ \beta \widehat{u^{\mathrm{nc}}} = \widehat{g} & \text{if } y = 0 \,. \end{cases}$$
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Lopatinskiĭ condition

Stability / instability of (6) is detected by the Lopatinskiĭ condition.

$$\omega := -\sqrt{\tau^2 + \eta^2} = \begin{cases} \text{eigenvalue of } \mathcal{A}(\tau, \eta) \text{ with } \text{negative} \\ \text{real part,} & \text{Re } \tau > 0, \\ \text{continuous extension,} & \text{Re } \tau = 0. \end{cases}$$
$$E(\tau, \eta) := \left(\frac{\eta^2}{2}, \tau(\mu - \omega)\right)^{\mathsf{T}} \text{eigenvector of } \mathcal{A}(\tau, \eta) \text{ corresponding to } \omega$$

Definition

• The Lopatinskii "determinant" associated to (6) is defined by

$$\Delta(\tau,\eta) := \det\left[\beta E(\tau,\eta)\right] = (\tau - \omega)(\Gamma \tau + \omega). \tag{7}$$

• We say that the Lopatinskiĭ condition holds if

 $\Delta(\tau,\eta) \neq 0$ for all $(\tau,\eta) \in \Xi_1$ with $\operatorname{Re} \tau > 0$;

We say that the uniform Lopatinskiĭ condition holds if
 Δ(τ, η) ≠ 0 for all (τ, η) ∈ Ξ₁.

Definition

- If the Lopatinskii condition is not satisfied the problem is said violently unstable (Hadamard ill-posedness).
- If the uniform Lopatinskii condition holds then the problem is said uniformly stable.
- If the Lopatinskii condition holds but not uniformly the problem is said weakly stable.

Lemma [Lopatinskiĭ condition for (6)]

- (1) $\Gamma < 0$. Then $\Delta(\tau, \eta) \neq 0$ for every $(\tau, \eta) \in \Xi_1$. Problem (6) is uniformly stable.
- (2) $0 \leq \Gamma < 1$. Let us define $\Lambda := (1 \Gamma^2)^{-1/2}$. Then, for any $(\tau, \eta) \in \Xi_1$,

 $\Delta(\tau,\eta) = 0$ if and only if $\tau = \pm i\Lambda\eta$.

Problem (6) is **weakly stable**.

(3) $\Gamma \geq 1$. Problem (6) is **violently unstable**.

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 $\Delta(\tau,\eta) = 0$ if and only if $\tau = \pm i\Lambda\eta$.

Problem (6) is weakly stable.

(3) $\Gamma \geq 1$. Problem (6) is violently unstable.

The uniformly stable case $\Gamma < 0$

For $\tau = \gamma + i\delta$, where $\gamma \ge 1$ and $\delta, \eta \in \mathbb{R}$, set

$$\lambda(\tau,\eta) := (|\tau|^2 + \eta^2)^{\frac{1}{2}} = (\gamma^2 + \delta^2 + \eta^2)^{\frac{1}{2}}.$$

Introduce the weighted Sobolev space

$$H^s_{\gamma}(\mathbb{R}^2) := \left\{ u \in \mathcal{D}'(\mathbb{R}^2) : e^{-\gamma t} u \in H^s(\mathbb{R}^2) \right\},$$
$$\|u\|_{H^s_{\gamma}(\mathbb{R}^2)} := \frac{1}{2\pi} \|\lambda^s \widehat{e^{-\gamma t} u}\|_{L^2(\mathbb{R}^2)}, \qquad L^2_{\gamma}(\mathbb{R}^2) = H^0_{\gamma}(\mathbb{R}^2).$$

Theorem

Assume $\Gamma < 0$. For all $\gamma \ge 1$, if $u \in H^1(\mathbb{R}^3_+)$ is a solution to (4) the following estimate holds:

$$\gamma \|u\|_{L^{2}(\mathbb{R}^{+};L^{2}_{\gamma}(\mathbb{R}^{2}))}^{2} + \|u^{\mathrm{nc}}\|_{x_{2}=0}\|_{L^{2}_{\gamma}(\mathbb{R}^{2})}^{2} \lesssim \|g\|_{L^{2}_{\gamma}(\mathbb{R}^{2})}^{2}.$$

 \implies **No loss of regularity** from the boundary datum.

PROOF

Because of the direct estimate

$$\gamma \|u\|_{L^2(\mathbb{R}^+;L^2_\gamma(\mathbb{R}^2))}^2 \lesssim \|u^{\mathrm{nc}}|_{x_2=0}\|_{L^2_\gamma(\mathbb{R}^2)}^2\,,$$

it's enough to show:

$$\|u^{\rm nc}|_{x_2=0}\|_{L^2_{\gamma}(\mathbb{R}^2)} \lesssim \|g\|_{L^2_{\gamma}(\mathbb{R}^2)}.$$
(8)

Lemma

For all $(\tau_0, \eta_0) \in \Xi_1$, there exist a neighborhood \mathscr{V} of (τ_0, η_0) in Ξ_1 and a continuous invertible matrix $T(\tau, \eta)$ defined on \mathscr{V} such that

$$\forall \, (\tau,\eta) \in \mathscr{V} \setminus \underbrace{\{\tau=0\}}_{\text{pole of } \mathcal{A}}, \quad T^{-1}\mathcal{A}T(\tau,\eta) = \begin{pmatrix} \omega & z \\ 0 & -\omega \end{pmatrix}.$$

The first column of $T(\tau, \eta)$ is $E(\tau, \eta)$.

Since Ξ_1 is compact, there exists a finite covering $\{\mathscr{V}_1, \ldots, \mathscr{V}_J\}$ of Ξ_1 by such neighborhoods with corresponding matrices $\{T_1, \ldots, T_J\}$, and a smooth partition of unity $\{\chi_j(\tau, \eta)\}_{j=1}^J \in C_c^{\infty}(\mathscr{V}_j)$ such that $\sum_{j=1}^J \chi_j^2 = 1$ on Ξ_1 .

Define $\Pi_j := \{(\tau, \eta) \in \Xi : \exists s > 0, s \cdot (\tau, \eta) \in \mathscr{V}_j\}$ and $W(\tau, \eta, y) := \chi_j T_j(\tau, \eta)^{-1} \widehat{u^{\mathrm{nc}}}(\tau, \eta, y), \quad \forall (\tau, \eta) \in \Pi_j.$

Assume that $(\tau, \eta) \in \Pi_j$ and $\operatorname{Re} \tau > 0$. Then $\frac{\mathrm{dW}}{\mathrm{dy}} = T_j^{-1} \mathcal{A} T_j W$. Hence

$$\frac{\mathrm{d}\mathsf{W}_2}{\mathrm{d}y} = -\omega\mathsf{W}_2, \quad \Longrightarrow \ \mathsf{W}_2 = 0 \ (\operatorname{Re}\omega < \mathbf{0}).$$

Using the boundary equation (5b) $(\beta \widehat{u^{nc}} = \widehat{g})$, one has

$$\chi_j \widehat{g} = \beta T_j(\tau, \eta) \mathsf{W}(\tau, \eta, 0) = \underbrace{\beta E(\tau, \eta)}_{\Delta(\tau, \eta)} \mathsf{W}_1(\tau, \eta, 0).$$
(9)

Because ($\Gamma < 0$: uniform stability)

$$\Delta(\tau,\eta) \neq 0 \qquad \forall (\tau,\eta) \in \Xi_1,$$

 $\exists C_1, C_2 > 0: \quad C_1 \leq \Delta(\tau, \eta) \leq C_2 \qquad \forall (\tau, \eta) \in \Xi_1.$

Extend $\Delta(\tau, \eta)$ as a homogeneous function of degree 0; then

$$C_1 \leq \Delta(\tau, \eta) \leq C_2 \qquad \forall (\tau, \eta) \in \Xi.$$

From (9)

$$\begin{split} |\mathsf{W}_1(\tau,\eta,0)| \lesssim \big|\chi_j\widehat{g}(\tau,\eta)\big|. \\ \text{Therefore, for all } (\tau,\eta) \in \Pi_j \text{ with } \gamma = \operatorname{Re} \tau > 0, \\ \big|\chi_j\widehat{u^{\operatorname{nc}}}(\tau,\eta,0)\big| \lesssim \big|\chi_j\widehat{g}(\tau,\eta)\big|. \end{split}$$

Applying Plancherel's theorem yields

$$||u^{\mathrm{nc}}|_{x_2=0}||_{L^2_{\gamma}(\mathbb{R}^2)} \lesssim ||g||_{L^2_{\gamma}(\mathbb{R}^2)},$$

that is (8).

The uniformly stable case $\Gamma < 0$ (ibvp)

More in general, for the problem

$$\begin{cases} U_{tt} - U_{xx} - U_{yy} = F & \text{for } t \in \mathbb{R}, \ x \in \mathbb{R}, \ y > 0, \\ \Gamma U_t + U_y = 0 & \text{for } y = 0, \\ U = 0 & \text{for } t < 0, \end{cases}$$
(10)

where F is a given source term such that F = 0 for t < 0, one can obtain

Theorem

Assume $\Gamma < 0$. For all $m \ge 0$ and for $\gamma \ge 1$, if $u \in H^{m+1}_{\gamma}(\mathbb{R}^3_+)$ is a solution to (10) the following estimate holds:

$$\gamma \|u\|_{H^m_{\gamma}(\mathbb{R}^3_+)}^2 + \|u^{\mathrm{nc}}|_{x_2=0}\|_{H^m_{\gamma}(\mathbb{R}^2)}^2 \lesssim \|F\|_{H^m_{\gamma}(\mathbb{R}^3_+)}^2.$$

 \implies No loss of regularity from the source term.

The weakly stable case $0 < \Gamma < 1$

Theorem

Assume $0 < \Gamma < 1$. For all $\gamma \ge 1$, if $u \in H^2(\mathbb{R}^3_+)$ is a solution of (4) the following estimate holds:

$$\gamma \|u\|_{L^{2}(\mathbb{R}^{+};L^{2}_{\gamma}(\mathbb{R}^{2}))}^{2} + \|u^{\mathrm{nc}}\|_{x_{2}=0}\|_{L^{2}_{\gamma}(\mathbb{R}^{2})}^{2} \lesssim \|g\|_{H^{1}_{\gamma}(\mathbb{R}^{2})}^{2}.$$

 \implies Loss of regularity from the boundary datum.

For the proof it's enough to show the estimate:

$$\|u^{\rm nc}|_{x_2=0}\|_{L^2_{\gamma}(\mathbb{R}^2)} \lesssim \|g\|_{H^1_{\gamma}(\mathbb{R}^2)}.$$
(11)

PROOF

Recall that

$$\Delta(\tau,\eta) = 0$$
 if and only if $\tau = \pm i\Lambda\eta, \ (\tau,\eta) \in \Xi_1,$

where $\Lambda := (1 - \Gamma^2)^{-1/2}$.

Lemma

When $\tau = \pm i\Lambda\eta$, the eigenvalue ω is purely imaginary. Each of these roots is simple in the sense that, if $q = \pm\Lambda$, then there exists a neighborhood \mathscr{V} of $(iq\eta, \eta)$ in Ξ_1 and a C^{∞} -function h_q defined on \mathscr{V} such that

$$\Delta(\tau,\eta) = (\tau - iq\eta)h_q(\tau,\eta), \quad h_q(\tau,\eta) \neq 0 \quad \text{for all } (\tau,\eta) \in \mathscr{V}.$$
(12)

Since Ξ_1 is compact, there exists a finite covering $\{\mathscr{V}_1, \ldots, \mathscr{V}_J\}$ of Ξ_1 by such neighborhoods with corresponding matrices $\{T_1, \ldots, T_J\}$, and a smooth partition of unity $\{\chi_j(\tau, \eta)\}_{j=1}^J \in C_c^{\infty}(\mathscr{V}_j)$ such that $\sum_{i=1}^J \chi_i^2 = 1$ on Ξ_1 .

Again, define $\Pi_j := \{(\tau, \eta) \in \Xi : \exists s > 0, s \cdot (\tau, \eta) \in \mathscr{V}_j\}$ and

$$\mathsf{W}(\tau,\eta,y) := \chi_j T_j(\tau,\eta)^{-1} \widehat{u^{\mathrm{nc}}}(\tau,\eta,y), \quad \forall \ (\tau,\eta) \in \Pi_j.$$

Assume that $(\tau, \eta) \in \Pi_j$ and $\operatorname{Re} \tau > 0$. Then $\frac{\mathrm{d}W}{\mathrm{d}y} = T_j^{-1} \mathcal{A} T_j W$. Hence

$$\frac{\mathrm{d}\mathsf{W}_2}{\mathrm{d}y} = -\omega\mathsf{W}_2, \quad \Longrightarrow \quad \mathsf{W}_2 = 0 \quad (\operatorname{Re}\omega < \mathbf{0}).$$

Using the boundary equation (5b), one has

$$\chi_j \widehat{g} = \beta T_j(\tau, \eta) \mathsf{W}(\tau, \eta, 0) = \underbrace{\beta E(\tau, \eta)}_{\Delta(\tau, \eta)} \mathsf{W}_1(\tau, \eta, 0).$$
(13)

• If $\Delta(\tau, \eta) \neq 0$ for all $(\tau, \eta) \in \mathscr{V}_j$, then we proceed as in the previous regular case.

• If
$$(iq\eta, \eta) \in \mathscr{V}_j$$
, with $q = \pm \Lambda$, from (12)

$$\Delta(\tau,\eta) = (\tau - iq\eta)h_q(\tau,\eta), \quad h_q(\tau,\eta) \neq 0.$$
(14)

Extending $\Delta(\tau,\eta)$ to Π_j as a homogeneous function of degree 1, from (13), (14) we obtain

$$|(\tau - iq\eta)\mathsf{W}_1(\tau, \eta, 0)| \lesssim \lambda(\tau, \eta) |\chi_j \widehat{g}(\tau, \eta)|.$$

Therefore, for all $(\tau, \eta) \in \Pi_j$ with $\gamma = \operatorname{Re} \tau > 0$,

$$\gamma \left| \chi_j \widehat{u^{\mathrm{nc}}}(\tau, \eta, 0) \right| \lesssim \lambda(\tau, \eta) \left| \chi_j \widehat{g}(\tau, \eta) \right|.$$

Applying Plancherel's theorem yields

$$\gamma \| u^{\mathrm{nc}} \|_{x_2=0} \|_{L^2_{\gamma}(\mathbb{R}^2)} \lesssim \| g \|_{H^1_{\gamma}(\mathbb{R}^2)},$$

that is (11).

Calculations as in

- 2D compressible vortex sheets, linear stability: J.-F. Coulombel–P.S. Indiana Univ. Math. J., 53 (2004), 941–1012,
- 2D compressible elastic flows, linear stability: R.M.Chen–J.Hu–D.Wang, Adv. Math. 311 (2017), 18–60.

The weakly stable case $0 < \Gamma < 1$ (ibvp)

More in general, for the problem

$$\begin{cases} U_{tt} - U_{xx} - U_{yy} = F & \text{for } t \in \mathbb{R}, \ x \in \mathbb{R}, \ y > 0, \\ \Gamma U_t + U_y = 0 & \text{for } y = 0, \\ U = 0 & \text{for } t < 0, \end{cases}$$
(15)

where F is a given source term such that F = 0 for t < 0, one can obtain

Theorem

Assume $0 < \Gamma < 1$. For all $m \ge 0$ and for $\gamma \ge 1$, if $u \in H^{m+2}_{\gamma}(\mathbb{R}^3_+)$ is a solution to (15) the following estimate holds:

$$\gamma \|u\|_{H^m_{\gamma}(\mathbb{R}^3_+)}^2 + \|u^{\mathrm{nc}}\|_{x_2=0}\|_{H^m_{\gamma}(\mathbb{R}^2)}^2 \lesssim \|F\|_{H^{m+1}_{\gamma}(\mathbb{R}^3_+)}^2.$$

 \implies Loss of regularity from the source term.