

MEAN FIELD GAMES AND PDE'S IN INFINITE D.

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SUMMARY

1. INTRODUCTION
2. ∞D EQUATIONS
3. ANALYSIS ON $\mathcal{M}(\times 3)$
4. STATE OF THE “ART”
5. A DREAM?

1. INTRODUCTION

- DYNAMICAL EQUILIBRIUM MODELS FOR LARGE POPULATIONS (in some cases limits of N player Nash equilibria)
- INTRINSICALLY ∞D MODELS state of the population is a nonnegative bounded measure \mathcal{M}
- Finite D if finite state space or no common randomness
- EXAMPLES EXISTED IN ECON but simple except KRUSELL-SMITH
- EARLY 00's (2006 publication) J-M. Lasry-PL² MFG + monotonicity + MASTER EQ.
- LOTS OF MATH MATERIAL (3-4 meeting every year)
- MATHS, ENGINEERS, PHYSICISTS, ECO., FINANCE, COMPUTER SC.

2. ∞D EQUATIONS

- state of the population $m \in \mathcal{M}$
- state of an agent $x \in E$ (ex. $\mathbb{R}^d \rightarrow \mathcal{M}(\mathbb{R}^d)$)
- “value function” $U(x, m, t) \in \mathbb{R}$ (ex. $t \in [0, T_0], T_0 < \infty$)
- General form ($t \rightarrow T - t$)

$$\frac{\partial U}{\partial t} + D + T + N = 0$$

D : Decision block

T : Transport block

N : Noise block

a generic agent chooses a strategy which affects the value $U(D)$, those decision transport the measure $m(T)$, possibly in random settings (N)

$$U|_{t=0} = U_0(x, m)$$

Example: Finite horizon, single population, decision “à la Bellman”, no intertemporal preference rate, continuous state space, Brownian noises. . .

$$D = \sup_{\alpha \in A} \{-b_{\alpha}(x, m) \cdot \partial_x U - f_{\alpha}(x, m)\}$$

$$\alpha^* \max, \quad b^* = b_{\alpha^*}(x, m)$$

$$T = \langle \partial_m U, -\partial_x \cdot (b^* m) \rangle$$

$$N = -\left(\frac{\nu + \mu}{2}\right) \Delta_x U + \langle \partial_m U, -\left(\frac{\nu + \mu}{2}\right) \Delta_x m \rangle \\ + \mu \langle \partial_x \partial_m U, \cdot \partial_x U \rangle$$

ν variance of idiosyncratic noise

μ variance of common noise

$$\partial_t U + A(x, m, \partial_x U) + \langle \partial_m U, -\partial_x \cdot (B(x, m, \partial_x U) m) \rangle + N + 0$$

RKS: • KS model!

• see article Nobel Meeting: 150 years of Game Theory

3. ANALYSIS ON $\mathcal{M}(X \ni)$

total size pop. fixed \mathcal{P} , 3 choices

- calculus in the vector space \mathcal{M}
- calculus in $(\mathcal{M}, W_1), \mathcal{P}(W_1 \text{ or } W_2)$
- calculus on \mathcal{P}_2 or H limit of calculus on $(\mathbb{R}^d)^N / \mathcal{S}^N$ as $N \rightarrow +\infty$

Here $(x_1, \dots, x_N) \in (\mathbb{R}^d)^N$ identified with all permutations

$$\iff m = \frac{1}{N} \sum_{i=1}^N \delta_{x_i} \in \mathcal{P}$$

$$\iff X, R.V. \text{ s.t. } X = x_i \text{ with proba } 1/N$$

Facts: PDE's with symmetry lift to \mathcal{P}_2 or H , "Lip f^{ions} on $(\mathbb{R}^d)^N / \mathcal{S}^N$ " become Lip f^{ions} on H and Lip f^{ions} on \mathcal{P} , $\phi(X) = \phi(m)$ ($\mathcal{L}(X) = m$) and $\|\partial_m \phi\|^2$ is

$$E|\nabla_x \phi|^2 = \int |\nabla_x \frac{\partial \phi}{\partial m}|^2 m$$

Master Eq. on \mathcal{P} or on $H : \nabla_x U(X, \mathcal{L}(X)) = \tilde{U}(X)$

$$\frac{\partial \tilde{U}}{\partial t} + (A(X, \tilde{U}) \cdot \partial_x) \tilde{U} = B(X, \tilde{U}) - N$$

no regularization (few dim., “in m ”) Hilbertian formulation

Rk: Finite D

- Finite state space : $U\mathbb{R}^k \rightarrow \mathbb{R}^k$

$$\frac{\partial U}{\partial t} + (A(y, U) \cdot \partial_y) U = B(y, U) - N$$

non conservative hyperbolic system with (very) partial regularization

- No common noise ($\mu = 0$) $U(x, m(t), t) = u(x, t)$

$$\frac{\partial u}{\partial t} + A(x, \partial_x u, m) - \frac{\nu}{2} \Delta_x u = 0, u|_{t=0} = u_0$$

$$\frac{\partial u}{\partial t} + \partial_x \cdot (B(x \partial_x u, m)) + \frac{\nu}{2} \Delta m = 0, m|_{t=T} = m_0$$

4. STATE OF THE ART

“SMOOTH” DATA

- PL² course: locally well-posed, globally under some monotonicity condition

Ex.: (B, A) mon on \mathbb{R}^{2k} , U_0 mon on \mathbb{R}^k Lip. $\exists!$ U Lip., mon.

$$\frac{\partial U}{\partial t} + (A(y, U) \cdot \partial_y) U = B(y, U)$$

- in general non uniqueness but
- Ch. Bertucci-PL²: if U_0 Lip ; $\partial_x U_0(x, m)$ Lip on $\mathbb{R}^d \times \mathcal{P}_1$
THEN $\exists T_0 \leq +\infty$ s.t. $\exists!$ Lip. sol. on $[0, T](\forall 1 < T_0)$ thus Lip implies uniqueness
- IF $T \uparrow$, uniqueness is lost (possibly) when regularity is lost!

5. A DREAM?

- BEYOND $T_0 < \infty$?
- SET OF SOLUTIONS (definition?), AND RULES FOR THE GAME TO SELECT ONE SOL. ?
- numerical existence for the oil production model EDMOND (Y. Achdou, Ch. Bertucci, J-M. Lasry, PL², A. Rostand and J. Scheinkman)
- particular case: B. Seeger-PL² with decreasing data

$$U_0(y_1, \dots, y_N) \searrow \text{ in } y_i \forall i.$$