

Part A Numerical Analysis 2016 Q1 solution

Existence: Define $L_{n,k}(x) = \prod_{\substack{j=0 \\ j \neq k}}^n \frac{(x-x_j)}{(x_k-x_j)} \in \Pi_n$ for $k=0,1,\dots,n$

then $L_{n,k}(x_j) = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{o.w.} \end{cases}$ so $p(x) = \sum_{k=0}^n f_k L_{n,k}(x) \in \Pi_n$

satisfies $p(x_i) = f_i$, $i=0,1,\dots,n$ (*)

Uniqueness: Assume $p, q \in \Pi_n$ both satisfy the conditions (*), then let

$r = p - q \in \Pi_n$ so that $r(x_i) = f_i - f_i = 0$, $i=0,1,\dots,n$.

But $r \in \Pi_n$ therefore has at least $n+1$ points where it is zero $\Rightarrow r(x) = 0$ $\forall x$.

hence uniqueness

(Bookwork) [6 marks]

if $n=2$, $x_0=0, x_1=1, x_2=2$
 $f_0=0, f_1=1, f_2=-2$

the $p(x) = -x$ clearly satisfies

the conditions (*) and hence by the above is the unique Lagrange Interpolating polynomial for the given data

(easy example) [2 marks]

$q(x) = \alpha x(x-1)(x-2) - x$ must be the set of all cubics which interpolate the given data for any $\alpha \in \mathbb{R}$.

$q(x) = \alpha x^3 - 3\alpha x^2 + (2\alpha-1)x$, so $q'(x) = 3\alpha x^2 - 6\alpha x + (2\alpha-1)$

So $q'(x_0) = q'(0) = 1$ only if $\alpha=1$, so $q(x) = x^3 - 3x^2 + x$.

(unseen simple generalisation) [3 marks]

Assume $p, q \in \Pi_{n+1}$ both satisfy (*) and $p'(x_0) = q'(x_0) = f'_0 \in \mathbb{R}$.

$r = p - q \in \Pi_{n+1}$ satisfies $r(x_i) = 0$, $i=0,1,\dots,n$, $r'(x_0) = 0$

Applying the Mean Value Theorem (or Rolle's Theorem) in each interval (x_{i-1}, x_i) $i=1,\dots,n$ $\exists \xi_i$ s.t. $r'(\xi_i) = 0$, $i=1,\dots,n$

Hence $r' \in \Pi_n$ vanishes at ξ_i , $i=1,\dots,n$ and x_0 which are $n+1$ distinct points; hence $r'(x) = 0$ $\forall x$ and so r is constant, but zero at e.g. x_0 so $r \equiv 0$ and we have uniqueness [4 marks]

at A Num. Anal. 2016 Q1 Soln. Cont.

is the quadrature rule we need function $L_0, L_1, L_2 \in \Pi_2$ s.t.

$$L_0(0) = 1, L_0'(0) = 0, L_0(1) = 0 \Rightarrow L_0(x) = -(x-1)(x+1)$$

$$L_1(0) = 0, L_1'(0) = 0, L_1(1) = 1 \Rightarrow L_1(x) = x^2$$

$$L_2(0) = 0, L_2'(0) = 1, L_2(1) = 0 \Rightarrow L_2(x) = -x(x-1)$$

Then give $f(x_0), f(x_1), f'(x_0)$, $p(x) = f(x_0)(1-x^2) + f(x_1)x^2 + f'(x_0)(xx^2)$

is quadratic and satisfies $p(0) = f(0), p(1) = f(1), p'(0) = f'(0)$

The required quadrature rule is therefore

$$\begin{aligned} \int_0^1 f(x) dx &\approx \int_0^1 p(x) dx = f(0) \int_0^1 (1-x^2) dx + f(1) \int_0^1 x^2 dx + f'(0) \int_0^1 xx^2 dx \\ &= \frac{2}{3} f(0) + \frac{1}{3} f(1) + \frac{1}{6} f'(0) \end{aligned}$$

(Gauss generalisation: Hermite interpolation is described in lectures and Newton-Cotes quadrature, but not this hybrid) [7 marks]

$$\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos x dx = \frac{\pi}{2} \int_0^1 \cos\left(\frac{\pi}{2}t - \frac{\pi}{2}\right) dt$$

$(x = \frac{\pi}{2}t - \frac{\pi}{2})$

$$\frac{\pi}{2} \left[\frac{2}{3} \cos\left(-\frac{\pi}{2}\right) + \frac{1}{3} \cos(0) + \frac{1}{6} \frac{\pi}{2} \right] = \frac{\pi}{6} + \frac{\pi^2}{24}$$

quadrature since $\frac{d}{dt} \left[\cos\left(\frac{\pi}{2}t - \frac{\pi}{2}\right) \right] = -\frac{\pi}{2} \sin\left(\frac{\pi}{2}t - \frac{\pi}{2}\right)$ so $f'(0) = \frac{\pi}{2}$

and $p\left(\frac{\pi}{2}t - \frac{\pi}{2}\right)$ on $[0, 1]$ is $p(x)$ on $[-\frac{\pi}{2}, 0]$

(Seen in the context of Gauss Quadrature, but not for this type of rule) [3 marks]

Part A Numerical Analysis 2016 Q2 Solution

$Q \in \mathbb{R}^{n \times n}$
 Q is an orthogonal matrix if $Q^T = Q^{-1}$ [1 mark]

If $A \in \mathbb{R}^{n \times n}$, $A = QR$ is a QR factorization if $Q \in \mathbb{R}^{n \times n}$ is orthogonal and $R \in \mathbb{R}^{n \times n}$ is upper triangular. (Bookwork) [2 marks]

$Ax = b \Leftrightarrow QRx = b \Leftrightarrow Rx = Q^T b$ (*) so find x by performing back substitution with the upper triangular matrix R in (*). Note A nonsingular $\Rightarrow Q^T A = R$ is nonsingular as orthogonal matrices are nonsingular by definition. [2 marks]

$$A^2 y = c \Leftrightarrow QRQRy = c \Leftrightarrow RQRy = Q^T c$$

so solve $Rz = Q^T c$ by back substitution,

then $QRy = z$ so solve $Ry = Q^T z$ by back substitution. [2 marks]

(1st part on product, 2nd simple extension similar to what is described in lecture for Gauss elim.)

$A = LU$, $L \in \mathbb{R}^{n \times n}$ is lower triangular with 1's on the diagonal and $U \in \mathbb{R}^{n \times n}$ is upper triangular. (Bookwork) [2 marks]

performing Gauss elimination on B

$$\begin{bmatrix} 2 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & 1 & -4 \end{bmatrix} \rightarrow \frac{1}{2} \begin{bmatrix} 2 & 1 & 1 \\ 0 & -1/2 & 3/2 \\ 0 & 1/2 & -9/2 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 1 & 1 \\ 0 & -1/2 & 3/2 \\ 0 & 0 & -3 \end{bmatrix}$$

$$\text{so } L = \begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ 1/2 & -1 & 1 \end{bmatrix}; U = \begin{bmatrix} 2 & 1 & 1 \\ 0 & -1/2 & 3/2 \\ 0 & 0 & -3 \end{bmatrix}$$

(simple example) [4 marks]

$$\text{Solving } Ly = b = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \Rightarrow y_1 = 1 \\ \frac{1}{2}y_1 + y_2 = 0 \Rightarrow y_2 = -\frac{1}{2} \\ \frac{1}{2}y_1 - 1(y_2) + y_3 = 0 \Rightarrow y_3 = -1$$

$$\text{and } Ux = y = \begin{bmatrix} 1 \\ -1/2 \\ -1 \end{bmatrix} \Rightarrow \begin{aligned} 2x_1 + (2) + \left(\frac{1}{3}\right) &= 1 \Rightarrow x_1 = -\frac{2}{3} \\ -\frac{1}{2}x_2 + \frac{3}{2}\left(\frac{1}{3}\right) &= -\frac{1}{2} \Rightarrow x_2 = 2 \\ x_3 &= \frac{1}{3} \end{aligned}$$

(Standard matrix example) [3 marks]

set A Num. Anal, 2016 Q2. Soln Cont.

$$A_k \leftarrow A$$

for $k=1, 2, \dots$

$$A_k = L_k U_k$$

$$A_{k+1} = U_k L_k$$

and.

(Unseen, but essentially same as QR alg which is Bookwork) [3 marks]

for $B = \frac{1}{2}A = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ \frac{1}{2} & -1 & 1 \end{bmatrix} = \underbrace{\begin{bmatrix} 2 & 1 & 1 \\ 0 & -\frac{1}{2} & \frac{3}{2} \\ 0 & 0 & -3 \end{bmatrix}}_U \underbrace{\begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_L$ we have $B_2 = UL = \begin{bmatrix} 3 & 0 & 1 \\ \frac{1}{2} & -2 & \frac{3}{2} \\ -\frac{3}{2} & 3 & -3 \end{bmatrix}$ - (+)

And now apply Gershgorin's Theorem:

For any $A \in \mathbb{R}^{n \times n}$ every eigenvalue λ is contained in at least one of

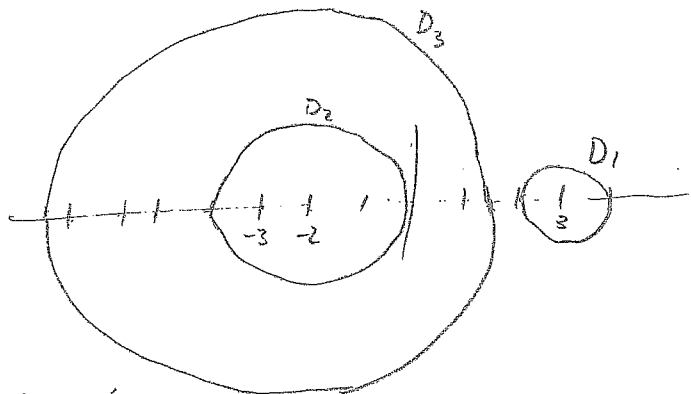
the discs $D_i = \left\{ z \in \mathbb{C} : |z - a_{ii}| \leq \sum_{\substack{j=1 \\ j \neq i}}^n |a_{ij}| \right\}$

The discs for B_2 from (+) are

D_1 centre 3 radius 1

D_2 centre -2 radius 2

D_3 centre -3 radius $\frac{9}{2}$



Now D_1 is disjoint from $D_2 \cup D_3$ so we can apply

Gershgorin's 2nd Theorem:

If any set of k discs is disjoint from the remaining discs then it must contain exactly k eigenvalues

Thus D_1 contains 1 eigenvalue which must therefore be real since B_2 is real

Thus by the above B_2 is similar to B which must therefore have a

eigenvalue in the interval $[2, 4]$

(Unseen use of Gershgorin's Theorem which are Bookwork)

[6 marks]

Part A Numerical Analysis 2016 Q3 Solution

$$\langle f, g \rangle = \int_{-1}^1 f(x)g(x) dx \quad (*)$$

$$P_0 = 1 \text{ and } P_1 = x - \frac{\langle x, 1 \rangle}{\langle 1, 1 \rangle} 1 = x \text{ as } \langle x, 1 \rangle = \int_{-1}^1 x \cdot 1 dx = 0$$

$$P_2 = x^2 - \frac{\langle x^2, x \rangle}{\langle x, x \rangle} x - \frac{\langle x^2, 1 \rangle}{\langle 1, 1 \rangle} 1 = x^2 - \frac{\int_{-1}^1 x^3 dx}{\int_{-1}^1 x^2 dx} x - \frac{\int_{-1}^1 x^2 dx}{\int_{-1}^1 1 dx} 1$$

\downarrow
 0 as $\int_{-1}^1 x^3 dx = 0$

$$= x^2 - \frac{2/3}{2} = x^2 - \frac{1}{3}$$

$$P_3 = x^3 - \frac{\langle x^3, x^2 - \frac{1}{3} \rangle}{\langle x^2 - \frac{1}{3}, x^2 - \frac{1}{3} \rangle} (x^2 - \frac{1}{3}) - \frac{\langle x^3, x \rangle}{\langle x, x \rangle} x - \frac{\langle x^3, 1 \rangle}{\langle 1, 1 \rangle} 1$$

\downarrow
 0 as $\int_{-1}^1 x^5 dx = 0 = \int_{-1}^1 x^3 dx$

$$= x^3 - \frac{\int_{-1}^1 x^3 x dx}{\int_{-1}^1 x x dx} = x^3 - \frac{2/5}{2/3} x = x^3 - \frac{3}{5} x$$

[A ; 6 marks]

Now since $P_R \in \Pi_R$, $\{P_0, P_1, \dots, P_R\}$ is a basis for Π_R so

$$\langle P_R, q \rangle = 0 \quad \forall q \in \Pi_{R-1} : \text{write } q = \sum_{j=1}^{R-1} \alpha_j P_j, \alpha_j \in \mathbb{R}$$

$$\text{so } \langle P_R, q \rangle = \langle P_R, \sum_{j=1}^{R-1} \alpha_j P_j \rangle = \sum_{j=1}^{R-1} \alpha_j \langle P_R, P_j \rangle = 0 \text{ as}$$

by symmetry
 and linearity in $\langle \cdot, \cdot \rangle$

$\{P_0, P_1, \dots, P_{k-1}\}$ are the orthogonal polynomials w.r.t. the inner product $\langle \cdot, \cdot \rangle$.

$$\text{So } 0 = \int_{-1}^1 P_R(x) P_0(x) dx = \int_{-1}^1 P_R(x) dx \text{ so } P_R \text{ changes sign at least once}$$

on $(-1, 1)$. Assume it changes sign at l distinct points r_1, \dots, r_l with $1 \leq l \leq k$ then let $q(x) = \prod_{i=1}^l (x - r_i)$ so that $P_R(x)q(x)$ does not change sign on $(-1, 1)$ which contradicts $\langle P_R, q \rangle = 0$ as proved above unless $l = k$; hence P_k has k simple roots in $(-1, 1)$

[B 6 marks]

$$\|f\| = \sqrt{\langle f, f \rangle}$$

[B 1 mark]

Part A Numerical Analysis 2016 Q3 Soln Cont

$W \subset V$ and $f \in V$, the $p \in W$ is a best approx if $\|f-p\| \leq \|f-q\| \quad \forall q \in W$
 [B: 1 mark]

$\langle f-p, q \rangle = 0 \quad \forall q \in W$ then for any $r = p+q \in W$

$$\|f-r\|^2 = \langle f-p-q, f-p-q \rangle = \underbrace{\langle f-p, f-p \rangle}_{\text{linear and symmetric}} - 2 \underbrace{\langle f-p, q \rangle}_0 + \langle q, q \rangle$$

$$\geq \langle f-p, f-p \rangle = \|f-p\|^2$$

so $\langle f-p, q \rangle = 0 \quad \forall q \in W \Rightarrow p \in W$ is a best approx to $f \in V$.
 [B; 3 marks]

$p = ax + b \in \Pi_1 = W$ is best approx to $x^3 \in \Pi_3 = V$ in \oplus if

$$\int_1^1 (x^3 - ax - b) \frac{1}{x} dx = 0 \quad \text{i.e.}$$

$$0a + 2b = 0 \Rightarrow b = 0$$

$$\frac{2}{3}a + 0b = \frac{2}{5} \Rightarrow a = \frac{3}{5}$$

$$\text{so } p(x) = \frac{3}{5}x.$$

[U, A 2 marks]

$$A = M_n \in \mathbb{R}^{n \times n}, \quad \langle A, B \rangle = \text{Trace}(B^T A) = \sum_{i=1}^n \sum_{k=1}^n b_{ki} a_{ki}$$

$$\|A\|^2 = \langle A, A \rangle = \sum_{i=1}^n \sum_{k=1}^n a_{ki}^2 \quad \text{so } \|A\| = \left(\sum_{k=1}^n \sum_{i=1}^n a_{ki}^2 \right)^{1/2}$$

i.e. the square root of the sum of the squares of all of the entries

[U, 2 marks]

$D \in W$ means $D \in \mathbb{R}^{n \times n}$ is diagonal so for any $A \in M_n$

$$\langle A, D \rangle = \sum_{i=1}^n \sum_{k=1}^n d_{ki} a_{ki} = \sum_{i=1}^n d_{ii} a_{ii} \quad \text{as } d_{ki} = 0 \text{ if } k \neq i$$

then $\langle A, D \rangle = 0$ when $a_{ii} = 0$ hence $D = \text{diag}(A)$ is the best approx to A from W since then $\langle A-D, D \rangle = 0 \quad \forall D \in W$

[Frobenius inner product has been = 4 marks]