

(a) Model I: $\frac{du}{dt} = f(u)$

Steady state: $\frac{du}{dt} = 0 \Rightarrow f(u^*) = 0$ □

Linear stability: Let $u = u_* + \tilde{u}$ where $|\tilde{u}| \ll u_*$

Then $\frac{d\tilde{u}}{dt} = f(u_* + \tilde{u}) = f(u_*) + \tilde{u} f'(u_*) + \text{h.o.t.}$

To first order, $\frac{d\tilde{u}}{dt} = \tilde{u} f'(u_*) \Rightarrow \tilde{u} = e^{f'(u_*)t}$

\therefore linearly stable if $f'(u_*) < 0$. □

Model II: $N_{t+1} = g(N_t)$

Steady state: $N_* = g(N_*)$ □

Linear stability: let $N_t = N_* + n_t$ where $|n_0| \ll N_*$

Then $N_{t+1} = g(N_* + n_t) = g(N_*) + n_t g'(N_*) + \text{h.o.t.}$

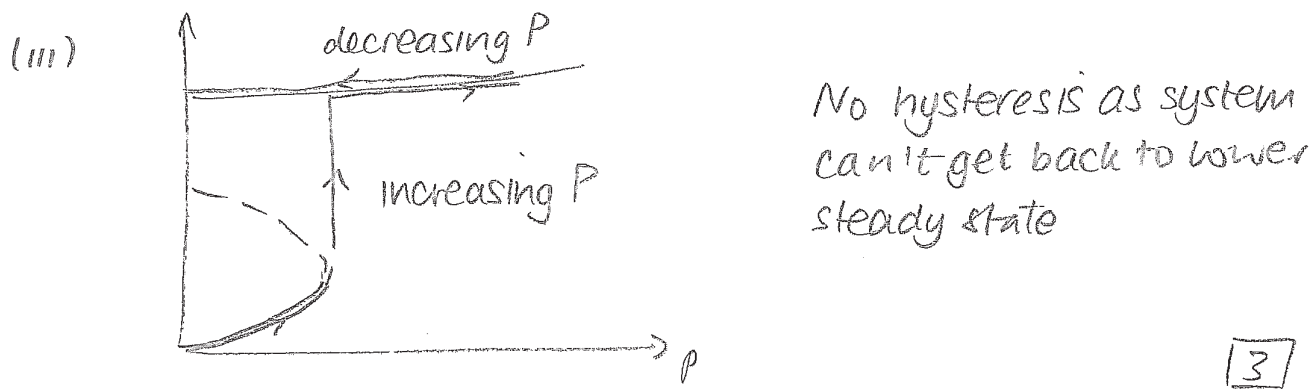
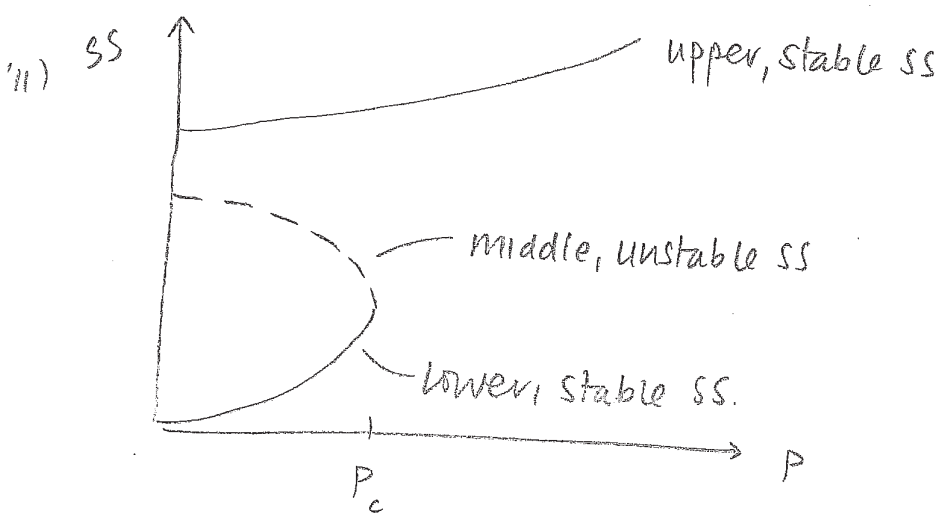
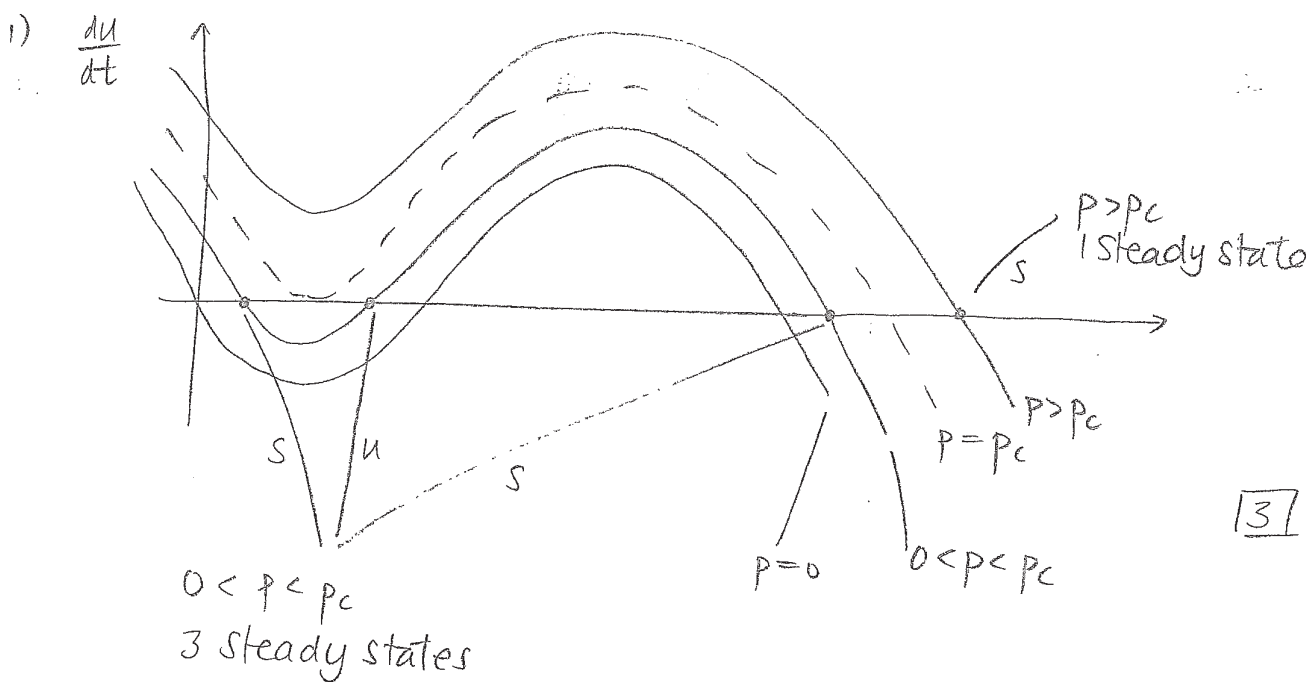
To first order, $n_{t+1} = n_t g'(N_*) \Rightarrow n_t = (g'(N_*))^t n_0$

\therefore linearly stable if $|g'(N_*)| < 1$. □

BOOKWORK - all seen before in lectures

TOTAL □ 6

b) $\frac{du}{dt} = u(u-1)(3-u) + P = f(u)$



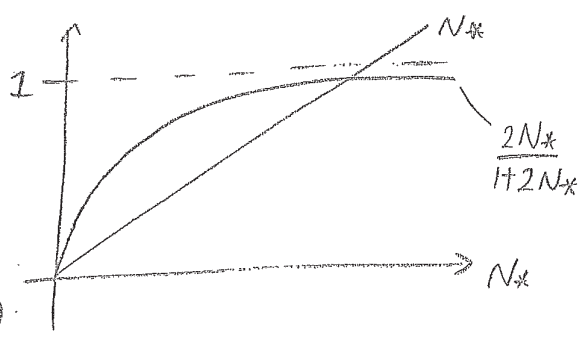
SIMILAR - similar examples covered in lectures / problem sheets

TOTAL [9]

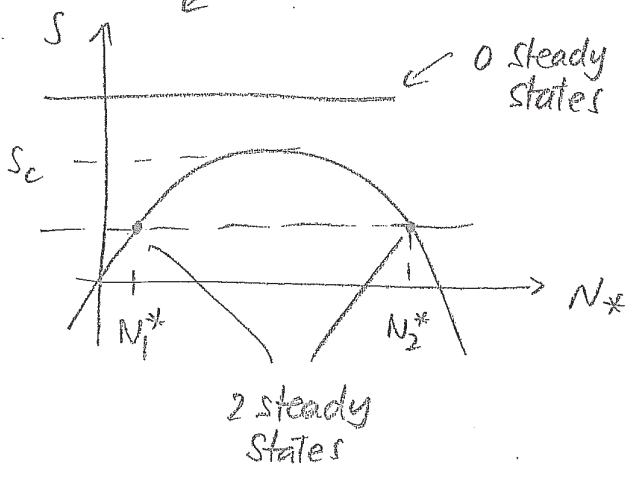
(i) $N^* = \frac{2N_t^2}{(N_t+s)(1+2N_t)}$, $N^* \neq 0 \Rightarrow (N^*+s)(1+2N^*) = 2N^*$ 2

(ii) Rearrange to write $s = s(N^*)$

$$s = \frac{2N^*}{1+2N^*} - N^*$$



use this to sketch $s(N^*)$

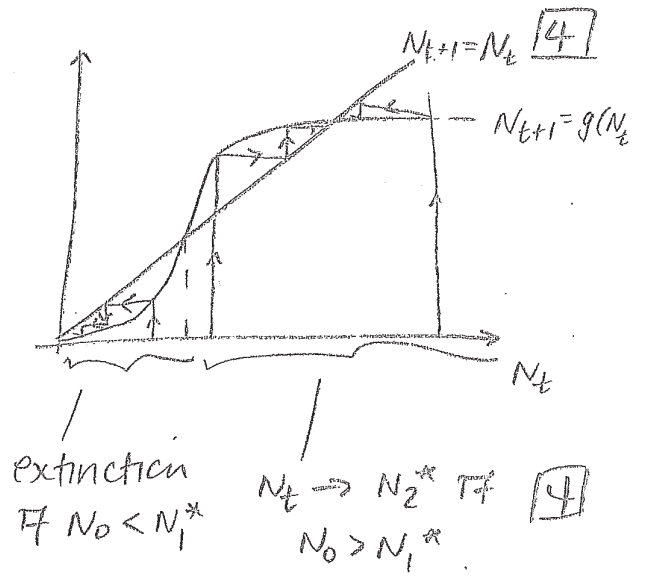
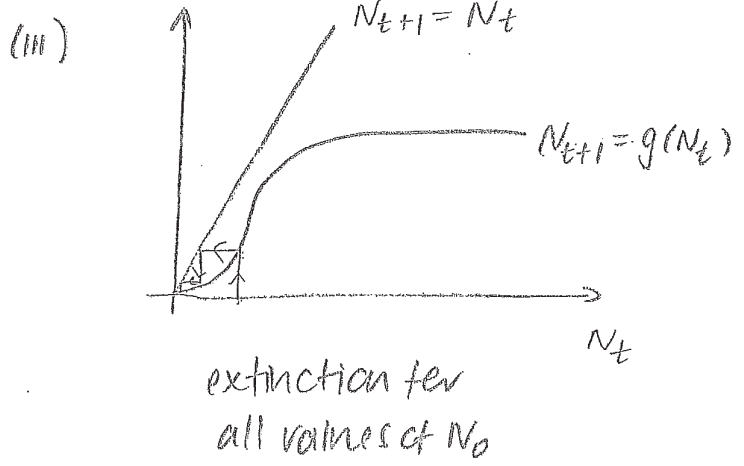


$$\frac{ds}{dN^*} = 0 \Rightarrow \frac{2(1+2N^*) - 4N^*}{(1+2N^*)^2} = 0$$

$$\Rightarrow 2 = (1+2N^*)^2$$

$$N^* = \frac{\sqrt{2}-1}{2}$$

$$\therefore s_c = s\left(\frac{\sqrt{2}-1}{2}\right) = \frac{(\sqrt{2}-1)^2}{2}$$



(i) SIMILAR

(ii) NEW RIDER

(iii) SIMILAR / NEW RIDER

TOTAL 10