

Interfaces in a Random Environment

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Overview

Random vs. periodic

- Introduction

- Perturbed gradient flow
- Forced mean curvature flow

- Results for minimizers of random energy

- The random obstacle model

- Results for the random obstacle model

• Existence of solutions
• Regularity of solutions
• Long time behavior

• Numerical simulations

- Work in progress: Multiscale (sub)solutions

- Open Problems

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 - Evolution of random obstacles (local interface motion)
 - Evolution of random obstacles (global evolution)
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 - Pinning (stationary solutions block interface motion)
 - Motion by mean curvature
 - Nonlocal motion
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Background: Perturbed gradient flow

Key features of Models:

- Evolution decreases free energy
 - Free energy is surface energy, i.e. area of interface
- Heterogeneities influence free energy **locally** (on small scale)

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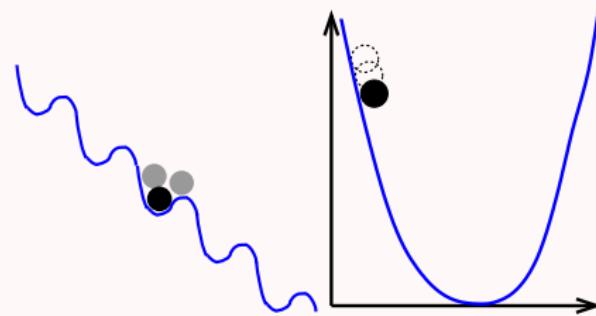
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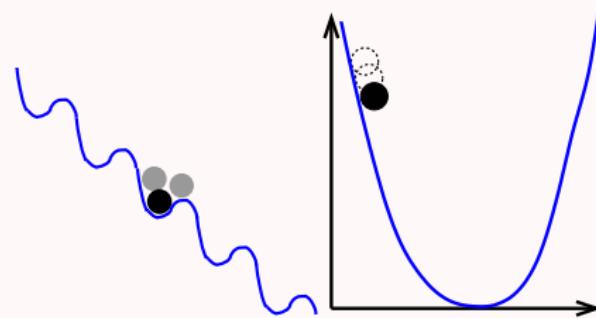
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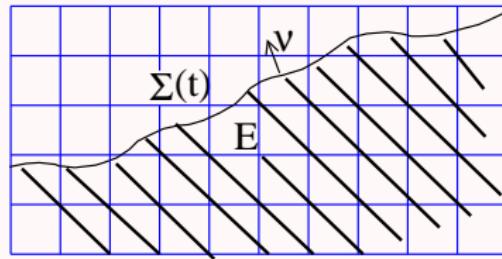
Zoom in on scale of heterogeneities

Perturbed Area Functional/Forced MCF

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Lipunov functional (formal):

$$\text{Area}(\Sigma) + \int_{\mathbb{R}^{n+1} \cap E} f(X) dX \quad \text{where } \Sigma = \partial E.$$

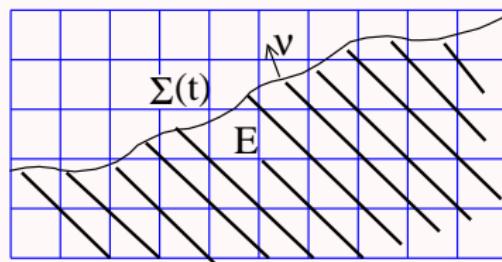


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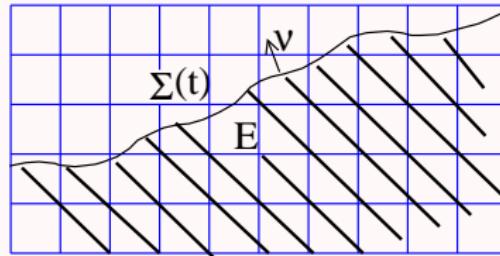


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Gradient flow:

$$V_X = \kappa_X + f(X), \quad X \in \Sigma(t) \subset \mathbb{R}^{n+1}$$

κ_X mean curvature of Σ at point X , V_X normal velocity at point X .

Minimisers of random of energy (with E. Orlandi)

$$\text{Area}(\Sigma \cap \Lambda) + \int_{\Lambda \cap E} f(X) dX \quad \text{where } \Sigma = \partial E.$$

$$F_\epsilon(u) = \int_{\Lambda} \left(\frac{\epsilon}{2} |\nabla u(x)|^2 + \frac{1}{\epsilon} W(u(x)) + \frac{\alpha_\epsilon}{\epsilon} h\left(\frac{x}{\epsilon}, \omega\right) u(x) \right) dx$$

h bounded random field, short correlation length

W double-well potential, two minimizers ± 1 .

- Idea: u^ϵ minimiser $\Rightarrow u^\epsilon \rightarrow \pm 1$ on $\mathbb{R}^{n+1} \setminus \Sigma$ as $\epsilon \rightarrow 0$, F_ϵ converges to (possibly anisotropic) area functional.

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- Replace gradient term by nonlocal term (Dirichlet form of fractional Laplacian) (D.-Orlandi in progress)

Forced MCF

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Related Homogenization Problem

Interface as level set: $\Sigma(t) = \{x \in \mathbb{R}^{n+1} : w(x, t) = 0\}$

$$V = \epsilon \kappa + f\left(\frac{x}{\epsilon}\right) \Rightarrow w_t = \epsilon \operatorname{tr} \left[\left(I - \frac{1}{|\nabla w|^2} \nabla w \otimes \nabla w \right) D^2 w \right] + f\left(\frac{x}{\epsilon}\right) |\nabla u|$$

$$V = c(\nu) \Rightarrow \bar{w}_t = c \left(\frac{\nabla \bar{w}}{|\nabla \bar{w}|} \right) |\nabla \bar{w}|$$

“Singular” Homogenization: Averaging *and* singular limit.

- Degenerate, nonlinear
- $f(x)$ may change sign

Forcing $f(x)$ strictly positive (+additional conditions), not random:

P.-L. Lions, P.E. Souganidis, (2005),

Additional conditions: Caffarelli, Monneau

Connection: Level sets evolve by (forced) MCF (Chen-Giga-Goto)

Random case mostly open! Look for simplified model:

Random Obstacle Model.

Related work

- Physics: QEW ($\partial_t u = \Delta u + f(x, u, \omega)$)
 - S. Brazovsii, Th. Nattermann (et al.) (FRG)
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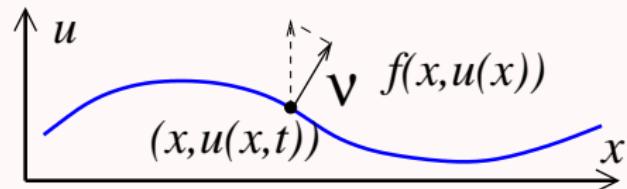
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Forced Mean Curvature Flow/Semilinear "Approx."

Forced MCF (Gradient flow of perturbed surface energy):

$$V_{x,u} = \kappa_{x,u} + f(x, u) + F$$



If surface is graph $(x, u(x, t))$ then $u(x, t) : \mathbb{R}^n \times \mathbb{R}_+ \rightarrow \mathbb{R}$ solves

$$\partial_t u = \sqrt{1 + |\nabla u|^2} \operatorname{div} \left(\frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) + \sqrt{1 + |\nabla u|^2} (f(x, u) + F).$$

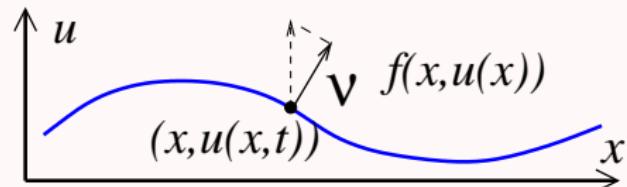
gradient small, then (heuristic) approximation: **semilinear PDE**

$$u_t = \Delta u + f(x, u) + F, \quad F \geq 0 : \text{external driving force.}$$

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$$\partial_t u = \sqrt{1 + |\nabla u|^2} \operatorname{div} \left(\frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) + \sqrt{1 + |\nabla u|^2} (f(x, u) + F).$$

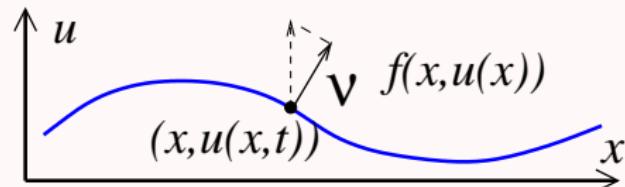
gradient small, then (heuristic) approximation: **semilinear PDE**

$$u_t = \Delta u + f(x, u) + F, \quad F \geq 0 : \text{external driving force.}$$

Forced Mean Curvature Flow/Semilinear "Approx."

Forced MCF (Gradient flow of perturbed surface energy):

$$V_{x,u} = \kappa_{x,u} + f(x, u) + F$$



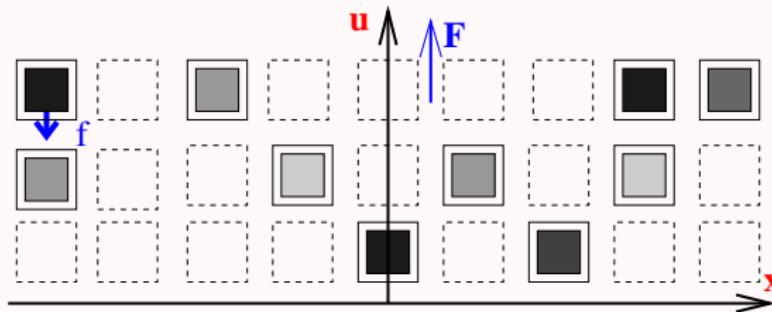
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The Random Obstacle Model

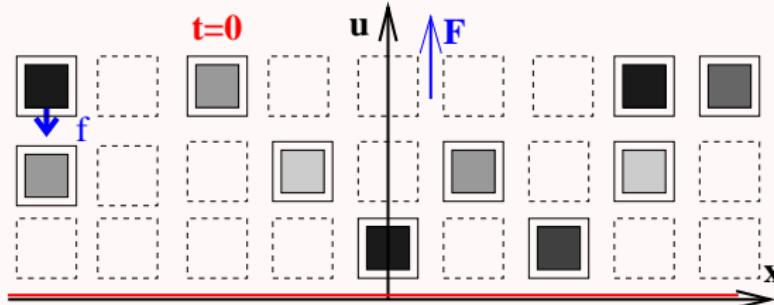


- Obstacles: $f(x, u, \omega) \leq 0$
- strength random
- $f(x, u, \omega) = c \geq 0$ else
- "driving" force $F \geq 0$

$$\begin{aligned}\partial_t u(x, t, \omega) &= \Delta u(x, t, \omega) + f(x, u(x, t, \omega), \omega) + F \quad \text{on } \mathbb{R}^n \\ u(x, 0) &= 0\end{aligned}$$

Quenched Edwards-Wilkinson Model (QEW)

The Random Obstacle Model

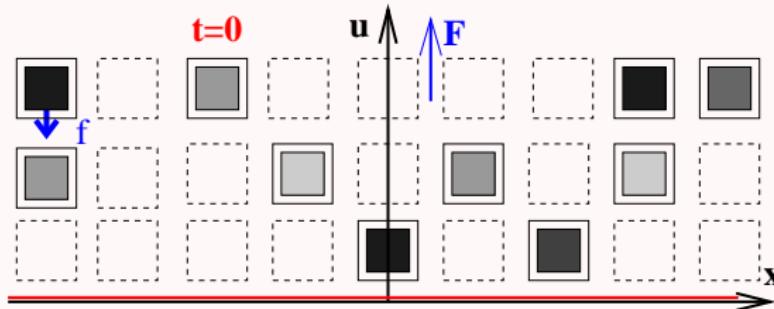


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Important: Comparison Principle.

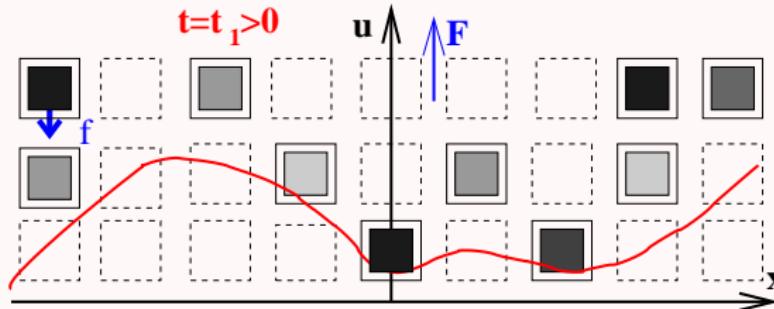
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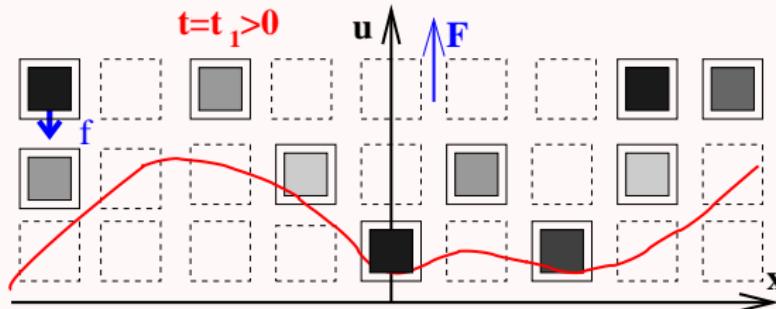
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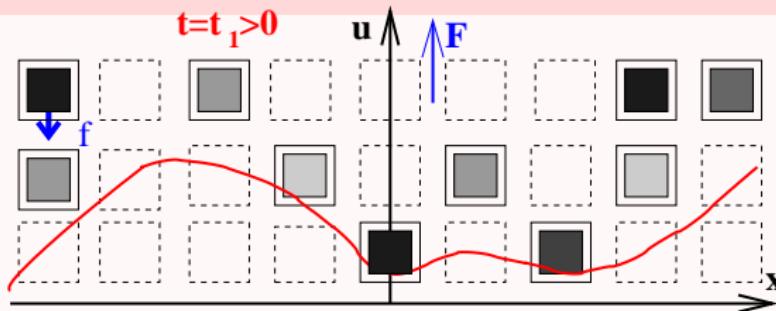
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- $0 < F < F_*$: nonnegative stationary solution exists
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The Random Obstacle Model



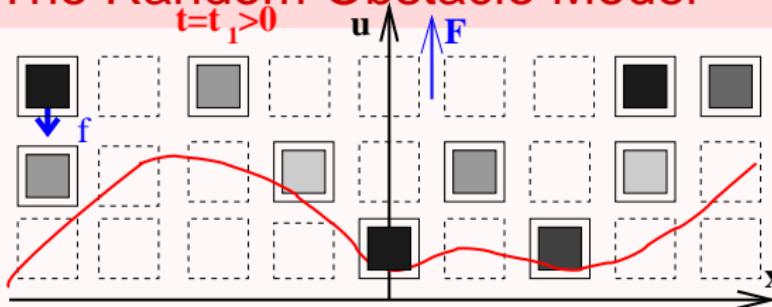
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The Random Obstacle Model

$t=t_1 > 0$



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"effective velocity" on scale $\tau = \epsilon^{-1}t$, $y = \epsilon^{-1}x$. $\partial_\tau \bar{v}(y, \tau, \omega) = \bar{c}$

- Periodic: Such F_* exists, velocity $\sim \sqrt{F - F_*}$
- $F = F^*$? Periodic: Stationary solution due to compactness (D.-Yip)

Random vs. Periodic: Loss of compactness and behaviour at critical forcing in zero dim.

What happens at $F = F_*$?

- Periodic environment (compactness): Stationary solution exists as u.c. limit of stationary solutions for $F < F_*$.
- Random environment: Zero Velocity **AND** non-existence of stationary solution possible

$$\dot{X} = F + \sin(2\pi X)$$

$$F_* = 1$$

χ cut-off, $\chi = 1$ near $x = 0$, $\chi = 0$ on $\mathbb{R} \setminus [-1/8, 1/8]$.

Z_i i.i.d., $Z_i > 0$ a.s., $\mathbb{E} Z_0 = \infty$. (square-root behavior)

Time to cross obstacle at i : $\sim Z_i$

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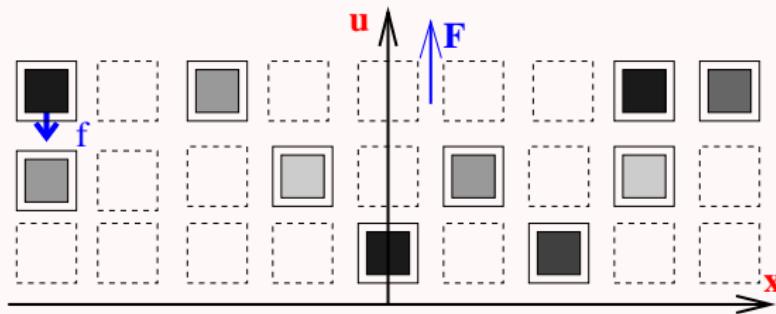
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Random Obstacle Model: Precise Setting



$$\begin{aligned}\partial_t u(x, t, \omega) &= \Delta u(x, t, \omega) + f(x, u(x, t, \omega), \omega) + F \quad \text{on } \mathbb{R}^n \\ u(x, 0) &= 0\end{aligned}$$

$F \geq 0$, (driving force), ϕ mollifier of $1_{[-\delta, \delta]^{n+1}}(x, u)$,

$$f(x, u) = \sum_{(i,j) \in \mathbb{Z}^n \times (\mathbb{Z} + \frac{1}{2})} (\mathbb{E}(\ell_{ij}) - \ell_{i,j}(\omega)) \phi(x - i, u - j)$$

$(\ell_{i,j}(\omega))_{(i,j) \in \mathbb{Z}^n \times (\mathbb{Z} + \frac{1}{2})}$ are a family of i.i.d. exponential random variables.

Nonnegative Solutions for R. O. M.

$$0 = \Delta u(x, \omega) + f(x, u(x, \omega), \omega) + F \quad \text{on } \mathbb{R}^n, \quad u(x) \geq 0 \quad (*)$$

Theorem (H. B., J. Coville, S. Luckhaus)

Let $n = 1$ and u solve $(*)$. Then there exist $F_0 > 0$ such that for $F > F_0$ there is almost surely no solution of $(*)$.

See also [1] and [2] and [3] for related results.

Let $\omega \in \Omega$. Then we can show that for $F < F_0$ there has almost surely a solution $u(\cdot, \omega)$ to $(*)$ with $u(\cdot, \omega) \geq 0$ for all $x \in \mathbb{R}$.

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Barrier for/limit of

$$\partial_t u(x, t, \omega) = \Delta u(x, t, \omega) + f(x, u(x, t, \omega), \omega) + F \quad \text{on } \mathbb{R}^n, \quad u(x, 0) = 0$$

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Let $n = 1, 2$. There ex. $0 < F_1$ such that for $0 < F < F_1$, $(*)$ has almost surely a solution with $\mathbb{E}[u(x, \omega)] = c < \infty$ for all $x \in \mathbb{R}^n$.

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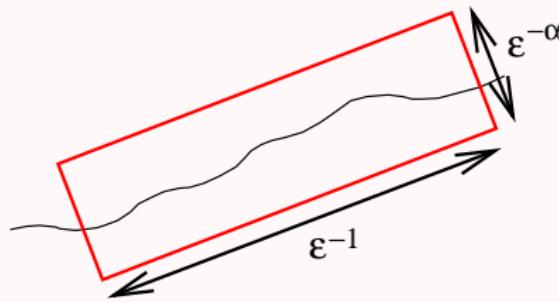
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Positive speed and oscillation

- Curve **oscillates sublinearly** in moving frame (kinetic scaling)
 $t = \epsilon^{-1} T, r = \epsilon^{-1} x.$)

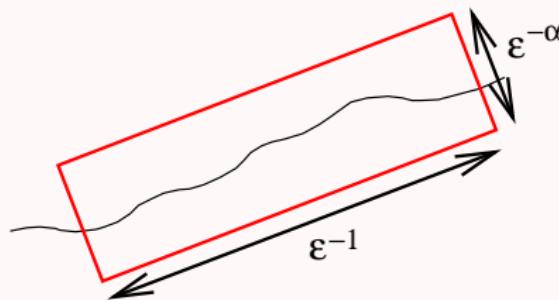


- positive average speed of subsolutions

Idea: Fastest plane below and slowest plane above graph (in ϵ^{-1} -box) have same average speed, which is deterministic (Obstacles i.i.d.)

Positive speed and oscillation

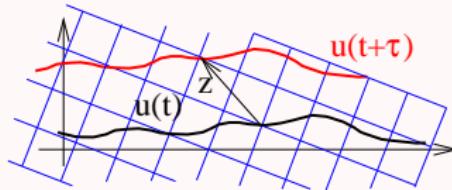
- Curve **oscillates sublinearly** in moving frame (kinetic scaling $t = \epsilon^{-1}T, r = \epsilon^{-1}x.$) May not be true in general



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Mean Curvature Flow with periodic forcing



- Effective velocity: Bounds in frame moving with velocity $c(\nu)$, continuous in ν
- Special solutions (Pulsating wave)

N. D., G. Karali, N.K. Yip, Pulsating Wave for Mean Curvature Flow in Inhomogeneous Medium, EJAM 19 (2008) , 661-699.

Assumption: Forcing small in C^1

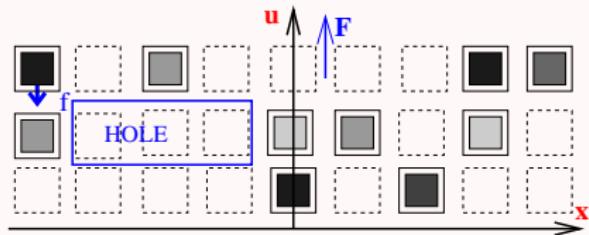
- Uniform motion
- Flat on $O(1)$ scale (L^∞ bound in moving frame)

Subsolution via Allen-Cahn kinks/bubbles

Random nonlinearity **bounded** but **changes sign**

$$\partial_t u(x, t, \omega) = \Delta u - \underbrace{W'(u) + \hat{F}}_{\leq f(x, u, \omega) + F}$$

$f(u) = -\|f(x, u, \omega)\|_\infty$ on height of obstacles except on "holes", smooth by suitable interpolation :

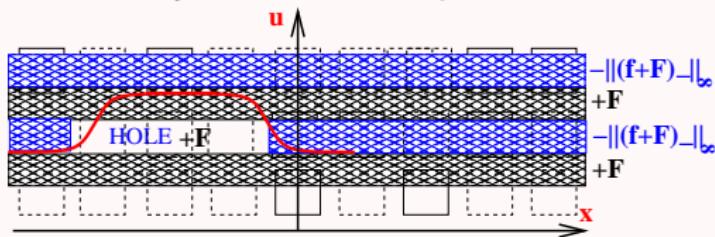


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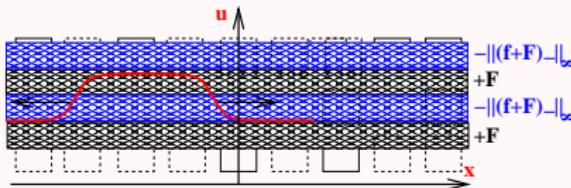
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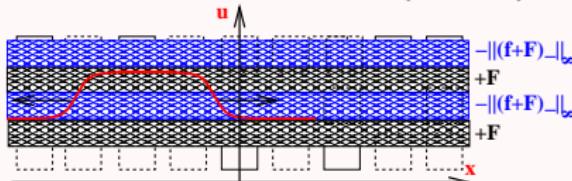


Radially symmetric "bubble-like" initial data: $u(x) > 1/2$ for $|x| < R$, $u(x) < -1/2$ for $|x| > R + K$, then for some K (depending on $W(\cdot)$) and R , F large, the **bubble grows** linearly in time. (" $F > 1/R = \kappa$ ")

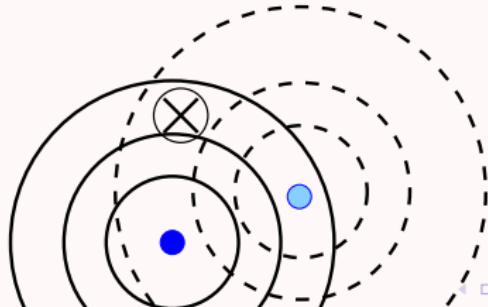
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Speed: \sim expectation of distance of z -axis to holes (Obstacles iid!)



Sketch of techniques

Non-Existence

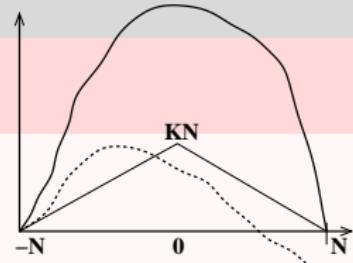
- Consider Dirichlet-problem on $[-N, N]$, discretize
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Analyst's approach: **Fixed point iteration**



Sketch of techniques

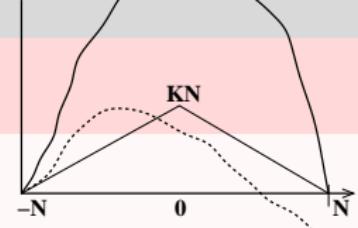
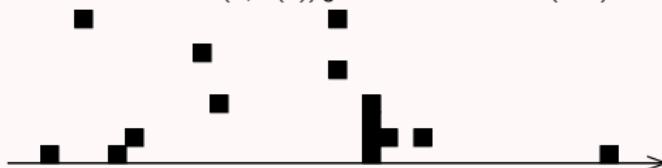
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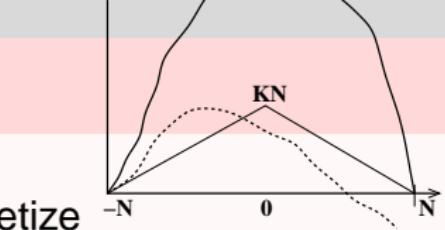
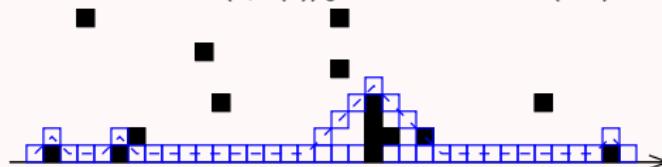
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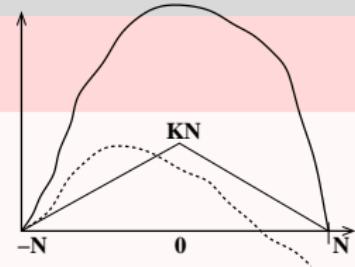
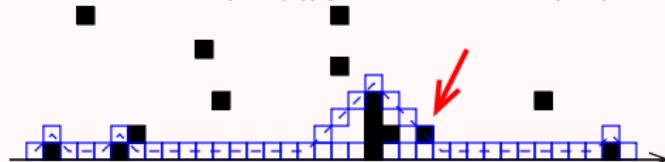
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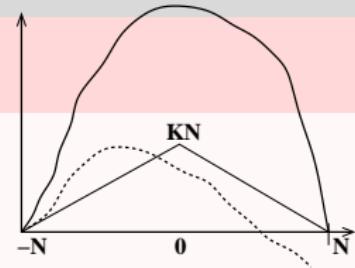
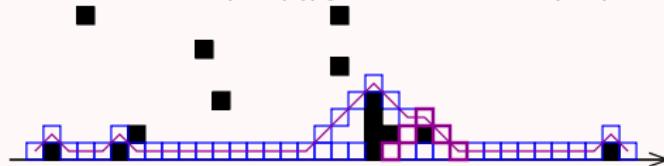
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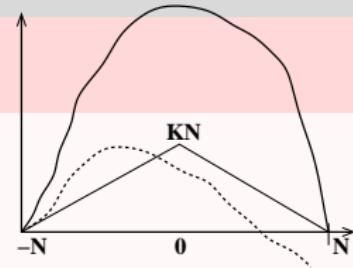
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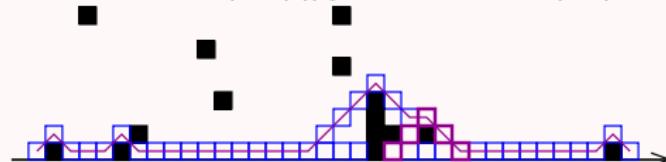
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- Approximate Lipschitz graph by function s.t. $\Delta u + f(x, u, \omega) + F \leq 0$. ("convex" corners at obstacles)

Renormalization (multiscale)

Motivation I Elliptic Homogenization: Corrector

$-\operatorname{div}(a(x)(\nabla u_0(x) + \nabla \phi(x))) = 0$ on one scale. Here oscillations on all scales, so recursive construction of "correctors."

Motivation II: Rigorous renormalization group for random field Ising model (3 d phase transition, 2 d not) by Bricmont-Kupiainen and Bovier-Külske

Idea: Strong obstacles can be neglected if they are isolated

Strategy: Lower bound for time it costs to cross box.

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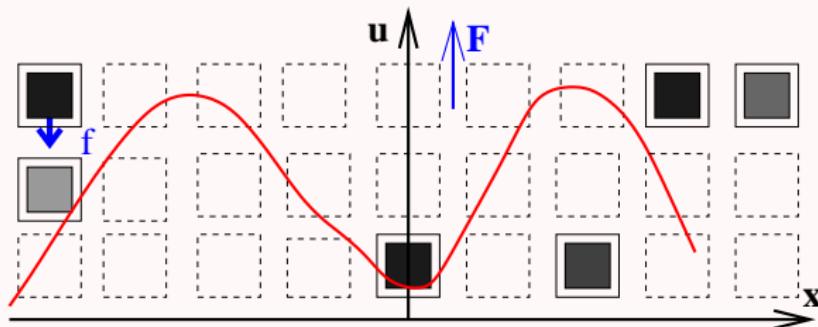
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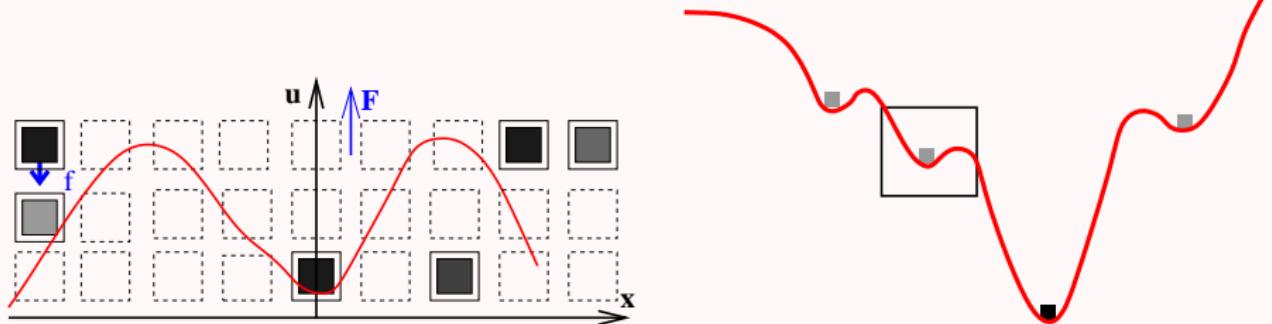
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Then very fast motion of minimum (**slip**)
Of interest: *Bound on total time to cross obstacle*



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- Information on oscillations
- Homogenization
- Dependence of average speed on F ?
- Effective variational models? $d(u_{k+1}, u_k) + E_{\text{eff}}(F, u_{k+1}) \rightarrow \min$

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Thank you for your attention!