Minimal hypersurfaces with bounded index and area

Ben Sharp

March 2017

Why should one care?

Set-up and definitions

Compactness and non-compactness

Main results

Minimal hypersurfaces with bounded index and area \square Why should one care?

- The work of Almgren '68 and Pitts '81 (also Schoen-Simon '81) guarantees the existence of at least one closed, smooth, minimal and embedded minimal hypersurface Mⁿ → Nⁿ⁺¹ in any closed Riemannain manifold N when n ≤ 6. It is a conjecture of Yau that there should be infinitely many distinct M → N.
- Due to the recent work of Marques-Neves '14, Yau's conjecture has been proved when *Ric_N* ≥ α > 0. Thus it makes sense to try to understand the space (where *M* is closed)

 $\mathfrak{M}(N) = \{ M^n \hookrightarrow N^{n+1} | M \text{ is smooth, minimal and embedded.} \}$

One way to get a handle on this space is to understand the relationship between the Betti numbers (or topology) of *M*, b_i(*M*) and the geometric-analytic properties; index(*M*), Hⁿ(*M*) and the total curvature ∫_M |A|ⁿ.

Throughout this talk N^{n+1} will be a closed Riemannian manifold with $2 \le n \le 6$ and $M^n \hookrightarrow N$ a smooth embedded minimal hypersurface which is also closed.

We call *M* minimal if for all $\phi_t : (-\varepsilon, \varepsilon) \times N \to N$, one parameter families of diffeomorphisms with $\phi_0 = Id$, $M_t = \phi_t(M)$ we have

$$rac{\partial}{\partial t} Vol(M_t)|_{t=0} = -\int_M H \cdot v \, \mathrm{d} V_M = 0.$$

Where for $x \in M$, $v(x) = \left(\frac{\partial \phi_t(x)}{\partial t}|_{t=0}\right)^{\perp_M} \in \Gamma(\mathbb{N}M)$ and $H = \operatorname{tr}_M A$ is the mean curvature of M.

Minimal hypersurfaces with bounded index and area \square Set-up and definitions

The index of M, index(M) is the Morse index - the number of negative eigenvalues associated with the Jacobi (second variation) operator for minimal hypersurfaces $M \subset N$:

$$\frac{\partial^2}{\partial t^2} \operatorname{Vol}(M_t)|_{t=0} = \int_M |\nabla^{\perp} v|^2 - |A|^2 |v|^2 - \operatorname{Ric}_N(v, v) \, \mathrm{d}V_M.$$

- Call *M* stable if $Q(v,v) := \int_M |\nabla^{\perp} v|^2 - |A|^2 |v|^2 - Ric_N(v,v) \, \mathrm{d}V_M \ge 0$ for all v,
- and locally minimising if Q(v, v) > 0 for all $v \neq 0$.
- If *M* is two-sided, $v = f\nu$ some $f \in C^{\infty}(M)$ and

$$Q(f\nu, f\nu) = \int_M |\nabla f|^2 - (|A|^2 + \operatorname{Ric}_N(\nu, \nu))f^2 \, \mathrm{d}V_M,$$

thus if $Ric_N > 0$ there are no stable, two sided, minimal hypersurfaces in N.

Compactness and non-compactness

Given a sequence $\{M_k^n\} \hookrightarrow N^{n+1}$ if we know that

$$\mathcal{H}^n(M_k) + \sup_{x \in M_k} |A_k(x)| \leq \Lambda < \infty$$

then there exists some M (minimal, smooth, closed, embedded) such that (up to subsequence) $M_k \rightarrow M$ smoothly and graphically. When $Ric_N > 0$ and n = 2 we can do better:

Theorem (Choi-Schoen '85)

Let N be a compact 3-dimensional manifold with positive Ricci curvature. Then the space of compact embedded minimal surfaces of fixed topological type in N is compact in the C^k topology for any $k \ge 2$ - i.e. smooth graphical convergence with multiplicity one.

Compactness and non-compactness

Remarks

- For n ≥ 3 control on topology can never give such a strong compactness theorem. Letting S⁴ → ℝ⁵ be the round sphere, W. Y. Hsiang '83 proved there exists a sequence M³_k → S⁴ such that M³_k ≅ S³, and H³(M³_k) ≤ Λ but M³_k → M where M = T²×[0,1] is singular at antipodal points.
- 2. When n = 2 and $Ric_N > 0$, by results of Ejiri-Micallef '08 and Choi-Wang '83 we get that

$$\mathit{index}(M) + \mathcal{H}^2(M) \leq C(N) rac{16\pi}{lpha} \left(rac{1}{|\pi_1(N)|} - \chi(M)
ight).$$

Question: are index and volume the correct quantities to control for higher dimensions?

Recall that Q is diagonalised by an L^2 -orthonormal basis of eigenfunctions $\{v_k\} \subset \Gamma(NM)$ with eigenvalues

$$\lambda_1 \leq \lambda_2 \leq \cdots \leq \lambda_k \cdots \to \infty$$

where

$$-\Delta_M^{\perp} v_k - |A|^2 v_k - \operatorname{Ric}_N(v_k, \cdot) = L_M v_k = \lambda_k v_k.$$

Therefore $index(M) = \max\{k|\lambda_k < 0\}$.

We will order the space $\mathfrak{M}(N)$ in the following way, given $p \in \mathbb{N}$ and $0 \leq \Lambda, \mu \in \mathbb{R}$

$$\mathcal{M}_{\rho}(\Lambda,\mu) = \{ M \in \mathfrak{M}(N) | \lambda_{\rho} \geq -\mu, \mathcal{H}^{n}(M) \leq \Lambda \}.$$

lf

$$\mathcal{M}(\Lambda, I) = \{M \in \mathfrak{M}(N) | index(M) \leq I, \mathcal{H}^n(M) \leq \Lambda\}$$

then we see easily that $\mathcal{M}(\Lambda, I) = \mathcal{M}_{I+1}(\Lambda, 0)$ but in general there is no obvious relationship between the two for $\mu > 0$.

Theorem (S '14 (in the case of $\mathcal{M}(\Lambda, I)$), Ambrozio - Carlotto - S '15 (in general))

Let $\{M_k\} \subset \mathcal{M}_p(\Lambda, \mu)$, then there exists $M \in \mathcal{M}_p(\Lambda, \mu)$, $m \in \mathbb{N}$ and a finite set mathcal $Y \subset M$ such that (up to subsequence) $M_k \to mM$ smoothly and graphically with multiplicity m on $M \setminus \mathcal{Y}$.

Assuming that $M_k \neq M$ eventually, we have $|\mathcal{Y}| \leq p-1$ and $nullity(M) \geq 1^1$ or $nullity(\tilde{M}) \geq 1^2$. Furthermore the following dichotomy holds:

- 1. if the number of leaves in the convergence is one then $\mathcal{Y} = \emptyset$
- 2. if the number of sheets is ≥ 2
 - *M* is two-sided implies that *M* is stable (index(M) = 0)
 - M is one-sided implies that M is stable.

²when *M* is one-sided \tilde{M} is the two-sided immersion related to *M*

¹i.e. there exists a non-trivial solution to $L_M v = 0$

Corollary (A-C-S '15)

Let N^{n+1} be a closed Riemannian manifold with $\operatorname{Ric}_N > 0$ and $2 \leq n \leq 6$. Then given any $0 \leq \mu, \Lambda < \infty$ and $p \in \mathbb{N}$ the class $\mathcal{M}_p(\Lambda, \mu)$ is compact in the C^I topology for all $I \geq 2$.

Notice that by an easy argument we have the existence of $C = C(\Lambda, p, \mu, N)$ such that for any $M \in \mathcal{M}_p(\Lambda, \mu)$

$$\sup_{M}|A|+\sum_{i}b_{i}(M)\leq C,$$

moreover there are only finitely many such M up to diffeomorphism.

A result of Chodosh-Ketover-Maximo '15 implies that in fact the volume bound can be dropped here when n = 2.

Open Problem: Can the volume bound be dropped when $n \ge 3$?

Theorem (Buzano - S '16)

Let $\{M_k\} \subset \mathcal{M}_p(\Lambda, \mu)$ for some fixed constants $0 \leq \Lambda, \mu, p \in \mathbb{N}$ independent of k. Then with M as in the previous theorem, there exists a finite number (possibly zero) $\{\Sigma_l^n\}_{l=1}^J \hookrightarrow \mathbb{R}^{n+1}$ of properly embedded minimal hypersurfaces with finite total curvature for which

$$\lim_{k\to\infty}\int_{M_k}|A_k|^n=m\int_{M}|A|^n+\sum_{l=1}^J\int_{\Sigma_l}|A_l|^n$$

where m is the multiplicity of the local graphical convergence away from \mathcal{Y} and $J \leq p - 1$. Furthermore when k is sufficiently large, the M_k 's are all diffeomorphic to one another.

Corollary

There exists some $C = C(N, p, \Lambda, \mu)$ such that $\mathcal{M}_p(\Lambda, \mu)$ contains at most C elements up to diffeomorphism.

The above has been proved by Chodosh-Ketover-Maximo using different methods when considering the more restrictive class $\mathcal{M}(\Lambda, I)$.

Corollary

There exists some $C = C(N, p, \Lambda, \mu)$ such that for any $M \in \mathcal{M}_p(\Lambda, \mu)$ we have

$$\int_M |A|^n \le C.$$

By results of Cheng-Tysk ($n \ge 3$) and Ejiri-Micallef (n = 2) we know that for any M

$$index(M) \leq C\left(\int_{M} |A|^{n} + \mathcal{H}^{n}(M)\right).$$

Thus we have

Corollary

There exists some $I = I(N, \Lambda, p, \mu)$ such that $\mathcal{M}(p, \mu, \Lambda) \subset \mathcal{M}(\Lambda, I)$.

In other words, if we consider the class of minimal hypersurfaces M so that $\mathcal{H}^n(M) \leq \Lambda$ then a control on index is *equivalent* to controlling just one of the eigenvalues λ_p away from $-\infty$ and either of these conditions is itself equivalent to controlling the total curvature of M.

Thank you for your attention!