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**Degree Master of Science in Mathematical Modelling and Scientific Computing**  
**Numerical Solution of Differential Equations & Numerical Linear Algebra**

**HILARY TERM 2009**

**Thursday 15th January, 2:00 p.m. – 4:00 p.m.**

*Candidates should submit answers to a maximum of four questions that include an answer to at least one question in each section.*

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Please start the answer to each question on a new page.

All questions will carry equal marks.

**Do not turn over until told that you may do so.**



## Section A — Numerical Solution of Differential Equations

### Question 1

Consider the initial value problem  $y' = f(x, y)$ ,  $y(x_0) = y_0$ , on the closed interval  $[x_0, X]$  of the real line, where  $f$  is a smooth function of its arguments and  $y_0$  is a given real number. On a uniform mesh

$$\{x_n : x_n = x_0 + nh, n = 0, \dots, N\}$$

of spacing  $h = (X - x_0)/N$ ,  $N \geq 1$ , the solution  $y$  to the initial value problem is approximated at the mesh points  $(x_n)_{n=0, \dots, N}$  by the sequence  $(y_n)_{n=0, \dots, N}$ , defined by the one-step method

$$y_{n+1} = y_n + ahf(x_n, y_n) + bhf(x_n + ch, y_n + chf(x_n, y_n)), \quad n = 0, \dots, N - 1, \quad (1)$$

where  $a$ ,  $b$  and  $c$  are real parameters and  $y_0$  is as above.

- (a) Define the truncation error  $T_n$  of this method. Show that

$$T_n = (1 - a - b)y'(x_n) + \frac{1}{2}(1 - 2bc)hy''(x_n) + \mathcal{O}(h^2), \quad \text{as } h \rightarrow 0.$$

Hence deduce that the method is consistent if, and only if,  $a + b = 1$ .

Show further that there exists a one-parameter family of second-order accurate methods of the form (1).

[8 marks]

- (b) By considering the method (1) applied to the problem  $y' = y$ ,  $y(0) = 1$ , show that there is no choice of  $a$ ,  $b$  and  $c$  such that the order of convergence exceeds 2.

[8 marks]

- (c) Suppose that a second-order method of the form (1) is applied to the initial value problem  $y' = \lambda y$ ,  $y(0) = 1$ , where  $\lambda < 0$  is a fixed constant. The solution  $y(x) = e^{\lambda x}$  to this initial value problem is monotonic decreasing. Find the set of all  $h > 0$  such that the corresponding sequence of numerical approximations  $(y_n)_{n=0, \dots, N}$ , with  $y_0 = 1$ , is monotonic decreasing.

Discuss the practical implications of the resulting restriction when  $\lambda$  is negative and  $|\lambda| \gg 1$ .

[9 marks]

## Question 2

Write down the general form of a linear  $k$ -step method for the numerical solution of the initial value problem  $y' = f(x, y)$ ,  $y(x_0) = y_0$ , on the mesh  $\{x_n : x_n = x_0 + nh, n = 0, 1, 2, \dots\}$  of uniform spacing  $h > 0$ .

- (a) What does it mean to say that a linear  $k$ -step method is *zero-stable*? State an equivalent characterisation of zero-stability in terms of the roots of a certain polynomial.

[8 marks]

- (b) Determine all values of the real parameter  $\alpha$  such that the linear 2-step method given by the formula

$$y_{n+2} - \alpha y_{n+1} + (\alpha - 1)y_n = \frac{h}{12} [(4 + \alpha)f_{n+2} + 8(2 - \alpha)f_{n+1} + (4 - 5\alpha)f_n]$$

is zero stable.

[9 marks]

- (c) Show that for  $\alpha = 0$  the method is fourth order accurate. Is the method convergent for:

- (i)  $\alpha = 0$ ;
- (ii)  $\alpha = 2$ ?

[Justify your answers.]

[8 marks]

### Question 3

Consider the system of linear algebraic equations

$$-a_j U_{j-1} + b_j U_j - c_j U_{j+1} = d_j, \quad j = 1, \dots, J-1,$$

with  $J \geq 2$ , and

$$U_0 = 0, \quad U_J = 0,$$

where  $a_j > 0$ ,  $b_j > 0$ ,  $c_j > 0$  and  $b_j > a_j + c_j$  for all  $j \in \{1, \dots, J-1\}$ .

(a) Show that

$$U_j = e_j U_{j+1} + f_j, \quad j = J-1, J-2, \dots, 1,$$

where

$$e_j = \frac{c_j}{b_j - a_j e_{j-1}}, \quad f_j = \frac{d_j + a_j f_{j-1}}{b_j - a_j e_{j-1}}, \quad j = 1, 2, \dots, J-1,$$

with  $e_0 = 0$  and  $f_0 = 0$ .

How would you use these formulae to formulate an algorithm for the solution of the system of linear equations? Explain in particular the *forward elimination* and *back substitution* steps of the algorithm.

[8 marks]

(b) Show by induction that  $0 < e_j < 1$  for  $j = 1, 2, \dots, J-1$ . Comment on the practical significance of this result in relation to the sensitivity of the computed values of  $U_j$  to rounding errors in the back-substitution step of the algorithm. You may assume that the values  $f_j$ ,  $j = 0, \dots, J-1$ , are free of rounding error.

[8 marks]

(c) Consider the heat equation  $u_t = u_{xx} + u_{yy}$  for  $(x, y)$  contained in the unit square  $\Omega = (0, 1)^2$  and for  $t \in (0, T]$ , subject to homogeneous Dirichlet boundary conditions and the initial condition  $u(x, y, 0) = u_0(x, y)$ , where  $u_0$  is a given continuous function of two variables defined on  $\bar{\Omega}$  and vanishing on the boundary of  $\Omega$ .

Set up an ADI scheme, based on the Crank–Nicolson method, for the numerical solution of this initial boundary value problem, on a uniform mesh of spacings  $\Delta x = 1/K$ ,  $\Delta y = 1/L$  and  $\Delta t = T/M$  in the  $x$ ,  $y$ , and  $t$  co-ordinate directions, respectively;  $K, L \geq 2$ ,  $M \geq 1$ .

Explain how the results of part (a) of this question can be exploited in this scheme.

[9 marks]

#### Question 4

Define the characteristic curves of the linear advection equation

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0, \quad -\infty < x < \infty, \quad t > 0,$$

where  $a$  is a given real number.

- (a) Suppose that the partial differential equation is supplemented by the initial condition  $u(x, 0) = u_0(x)$ . Show that  $u(x, t) = u_0(x - at)$ .

What is the domain of dependence of the point  $(x, t)$ ?

[10 marks]

- (b) Now suppose that this initial value problem has been approximated by the finite difference scheme

$$\frac{U_j^{n+1} - U_j^n}{\Delta t} + a \frac{U_j^n - U_{j-1}^n}{\Delta x} = 0, \quad j = \dots, -1, 0, 1, \dots, \quad n \geq 0,$$

$$U_j^0 = u_0(j\Delta x).$$

Formulate the Courant–Friedrichs–Lewy (CFL) condition relating the domain of dependence of the finite difference scheme to that of the differential equation.

Find all values of  $a$  such that the above difference scheme obeys the CFL condition.

Show further that when the CFL condition holds, the difference scheme is stable in the  $\ell_\infty$  norm in the sense that

$$\max_{n \geq 0} \|U^n\|_{\ell_\infty} \leq \|U^0\|_{\ell_\infty},$$

where  $\|U^n\|_{\ell_\infty} = \max_j |U_j^n|$ .

[15 marks]

## Section B — Numerical Linear Algebra

### Question 5

- (a) What axioms are required for  $\langle \cdot, \cdot \rangle : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$  to define an inner product?

[4 marks]

- (b) How is the vector norm  $\|\cdot\|_2$  defined? Given a vector norm, how is a corresponding (subordinate) matrix norm defined?

[4 marks]

- (c) What is the Singular Value Decomposition (SVD) of a matrix  $A \in \mathbb{R}^{m \times n}$ ? (You do not need to prove that it exists). Show that  $\|A\|_2 = \sigma_1$  where  $\sigma_1$  is the largest singular value of  $A$ .

[7 marks]

- (d) How might the SVD of  $A \in \mathbb{R}^{m \times n}$ ,  $m > n$ , be used to solve a linear least squares problem

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2$$

for given  $b \in \mathbb{R}^m$ ? You should assume that  $A$  has full rank.

[4 marks]

- (e) Now  $(x_i, y_i, z_i), i = 1, \dots, m$ , are points in  $\mathbb{R}^3$  and it is required to find the plane  $\mathbf{r} \cdot \mathbf{n} = c$  which fits best through these points in the least squares sense. Here  $\mathbf{r} = (x, y, z)$  and  $\mathbf{n} = (n_1, n_2, n_3)$  is a unit normal vector to the plane; note that any two of  $n_1, n_2, n_3$  could be zero. Formulate this problem as a linear least squares problem  $\min_{x \in \mathbb{R}^n} \|Ax - b\|_2$  together with the constraint  $n_1^2 + n_2^2 + n_3^2 = 1$ , giving explicit expressions for  $A, b$  and  $x$ . You do not need to solve this problem.

[6 marks]

### Question 6

This question is about the solution of the linear system  $Ax = b$  given  $A \in \mathbb{R}^{n \times n}$  which is nonsingular and  $b \in \mathbb{R}^n$ .

- (a) Give an algorithm for Gaussian Elimination (GE). Why is ‘pivoting’ possibly required? Show that all of the multipliers in GE are in absolute value less than or equal to 1 when partial pivoting is employed. To what matrix factorization is GE equivalent to and how is pivoting represented?

**[11 marks]**

- (b) What is Gauss-Seidel iteration? If  $D = \text{diag}(A)$ ,  $L$  is the strictly lower triangular part of  $A$  and  $U$  is the strictly upper triangular part of  $A$ , write Gauss-Seidel iteration in matrix form.

State but do not prove a theorem giving necessary and sufficient conditions for the convergence of the sequence of iterates  $\{x^{(k)}\}$  computed by the simple iteration

$$Mx^{(k)} = Nx^{(k-1)} + b, \quad k = 1, 2, \dots, \quad x^{(0)} \text{ arbitrary,}$$

where  $A = M - N$ . Prove that if  $A$  is strictly row diagonally dominant, then Gauss-Seidel iteration converges.

**[14 marks]**