Kinetic modeling for motion of Myxobacteria with nematic alignment

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Models of Myxobacteria Motion

- Self-propelled elongated rods $(l \times w)$ in 2-d media
- Move along the longer axis (direction $e(\theta) \in S^2$ and speed v)
- Nematic alignment on collisions (timescale of alignment l/v):



(a) type I binary alignment (symmetric)

(b) type II binary alignment (asymmetric)





- Reversals and tumbled motion
- Chemotaxis and slime following

Phenomenological Models of Multi-Cell Alignment (Vicsek-type models)

• Alignment to the local mean director:





- γ strength of alignment, l interaction radius
- References

Peruani Deutch Bar A mean field theory for self-propelled particles interacting by velocity alignment mechanism (2008)

Ginelli Peruani Bar large-scale collective properties of self-propelled rods (2010)

Degond Manhart Yu A continuum model for nematic alignment (2017)

Degond Merino-Aceituno Nematic alignment of self-propelled particles: from particle to microscopic dynamics (2020)

Frouvelle Liu Dynamics in a kinetic model of oriented particles with phase transition (2011)

Phenomenological Models of Multi-Cell Alignment (Vicsek-type models)

- Mean-field model of alignment in liquid crystals (Maier-Saupe theory)
- Interaction potential for pair of cells:

$$U(\theta_i, \theta_j) = -\cos^2(\theta_j - \theta_i)$$

• Aggregated potential: $\sum_{j:|x_i-x_j| < l} U(\theta_i, \theta_j)$



• Alignment along the gradient of the aggregated potential:

$$\frac{d\theta_i}{dt} = -\gamma \sum_{j:|x_i - x_j| < l} \nabla U(\theta_i, \theta_j) = \gamma \sum_{j:|x_i - x_j| < l} \sin(2(\theta_j - \theta_i))$$

• Equivalent to the mean director model with $\gamma = \gamma |\sum_{j:|x_i - x_j| < l} e^{2i\theta_j}|$

Phenomenological Models of Multi-Cell Alignment

• *Peruani-Deutch-Bar EPJ 2008* A mean field theory for self-propelled particles interacting by velocity alignment mechanism

• LC-model: N point particles (x_i, θ_i) , each moving with velocity $ve(\theta_i)$ and orientation angles changes according to some averaging rule:

$$\frac{dx_i}{dt} = ve(\theta_i)$$

$$\frac{d\theta_i}{dt} = \gamma \sum_{j:|x_i - x_j| < l} \sin(2(\theta_j - \theta_i)) + \text{noise}$$

Phenomenological Models of Multi-Cell Alignment

• Fokker-Planck equation for the density of cells (f) in the in the phase space (x, θ)

$$\partial_t f + v e(\theta) \cdot \nabla f = \gamma N \partial_\theta \left(f \int_{|y-x| < r} \int_{-\pi}^{\pi} \sin(2(\theta - \theta_1)) f(y, \theta_1, t) \, d\theta_1 dy \right) + D \partial_\theta^2 f$$

• Application: phase transition to an aligned state (order parameter S , $\eta = diffusivity/density$) parameter.



Can LC-model for myxobacteria alignment be derived from a model based on binary collisions?

Boltzmann Equation for Rarefied Gas

- f(x,v,t) density of distribution of hard spheres in (x,v) space
- Nondimensional Boltzmann equation

• $\frac{Nl^3}{l^3} = \frac{l}{d}$

 $\partial_t f + v \cdot \nabla f = \frac{Nl^2}{L^2}Q(f, f) + O\left(\frac{Nl^3}{L^3}\right)$

Q(f,f) – Boltzmann operator (leading term of the collision operator)

• Inverse of Knudsen number:
$$Kn^{-1} = \frac{Nl^2}{L^2} = \frac{L}{d}$$
, d – mean free path,

N – number of spheres I – radius L – macroscopic length T – macroscopic time v = L/T – macroscopic speed

Air at 25 deg C, 1 atm, L=1m

$$\frac{Nl^2}{L^2} \approx 10^7 \quad \frac{Nl^3}{L^3} \approx 10^{-3}$$

 Assumptions leading to the Boltzmann equation: large N, small I/L, small I/d, binary collisions, independence of two particle distribution (molecular chaos)

Boltzmann Equation for Rarefied Gas

• Boltzmann equation :

$$\partial_t f + v \cdot \nabla f = \frac{Nl^2}{L^2} Q(f, f)$$

• Short mean-free-path limit:

$$\frac{Vl^2}{L^2} \to \infty$$

• Equilibria are solutions of Q(f,f)=0. Equilibrium densities are Maxwellians

$$f(x,v,t) = \frac{\rho(x,t)}{(2\pi T(x,t))^{3/2}} e^{-\frac{|v-u(x,t)|^2}{2T(x,t)}}$$

- Collisions preserve number of particles, momentum and energy (3 moments of Q(f,,f) are zeros)
- Euler equations of Gas Dynamics for $\rho(x, t)$, u(x, t), T(x, t)

Boltzmann-type models for self-propelled rods

- **Bertin/Droz/Gregoire** Boltzmann and hydrodynamic description for self-propelled particles Phys Rev E 2018)
- Hittmeir/Kanzler/Manhart/Schmeiser Kinetic modeling of colonies of Myxobacteria KRM 2022)

Kinetic modeling of colonies of Myxobacteria (Hittmeir/Kanzler/Manhart/Schmeiser KRM 2022)

- Cells are thin rods of length I with orientation e(θ) (unit vector) moving with velocity ve(θ)
- Co-oriented collisions (angle between $e(\theta)$ and $e(\theta_1)$ is less than $\frac{\pi}{2}$

$$\theta_1$$

• Anti-oriented collisions (angle between $e(\theta)$ and $e(\theta_1)$ is more than $\frac{\pi}{2}$



- Number of cells and total (sum) angle are preserved in collisions
- Assumptions
- 1. Binary collisions
- 2. Two-particle independence
- Kinetic equation

$$\partial_t f + e(\theta) \cdot \nabla f = \frac{Nl}{L} \left(Q_{al}(f, f) + Q_{rev}(f, f) \right) + O\left(\frac{Nl^2}{L^2} \right)$$

- Limit of $N \to \infty$, $\frac{l}{L} \to 0$, $\frac{Nl}{L} \to \infty$ and $\frac{Nl^2}{L^2} \to 0$
- Equilibrium: $Q_{al}(f,f) + Q_{rev}(f,f) = 0$ $\Leftrightarrow \quad f_{eq}(x,\theta,t) = \rho_+(x,t)\delta(\theta - \theta_+(x,t)) + \rho_-(x,t)\delta(\theta - \theta_+(x,t) - \pi)$

Kinetic modeling of colonies of Myxobacteria (Hittmeir/Kanzler/Manhart/Schmeiser KRM 2022)

• Collision and Reversal operators

$$Q_{al}(f,f) = -\int_{\theta-\frac{\pi}{2}}^{\theta+\frac{\pi}{2}} |\sin(\theta-\theta_1)| f(x,\theta,t) f(x,\theta_1,t) d\theta_1$$
$$+ 2\int_{\theta-\frac{\pi}{4}}^{\theta+\frac{\pi}{4}} |\sin(\theta-\theta_1)| f(x,2\theta-\theta_1,t) f(x,\theta_1,t) d\theta_1$$

$$Q_{rev}(f,f) = -\int_{\theta+\frac{\pi}{2}}^{\theta+\frac{3\pi}{2}} |\sin(\theta-\theta_1)| f(x,\theta,t) f(x,\theta_1,t) d\theta_1$$

+
$$\int_{\theta+\frac{\pi}{2}}^{\theta+\frac{3\pi}{2}} |\sin(\theta-\theta_1)| f(x,\theta+\pi,t) f(x,\theta_1+\pi,t) d\theta_1$$

Kinetic modeling of colonies of Myxobacteria (Hittmeir/Kanzler/Manhart/Schmeiser KRM 2022)

- Two-group orientation geometry is invariant under collisions
- Orientation groups, S₊, S₋, are invariant in transport and collisions
- Number of cells in each group, S_+, S_- , is preserved in collisions
- 3 conserved quantities and 3 parameters in equilibrium density
- Applications: existence/uniqueness/convergence to equilibrium for space homogeneous eq for "Maxwellian cells"



$$\begin{aligned} \partial_t \rho_+ + \nabla \cdot (\rho_+ e(\theta_+)) &= 0\\ \partial_t \rho_- - \nabla \cdot (\rho_- e(\theta_+)) &= 0\\ \partial_t ((\rho_+ + \rho_-)\theta_+) + \nabla \cdot ((\rho_+ + \rho_-)\theta_+ e(\theta_+)) &= 0 \end{aligned}$$

Hyperbolic system of PDEs

Boltzmann and hydrodynamic description for self-propelled partiles (Bertin/Droz/Gregoire Phys Rev E 2018)

- Two point particles moving with velocities $ve(\theta)$ and $ve(\theta_1)$ interact when distance between particles < |
- New orientations

$$\hat{ heta} = ar{ heta} + \eta$$

 $\hat{ heta}_1 = ar{ heta} + \eta_1$
 $ar{ heta} = \operatorname{Arg}(\mathrm{e}(heta) + \mathrm{e}(heta_1))$

 η , η_1 - independent Gaussians (noise)

- Diffusion: random adjustments to orientation as a Poisson process with frequency λ : $\hat{\theta} = \theta + \eta_d$
- Binary collisions, Two-particle independence, $N \to \infty$, $\frac{l}{L} \to 0, \ \frac{\lambda L}{\nu} \approx 1, \ \frac{Nl}{L} \approx 1 \ \text{and} \ \frac{Nl^2}{L^2} \to 0$

 $\partial_t f + e(\theta) \cdot \nabla f = Q_{diff}(f, f) + Q_{al}(f, f)$



Macroscopic parameters: density ρ and momentum w

$$\rho(x,t) = \int_{-\pi}^{\pi} f(x,\theta,t) d\theta$$
$$w(x,t) = \int_{-\pi}^{\pi} e(\theta) f(x,\theta,t) d\theta$$
$$= \int_{-\pi}^{\pi} e^{i\theta} f(x,\theta,t) d\theta$$

Boltzmann and hydrodynamic description for self-propelled partiles (Bertin/Droz/Gregoire Phys Rev E 2018)

• Conservation of number of cells in collisions

$$\partial_t \rho + \nabla \cdot w = 0$$

• First moment

$$\partial_t w = \int_{-\pi}^{\pi} e(\theta) \left(-e(\theta) \cdot \nabla f + Q_{al} + Q_{diff}\right) d\theta$$

• Fourier modes $f = \sum f_k e^{ik\theta}$ with

 $f_0 \approx \rho$, $f_1 \approx w$

• Asymptotic regime of small macroscopic velocity:

 $\rho \approx O(1), |w| = \varepsilon, \ |f_k| \approx O\left(\varepsilon^{-|k|}\right), \ \varepsilon \ll 1$

 $\partial_t \rho + \nabla \cdot w = 0$ $\partial_t w + \gamma (w \cdot \nabla) w = -\frac{1}{2} \nabla (\rho - kw \cdot w) + (\mu - \xi w \cdot w) w$ $+ v \Delta w - k (\nabla \cdot w) w$

Limiting macroscopic equations

• Application: stability of homogeneous state

$$\partial_t w = (\mu - \xi w \cdot w) w$$

If $\mu < 0$, the only steady state w=0 (stable) if $\mu > 0$, non-zero steady states $w = \sqrt{\frac{\mu}{\xi}} e(\theta)$

A mean-field model for nematic alignment of self-propelled rods (MP/Murphy/Igoshing/Timofeyev to appear in Phys Rev E 2022)

- Symmetric alignment in binary collisions
 - θ_1
- δ small parameter

$$\theta' = \theta + \delta \sin(2(\theta_1 - \theta))$$

$$\theta'_1 = \theta_1 - \delta \sin(2(\theta_1 - \theta))$$

 Assumptions: binary collisions, two-particle independence • Geometry of interactions in time Δt





• Area of interaction parallelograms:

 $lv\Delta t |\sin(\theta - \theta_1)|$

A mean-field model for nematic alignment of self-propelled rods

• Balance of probability + Scaling + Asymptotic expansion:

$$\partial_t f + v(\theta) \cdot \nabla f = -\frac{(N-1)l\delta}{L} \partial_\theta \left(f(x,\theta,t) \int_{-\pi}^{\pi} |\sin(\theta_1'-\theta)| \phi(\theta_1'-\theta) f(x,\theta_1',t) d\theta_1' \right) + O\left(NlL^{-1}\delta^2\right) + O\left(Nl^2L^{-2}\delta\right).$$

- $\delta \ll 1$, $\frac{l}{L} \ll 1$, N $\gg 1$
- $\frac{Nl\delta}{L} = \delta \frac{N}{L^2} (lL) = 1$: (amount of alignment per collision)x(cell density)x("interaction area" over characteristic distance L)=(amou of alignment per collision)x(# of collisions over characteristic distance L)=1
- Large number of collisions over characteristic distance L
- Conclusion: Liquid crystal model of myxocell alignment can be derived on the basis of purely collisional model, in the limit of the zero interaction distance and large number of cells
- Application: phase transition to an aligned state



Asymmetric Alignment



Mechanical interactions between two cells during head-to-side collision. From Balagam et al. PLOS Comp. Bio. 2014.

Kinetic equation

$$\partial_t f + e(\theta) \cdot \nabla f = \frac{Nl}{L} Q_o(f, f) + \frac{Nl^2}{L^2} Q_1(f, f)$$
Physical range: $\frac{Nlw}{L^2} < 1$
Length (l) = 3µm, width (w) = 0.5µm: $\frac{Nl^2}{L^2} < 6$
N = 1,000-10,000 L = 500µm
 $\frac{Nl}{L} = 6..60$ $\frac{Nl^2}{L^2} = 0.036..0.36$



- Initial set of orientations and their reflections is preserved in collisions and transport
- Assumptions:
- 1. Binary collisions
- 2. Two-particle independence

3.
$$\frac{Nl}{L} \gg 1$$
, $\frac{Nl^2}{L^2} \approx 1$

Interaction Operators

$$\begin{aligned} Q_0(f,f) &= \int_{\theta-\frac{\pi}{2}}^{\theta+\frac{\pi}{2}} |\sin(\theta-\theta_1)| (f(x,\theta+\pi,t)f(x,\theta_1,t) - f(x,\theta,t)f(x,\theta_1+\pi,t)) d\theta_1 \\ Q_1(f,f) &= \int_{\theta-\frac{\pi}{2}}^{\theta+\frac{\pi}{2}} |\sin(\theta-\theta_1)| (f(x,\theta_1,t)e(\theta_1) \cdot \nabla_x f(x,\theta,t) - f(x,\theta,t)e(\theta) \cdot \nabla_x f(x,\theta_1,t) \\ &+ f(x,\theta_1,t)e(\theta_1) \cdot \nabla_x f(x,\theta+\pi,t) - f(x,\theta,t)e(\theta) \cdot \nabla_x f(x,\theta_1+\pi,t)) d\theta_1 \end{aligned}$$

- Asymmetry (key property): $Q_0(f,f)(x,\theta + \pi,t) = -Q_0(f,f)(x,\theta,t)$
- Equilibria: $Q_0(f,f) = 0$
- Two co-oriented groups: $f(x,\theta,t) = \begin{cases} f_+(x,\theta,t), & \theta \in S_+ \\ \lambda(x,t)f_+(x,\theta+\pi), \theta \in S_- \end{cases}$ (the only equilibrium for two nematic orientations)



Singular Limit and Macroscopic Equations

Limit of
$$N \to \infty$$
, $\frac{l}{L} \to 0$, $\frac{Nl}{L} \to \infty$, and $\frac{Nl^2}{L^2} \approx 1$

- Implications:
 - 1. $Q_0(f, f) \rightarrow 0$
 - 2. If initial data are nematically co-oriented then so is $f(x, \theta, t)$ for any (x, t)

3. Assuming finite set of m initial orientations $\theta_1, \ldots, \theta_m$,

$$f(x,\theta,t) = \sum_{k} \rho_{k}(x,t)\delta(\theta - \theta_{k}) + \lambda(x,t)\rho_{k}(x,t)\delta(\theta - \theta_{k} - \pi)$$
(m+1) macroscopic parameters

- Equations:
 - 1. conservation of total number of cells
 - 2. m asymmetry conditions

Examples of Macroscopic Equations

• One co-oriented group with two angles θ_1, θ_2 :

$$\partial_t \left[\begin{array}{c} \rho_1 \\ \rho_2 \end{array} \right] + A(\rho) \partial_x \left[\begin{array}{c} \rho_1 \\ \rho_2 \end{array} \right] = 0,$$

where $A(\rho)$ is a 2 × 2 matrix

$$A(\rho) = \begin{bmatrix} e(\theta_1)_1 - |\sin(\theta_1 - \theta_2)|e(\theta_2)_1\rho_2 & |\sin(\theta_1 - \theta_2)|e(\theta_1)_1\rho_1 \\ |\sin(\theta_1 - \theta_2)|e(\theta_2)_1\rho_2 & e(\theta_2)_1 - |\sin(\theta_1 - \theta_2)|e(\theta_1)_1\rho_1 \end{bmatrix}$$

• Two nematically co-oriented group with two angles:

$$\partial_t \left[egin{array}{c}
ho_1 \
ho_2 \ \lambda \end{array}
ight] + A(
ho) \partial_x \left[egin{array}{c}
ho_1 \
ho_2 \ \lambda \end{array}
ight] = 0$$

 $\begin{bmatrix} \frac{1-\lambda+(1-\lambda^{2})\rho_{2}}{\sqrt{2}(1+\lambda)} + \frac{\sqrt{2}\lambda\rho_{1}}{(1+\lambda)(\rho_{1}+\rho_{2})} & \frac{(1-\lambda)\rho_{1}}{\sqrt{2}} - \frac{\sqrt{2}\lambda\rho_{1}}{(1+\lambda)(\rho_{1}+\rho_{2})} & \frac{-\rho_{1}+2(1-\lambda)\rho_{1}\rho_{2}}{\sqrt{2}(1+\lambda)} + \frac{\rho_{1}(\rho_{1}-\rho_{2})}{\sqrt{2}(1+\lambda)(\rho_{1}+\rho_{2})} \\ -\frac{(1-\lambda)\rho_{2}}{\sqrt{2}} + \frac{\sqrt{2}\lambda\rho_{2}}{(1+\lambda)(\rho_{1}+\rho_{2})} & -\frac{1-\lambda+(1-\lambda^{2})\rho_{1}}{\sqrt{2}(1+\lambda)} - \frac{\sqrt{2}\lambda\rho_{2}}{(1+\lambda)(\rho_{1}+\rho_{2})} & \frac{-\rho_{2}-2(1-\lambda)\rho_{1}\rho_{2}}{\sqrt{2}(1+\lambda)} + \frac{\rho_{2}(\rho_{1}-\rho_{2})}{\sqrt{2}(1+\lambda)(\rho_{1}+\rho_{2})} \\ -\frac{\sqrt{2}\lambda}{(\rho_{1}+\rho_{2})} & \frac{\sqrt{2}\lambda}{(\rho_{1}+\rho_{2})} & \frac{\sqrt{2}\lambda\rho_{2}}{(\rho_{1}+\rho_{2})} & -\frac{(\rho_{1}-\rho_{2})}{\sqrt{2}(\rho_{1}+\rho_{2})} + \frac{\sqrt{2}\lambda\rho_{2}}{(1+\lambda)(\rho_{1}+\rho_{2})} \end{bmatrix}$

• Hyperbolic system of PDES

 $A(\rho)$ is a 3x3 matrix

ABM and PDE simulations

• Two orientations θ_1, θ_2 , N=4000 cells, square domain of side L=400 μm , average over 1000 simulations



Gaussian bands







initial bands



Uniform bands

ABM and PDE simulations

- Interaction of uniform bands
- ABM (solid line) vs. PDE (dotted line)



PDEs $(c_1, c_2 > 0)$ $\partial_t \rho_1 + c_1 \partial_x (\rho_1 (1 + c_2 \rho_2)) = 0$ $\partial_t \rho_2 - c_1 \partial_x (\rho_2 (1 + c_2 \rho_1)) = 0$

Numerical solution of PDE model (Lax-Friedrichs scheme)

• Interaction of uniform bands (numerical solution of PDEs)



• Wave structure in the interaction of two uniform bands



Further Comments

- I. Summary
 - Boltzmann-type PDE model gives reasonable qualitative approximation of agentbase dynamics
 - Higher order terms in the Boltzmann equation must be accounted for

II. Difficulties

- PDEs are generically non-conservative
- Agent-based dynamics exhibit growth of correlations (clustering due to short meanfree path)
- Two-particle independence hypothesis is violated in a long run
- Boltzmann-type PDE model is valid in transient regimes
- III. Future Work
 - Different closures for the kinetic function (f)
 - Models with Reversals and Refraction period
 - Different geometries of alignment (for ex. turning trough the head of a cell)