Global Weak Solution to the Cauchy Problem of Spherically Symmetric Compressible Full Navier-Stokes Equations.

#### Yucong Huang

University of Oxford (2017~2022) / University of Edinburgh (2022~)

#### Oxford Workshop on Stability Analysis for Nonlinear PDEs August 2022

This is a joint work with Gui-Qiang G. Chen(University of Oxford) and Shengguo Zhu(Shanghai Jiao Tong University).

#### 1 Introduction

- 1.1 Equations
- 1.2 Previous results

#### 2 Main Theorem

- 2.1 Definition of weak solution
- 2.2 Global-in-time existence of weak solution

#### 3 Main Strategy

- 3.1 Exterior problems
- 3.2 Lagrangian reformulation
- 3.3 Uniform a-priori estimates

#### 1 Introduction

- 1.1 Equations
- 1.2 Previous results
- 2 Main Theorem
  - 2.1 Definition of weak solution
  - 2.2 Global-in-time existence of weak solution

#### 3 Main Strategy

- 3.1 Exterior problems
- 3.2 Lagrangian reformulation
- 3.3 Uniform a-priori estimates

#### 1 Introduction

- 1.1 Equations
- 1.2 Previous results
- 2 Main Theorem
  - 2.1 Definition of weak solution
  - 2.2 Global-in-time existence of weak solution

#### 3 Main Strategy

- 3.1 Exterior problems
- 3.2 Lagrangian reformulation
- 3.3 Uniform a-priori estimates

## 1. Introduction

포 제 표

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $ho \geq 0$  is mass density,  $ec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is

**pressure**,  $E := e + \frac{|U|^{-}}{2}$  is total energy per unit mass, *e* is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \ge 0$  is heat conduction coefficient, and S is viscous stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e=c_V heta$ . Hence,

1. 
$$P = P(\rho, e) = (\gamma - 1)\rho e$$
, where  $\gamma > 1$ .

2. div $(\kappa_Q \nabla \theta) = \kappa \Delta e$  where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $\rho \geq 0$  is mass density,  $\vec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is pressure,  $E := e + \frac{|\vec{U}|^2}{2}$  is total energy per unit mass, e is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \geq 0$  is heat conduction coefficient, and S is viscous

stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e=c_V heta$ . Hence,

1. 
$$P = P(\rho, e) = (\gamma - 1)\rho e$$
, where  $\gamma > 1$ .

2. div $(\kappa_Q \nabla \theta) = \kappa \Delta e$  where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

4/30

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $\rho \geq 0$  is mass density,  $\vec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is pressure,  $E := e + \frac{|\vec{U}|^2}{2}$  is total energy per unit mass, e is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \geq 0$  is heat conduction coefficient, and S is viscous stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e=c_V heta$ . Hence,

1. 
$$P = P(\rho, e) = (\gamma - 1)\rho e$$
, where  $\gamma > 1$ .

2. div $(\kappa_Q \nabla \theta) = \kappa \Delta e$  where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

4/30

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $\rho \geq 0$  is mass density,  $\vec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is pressure,  $E := e + \frac{|\vec{U}|^2}{2}$  is total energy per unit mass, e is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \geq 0$  is heat conduction coefficient, and S is viscous stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e=c_V heta$ . Hence,

1. 
$$P = P(\rho, e) = (\gamma - 1)\rho e$$
, where  $\gamma > 1$ .

2. div $(\kappa_Q \nabla \theta) = \kappa \Delta e$  where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $\rho \geq 0$  is mass density,  $\vec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is pressure,  $E := e + \frac{|\vec{U}|^2}{2}$  is total energy per unit mass, e is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \geq 0$  is heat conduction coefficient, and S is viscous stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e=c_V heta$ . Hence,

1. 
$$P = P(\rho, e) = (\gamma - 1)\rho e$$
, where  $\gamma > 1$ .

2. div $(\kappa_Q \nabla \theta) = \kappa \Delta e$  where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $\rho \geq 0$  is mass density,  $\vec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is pressure,  $E := e + \frac{|\vec{U}|^2}{2}$  is total energy per unit mass, e is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \geq 0$  is heat conduction coefficient, and S is viscous stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e=c_V heta$ . Hence,

- 1.  $P = P(\rho, e) = (\gamma 1)\rho e$ , where  $\gamma > 1$ .
- 2. div $(\kappa_Q \nabla \theta) = \kappa \Delta e$  where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $\rho \geq 0$  is mass density,  $\vec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is pressure,  $E := e + \frac{|\vec{U}|^2}{2}$  is total energy per unit mass, e is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \geq 0$  is heat conduction coefficient, and  $\mathbb{S}$  is viscous stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e=c_V heta$ . Hence,

1. 
$$P = P(\rho, e) = (\gamma - 1)\rho e$$
, where  $\gamma > 1$ .

2. div $(\kappa_Q \nabla \theta) = \kappa \Delta e$  where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $\rho \geq 0$  is mass density,  $\vec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is pressure,  $E := e + \frac{|\vec{U}|^2}{2}$  is total energy per unit mass, e is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \geq 0$  is heat conduction coefficient, and  $\mathbb{S}$  is viscous stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e = c_V \theta$ . Hence,

1. 
$$P = P(\rho, e) = (\gamma - 1)\rho e$$
, where  $\gamma > 1$ .

2. div $(\kappa_Q \nabla \theta) = \kappa \Delta e$  where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

For dimensions n = 2, 3, heat-conducting compressible flow is governed by the following system of partial differential equations:

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \vec{U}) = 0, \\ \partial_t(\rho \vec{U}) + \operatorname{div}(\rho \vec{U} \otimes \vec{U}) + \nabla P = \operatorname{div}\mathbb{S}, \\ \partial_t(\rho E) + \operatorname{div}((\rho E + P)\vec{U}) = \operatorname{div}(\mathbb{S} \cdot \vec{U}) + \operatorname{div}(\kappa_Q \nabla \theta), \end{cases}$$
(CNS)

where  $\rho \geq 0$  is mass density,  $\vec{U} = (U^1, \dots, U^n) \in \mathbb{R}^n$  is velocity,  $P \geq 0$  is pressure,  $E := e + \frac{|\vec{U}|^2}{2}$  is total energy per unit mass, e is internal energy per unit mass,  $\theta$  is temperature,  $\kappa_Q \geq 0$  is heat conduction coefficient, and  $\mathbb{S}$  is viscous stress tensor.

Two assumptions: (1) Ideal gas; (2) Polytropic, i.e.  $e = c_V \theta$ . Hence,

1. 
$$P = P(\rho, e) = (\gamma - 1)\rho e$$
, where  $\gamma > 1$ .

2. 
$$\operatorname{div}(\kappa_Q \nabla \theta) = \kappa \Delta e$$
 where  $\kappa \equiv \kappa_Q/c_V \ge 0$ .

#### 1.1 Introduction: Viscous Stress Tensor

The viscous stress tensor,  $\mathbb{S}$  is given as follows:

$$\mathbb{S}(\nabla \vec{U}) \mathrel{\mathop:}= \mu (\nabla \vec{U} + \nabla \vec{U}^\top) + \lambda \mathbb{I}_n \mathrm{div} \vec{U},$$

where  $\mathbb{I}_n$  is  $n \times n$  identity matrix,  $\mu$  is the shear viscosity coefficient and quantity  $\frac{2}{n}\mu + \lambda$  is the bulk viscosity coefficient.

We assume  $\mu$ ,  $\lambda$  to be given constants. Then the term divS can be written as the following second order linear differential operator:

$$\operatorname{div} \mathbb{S}(\nabla \vec{U}) = L \vec{U} := \mu \, \triangle \vec{U} + (\mu + \lambda) \, \nabla \operatorname{div} \vec{U}.$$

Moreover, we also impose the following physical condition:

$$\mu>0 \quad \text{and} \quad \frac{2}{n}\mu+\lambda\geq 0\,.$$

The sufficient condition for L to be an elliptic operator is  $\mu > 0$  and  $\mu + \lambda \ge 0$ .

5/30

#### 1.1 Introduction: Viscous Stress Tensor

The viscous stress tensor,  $\mathbb{S}$  is given as follows:

$$\mathbb{S}(\nabla \vec{U}) \mathrel{\mathop:}= \mu(\nabla \vec{U} + \nabla \vec{U}^{\top}) + \lambda \mathbb{I}_n \mathrm{div} \vec{U},$$

where  $\mathbb{I}_n$  is  $n \times n$  identity matrix,  $\mu$  is the shear viscosity coefficient and quantity  $\frac{2}{n}\mu + \lambda$  is the bulk viscosity coefficient.

We assume  $\mu$ ,  $\lambda$  to be given constants. Then the term  $\operatorname{div}\mathbb{S}$  can be written as the following second order linear differential operator:

$$\mathrm{div}\mathbb{S}(\nabla \vec{U}) = L\vec{U} := \mu \, \triangle \vec{U} + (\mu + \lambda) \, \nabla \mathrm{div}\vec{U}.$$

Moreover, we also impose the following physical condition:

$$\mu>0 \quad \text{and} \quad \frac{2}{n}\mu+\lambda\geq 0\,.$$

The sufficient condition for L to be an elliptic operator is  $\mu > 0$  and  $\mu + \lambda \ge 0$ .

#### 1.1 Introduction: Viscous Stress Tensor

The viscous stress tensor,  $\mathbb{S}$  is given as follows:

$$\mathbb{S}(\nabla \vec{U}) \mathrel{\mathop:}= \mu(\nabla \vec{U} + \nabla \vec{U}^{\top}) + \lambda \mathbb{I}_n \mathrm{div} \vec{U},$$

where  $\mathbb{I}_n$  is  $n \times n$  identity matrix,  $\mu$  is the shear viscosity coefficient and quantity  $\frac{2}{n}\mu + \lambda$  is the bulk viscosity coefficient.

We assume  $\mu$ ,  $\lambda$  to be given constants. Then the term  $\operatorname{div}\mathbb{S}$  can be written as the following second order linear differential operator:

$$\mathrm{div}\mathbb{S}(\nabla \vec{U}) = L \vec{U} \coloneqq \mu \, \triangle \vec{U} + (\mu + \lambda) \, \nabla \mathrm{div} \vec{U}.$$

Moreover, we also impose the following physical condition:

$$\mu>0 \quad \text{and} \quad \frac{2}{n}\mu+\lambda\geq 0\,.$$

The sufficient condition for L to be an elliptic operator is  $\mu > 0$  and  $\mu + \lambda \ge 0$ .

For spherically symmetric solution, it takes the form:

$$(\rho, \vec{U}, e)(\vec{x}, t) = (\rho(|\vec{x}|, t), u(|\vec{x}|, t) \frac{\vec{x}}{|\vec{x}|}, e(|\vec{x}|, t)), \quad (\vec{x}, t) \in \mathbb{R}^n \times [0, \infty) \,.$$

Denote  $r \equiv |\vec{x}|$  and  $m \equiv n - 1$ . Then  $(\rho, u, e)(r, t)$  satisfies the equations:

$$\begin{cases} \partial_t \rho + u \partial_r \rho + \rho \Big( \partial_r u + m \frac{u}{r} \Big) = 0, \\ \rho \partial_t u + \rho u \partial_r u + \partial_r P = \beta \partial_r \Big( \frac{\partial_r (r^m u)}{r^m} \Big), \\ \rho \partial_t e + \rho u \partial_r e + P \frac{\partial_r (r^m u)}{r^m} = \mathcal{D} + \kappa \frac{\partial_r (r^m \partial_r e)}{r^m}, \end{cases}$$
(SNS)

where 
$$\mathcal{D} := 2\mu \left( |\partial_r u|^2 + m \frac{u^2}{r^2} \right) + \lambda \left( \partial_r u + m \frac{u}{r} \right)^2$$
,  $\beta := 2\mu + \lambda > 0$ .

We call it the **(Spherically Symmetric) Cauchy Problem** if the domain is set in  $(r,t) \in [0,\infty) \times [0,\infty)$ , with the initial condition:

$$(
ho, u, e)(r, 0) = (
ho_0, u_0, e_0)(r) \ \ {
m for} \ \ r \in [0, \infty).$$

For spherically symmetric solution, it takes the form:

$$(\rho, \vec{U}, e)(\vec{x}, t) = (\rho(|\vec{x}|, t), u(|\vec{x}|, t) \frac{\vec{x}}{|\vec{x}|}, e(|\vec{x}|, t)), \quad (\vec{x}, t) \in \mathbb{R}^n \times [0, \infty) \,.$$

Denote  $r \equiv |\vec{x}|$  and  $m \equiv n - 1$ . Then  $(\rho, u, e)(r, t)$  satisfies the equations:

$$\begin{cases} \partial_t \rho + u \partial_r \rho + \rho \left( \partial_r u + m \frac{u}{r} \right) = 0, \\ \rho \partial_t u + \rho u \partial_r u + \partial_r P = \beta \partial_r \left( \frac{\partial_r (r^m u)}{r^m} \right), \\ \rho \partial_t e + \rho u \partial_r e + P \frac{\partial_r (r^m u)}{r^m} = \mathcal{D} + \kappa \frac{\partial_r (r^m \partial_r e)}{r^m}, \end{cases}$$
(SNS)

where 
$$\mathcal{D} := 2\mu \left( |\partial_r u|^2 + m \frac{u^2}{r^2} \right) + \lambda \left( \partial_r u + m \frac{u}{r} \right)^2$$
,  $\beta := 2\mu + \lambda > 0$ .

We call it the **(Spherically Symmetric) Cauchy Problem** if the domain is set in  $(r,t) \in [0,\infty) \times [0,\infty)$ , with the initial condition:

$$(\rho, u, e)(r, 0) = (\rho_0, u_0, e_0)(r)$$
 for  $r \in [0, \infty)$ . (II

6/30

For spherically symmetric solution, it takes the form:

$$(\rho, \vec{U}, e)(\vec{x}, t) = (\rho(|\vec{x}|, t), u(|\vec{x}|, t) \frac{\vec{x}}{|\vec{x}|}, e(|\vec{x}|, t)), \quad (\vec{x}, t) \in \mathbb{R}^n \times [0, \infty) \,.$$

Denote  $r \equiv |\vec{x}|$  and  $m \equiv n-1$ . Then  $(\rho, u, e)(r, t)$  satisfies the equations:

$$\begin{cases} \partial_t \rho + u \partial_r \rho + \rho \left( \partial_r u + m \frac{u}{r} \right) = 0, \\ \rho \partial_t u + \rho u \partial_r u + \partial_r P = \beta \partial_r \left( \frac{\partial_r (r^m u)}{r^m} \right), \\ \rho \partial_t e + \rho u \partial_r e + P \frac{\partial_r (r^m u)}{r^m} = \mathcal{D} + \kappa \frac{\partial_r (r^m \partial_r e)}{r^m}, \end{cases}$$
(SNS)

where 
$$\mathcal{D} := 2\mu \Big( |\partial_r u|^2 + m \frac{u^2}{r^2} \Big) + \lambda \Big( \partial_r u + m \frac{u}{r} \Big)^2$$
,  $\beta := 2\mu + \lambda > 0$ .

We call it the **(Spherically Symmetric) Cauchy Problem** if the domain is set in  $(r,t) \in [0,\infty) \times [0,\infty)$ , with the initial condition:

$$(
ho, u, e)(r, 0) = (
ho_0, u_0, e_0)(r) \ \ {
m for} \ \ r \in [0, \infty).$$

For spherically symmetric solution, it takes the form:

$$(\rho, \vec{U}, e)(\vec{x}, t) = (\rho(|\vec{x}|, t), u(|\vec{x}|, t) \frac{\vec{x}}{|\vec{x}|}, e(|\vec{x}|, t)), \quad (\vec{x}, t) \in \mathbb{R}^n \times [0, \infty) \,.$$

Denote  $r \equiv |\vec{x}|$  and  $m \equiv n-1$ . Then  $(\rho, u, e)(r, t)$  satisfies the equations:

$$\begin{cases} \partial_t \rho + u \partial_r \rho + \rho \left( \partial_r u + m \frac{u}{r} \right) = 0, \\ \rho \partial_t u + \rho u \partial_r u + \partial_r P = \beta \partial_r \left( \frac{\partial_r (r^m u)}{r^m} \right), \\ \rho \partial_t e + \rho u \partial_r e + P \frac{\partial_r (r^m u)}{r^m} = \mathcal{D} + \kappa \frac{\partial_r (r^m \partial_r e)}{r^m}, \end{cases}$$
(SNS)

where 
$$\mathcal{D} := 2\mu \Big( |\partial_r u|^2 + m \frac{u^2}{r^2} \Big) + \lambda \Big( \partial_r u + m \frac{u}{r} \Big)^2$$
,  $\beta := 2\mu + \lambda > 0$ .

We call it the **(Spherically Symmetric) Cauchy Problem** if the domain is set in  $(r,t) \in [0,\infty) \times [0,\infty)$ , with the initial condition:

$$(\rho, u, e)(r, 0) = (\rho_0, u_0, e_0)(r)$$
 for  $r \in [0, \infty)$ . (ID)

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the global-in-time existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

 $\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$ 

- Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = {x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.
- Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball: Ω = B(0; R), R > 0. They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin |x| = 0.

・ロト ・雪 ト ・ ヨ ト ・

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the **global-in-time** existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

 $\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$ 

- Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = {x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.
- Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball: Ω = B(0; R), R > 0. They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin |x| = 0.

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the **global-in-time** existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

 $\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$ 

Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = { x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.

Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball: Ω = B(0; R), R > 0. They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin |x| = 0.

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the **global-in-time** existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

 $\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$ 

Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = { x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.

Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball: Ω = B(0; R), R > 0. They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin |x| = 0.

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the **global-in-time** existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

$$\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$$

Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = {x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.

• Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball:  $\Omega = B(\vec{0}; R)$ , R > 0. They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin  $|\vec{x}| = 0$ .

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the **global-in-time** existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

$$\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$$

Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = {x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.

• Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball:  $\Omega = B(\vec{0}; R), R > 0$ . They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin  $|\vec{x}| = 0$ .

ヘロト 人間ト ヘヨト ヘヨト

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the **global-in-time** existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

$$\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$$

Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = {x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.

• Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball:  $\Omega = B(\vec{0}; R)$ , R > 0. They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin  $|\vec{x}| = 0$ .

・ロト ・雪 ト ・ヨ ト ・ ヨ ト

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the **global-in-time** existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

$$\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$$

Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = {x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.

• Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball:  $\Omega = B(\vec{0}; R)$ , R > 0. They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin  $|\vec{x}| = 0$ .

- Kazhikhov and Shelukhin 1977 considered one-dimensional(1D) bounded spatial domain  $\Omega = [a, b]$ , with **large smooth** initial data such that  $0 < \inf_{x \in \Omega} \rho_0(x) < \sup_{x \in \Omega} \rho_0 < \infty$ . They obtained the **global-in-time** existence and uniqueness of a classical solution.
- Kawashima and Nishida 1981 extended the result of Kazhikhov-Shelukhin to the Cauchy Problem in the entire spatial domain  $x \in \mathbb{R}$ . Moreover,

$$\lim_{t \to \infty} \|(\rho, u, e)(\cdot, t) - (\overline{\rho}, 0, \overline{\theta})\|_{L^{\infty}(\mathbb{R})}.$$

- Jiang 1996 considered large, smooth, multi-dimensional(MD) spherically symmetric initial data in the exterior domain Ω = {x ∈ ℝ<sup>n</sup> : a ≤ |x| < ∞} for a fixed a > 0. He obtained the global-in-time existence and uniqueness of a spherically symmetric classical solution.
- Hoff and Jenssen 2004 considered large, discontinuous, MD spherically symmetric initial data in a bounded ball:  $\Omega = B(\vec{0}; R), R > 0$ . They obtained a global-in-time spherically symmetric weak solution. The significance of this result is that the region includes the origin  $|\vec{x}| = 0$ .

- Nash 1962 considered the Cauchy Problem in  $\Omega = \mathbb{R}^n$ , with large smooth initial data such that  $C_0^{-1} \leq \rho_0 \leq C_0$  for some  $C_0 > 0$ . He obtained the local-in-time existence and uniqueness of a classical solution.
- Lions 1993 considered the equations for isentropic flow, P(ρ) = Aρ<sup>γ</sup>, with large, possibly discontinuous initial data. Under the assumption that γ ≥ 3/2 if n = 2 and γ ≥ 9/5 if n = 3, he obtained a global-in-time finite energy weak solution in a bounded or periodic domain Ω ⊊ ℝ<sup>n</sup>:

$$\begin{split} \rho_0 &\in L^{\gamma} \cap L^1(\Omega) \quad \text{and} \quad \sqrt{\rho_0} u_0 \in L^2(\Omega) \\ \Rightarrow \begin{cases} \rho \in L^{\infty}(0,T;L^{\gamma} \cap L^1(\Omega)) \cap C([0,\infty);L^q(\Omega)) \,, & 1 \leq q < \gamma \\ \nabla u \in L^2(0,T;L^2(\Omega)) \,, & \rho |u|^2 \in L^{\infty}(0,T;L^1(\Omega)) \,. \end{cases} \end{split}$$

- Nash 1962 considered the Cauchy Problem in  $\Omega = \mathbb{R}^n$ , with large **smooth** initial data such that  $C_0^{-1} \leq \rho_0 \leq C_0$  for some  $C_0 > 0$ . He obtained the local-in-time existence and uniqueness of a classical solution.
- Lions 1993 considered the equations for isentropic flow, P(ρ) = Aρ<sup>γ</sup>, with large, possibly discontinuous initial data. Under the assumption that γ ≥ 3/2 if n = 2 and γ ≥ 9/5 if n = 3, he obtained a global-in-time finite energy weak solution in a bounded or periodic domain Ω ⊊ ℝ<sup>n</sup>:

$$\begin{split} \rho_0 &\in L^{\gamma} \cap L^1(\Omega) \quad \text{and} \quad \sqrt{\rho_0} u_0 \in L^2(\Omega) \\ \Rightarrow \begin{cases} \rho \in L^{\infty}(0,T;L^{\gamma} \cap L^1(\Omega)) \cap C([0,\infty);L^q(\Omega)) \,, & 1 \leq q < \gamma \\ \nabla u \in L^2(0,T;L^2(\Omega)) \,, & \rho |u|^2 \in L^{\infty}(0,T;L^1(\Omega)) \,. \end{cases} \end{split}$$

- Nash 1962 considered the Cauchy Problem in  $\Omega = \mathbb{R}^n$ , with large smooth initial data such that  $C_0^{-1} \leq \rho_0 \leq C_0$  for some  $C_0 > 0$ . He obtained the local-in-time existence and uniqueness of a classical solution.
- Lions 1993 considered the equations for isentropic flow,  $P(\rho) = A\rho^{\gamma}$ , with large, possibly discontinuous initial data. Under the assumption that  $\gamma \geq 3/2$  if n = 2 and  $\gamma \geq 9/5$  if n = 3, he obtained a global-in-time finite energy weak solution in a bounded or periodic domain  $\Omega \subseteq \mathbb{R}^n$ :

$$\begin{split} \rho_0 &\in L^{\gamma} \cap L^1(\Omega) \quad \text{and} \quad \sqrt{\rho_0} u_0 \in L^2(\Omega) \\ \Rightarrow \begin{cases} \rho \in L^{\infty}(0,T;L^{\gamma} \cap L^1(\Omega)) \cap C([0,\infty);L^q(\Omega)) \,, & 1 \leq q < \gamma \\ \nabla u \in L^2(0,T;L^2(\Omega)) \,, & \rho |u|^2 \in L^{\infty}(0,T;L^1(\Omega)) \,. \end{cases} \end{split}$$

- Nash 1962 considered the Cauchy Problem in  $\Omega = \mathbb{R}^n$ , with large smooth initial data such that  $C_0^{-1} \leq \rho_0 \leq C_0$  for some  $C_0 > 0$ . He obtained the local-in-time existence and uniqueness of a classical solution.
- Lions 1993 considered the equations for isentropic flow,  $P(\rho) = A\rho^{\gamma}$ , with large, possibly discontinuous initial data. Under the assumption that  $\gamma \geq 3/2$  if n = 2 and  $\gamma \geq 9/5$  if n = 3, he obtained a global-in-time finite energy weak solution in a bounded or periodic domain  $\Omega \subsetneq \mathbb{R}^n$ :

$$\begin{split} \rho_0 &\in L^{\gamma} \cap L^1(\Omega) \quad \text{and} \quad \sqrt{\rho_0} u_0 \in L^2(\Omega) \\ \Rightarrow \begin{cases} \rho \in L^{\infty}(0,T;L^{\gamma} \cap L^1(\Omega)) \cap C([0,\infty);L^q(\Omega)) \,, & 1 \leq q < \gamma \\ \nabla u \in L^2(0,T;L^2(\Omega)) \,, & \rho |u|^2 \in L^{\infty}(0,T;L^1(\Omega)) \,. \end{cases} \end{split}$$

- Nash 1962 considered the Cauchy Problem in  $\Omega = \mathbb{R}^n$ , with large smooth initial data such that  $C_0^{-1} \leq \rho_0 \leq C_0$  for some  $C_0 > 0$ . He obtained the local-in-time existence and uniqueness of a classical solution.
- Lions 1993 considered the equations for isentropic flow,  $P(\rho) = A\rho^{\gamma}$ , with large, possibly discontinuous initial data. Under the assumption that  $\gamma \geq 3/2$  if n = 2 and  $\gamma \geq 9/5$  if n = 3, he obtained a global-in-time finite energy weak solution in a bounded or periodic domain  $\Omega \subsetneq \mathbb{R}^n$ :

$$\begin{split} \rho_0 &\in L^{\gamma} \cap L^1(\Omega) \quad \text{and} \quad \sqrt{\rho_0} u_0 \in L^2(\Omega) \\ \Rightarrow \begin{cases} \rho \in L^{\infty}(0,T;L^{\gamma} \cap L^1(\Omega)) \cap C([0,\infty);L^q(\Omega)) \,, & 1 \leq q < \gamma \\ \nabla u \in L^2(0,T;L^2(\Omega)) \,, & \rho |u|^2 \in L^{\infty}(0,T;L^1(\Omega)) \,. \end{cases} \end{split}$$

#### 2. Main Theorem

포 제 표
Given T > 0 and initial data  $(\rho_0, \vec{U}_0, e_0)(\vec{x})$  in  $\vec{x} \in \mathbb{R}^n$ , we say  $(\rho, \vec{U}, e)(\vec{x}, t)$  is a weak solution to the Cauchy Problem (CNS) and (ID) in  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$  if

1. there exists an upper semi-continuous map  $\underline{r}(t): [0,T] \to [0,\infty)$  and a constant  $C_0 = C_0(\rho_0, u_0, e_0) > 0$ , such that

 $\sup_{t \in [0,T]} \underline{r}(t) \le C_0 \quad \text{and} \quad \lim_{t \to 0^+} \underline{r}(t) = 0. \quad \underline{r}(t) \text{ is called "vacuum radius"}.$ 

Using  $\underline{r}(t)$ , we define the fluid region  $\mathcal F$ , and the vacuum region  $\mathcal V$  as:

 $\mathcal{F} := \{ (\vec{x}, t) \in \mathbb{R}^n \times [0, T] : \underline{r}(t) < |\vec{x}| < \infty \} , \ \mathcal{V} := \mathbb{R}^n \backslash \mathcal{F}.$ 

2.  $\rho \in L^{\infty}_{loc}(\mathcal{F})$  and  $(\vec{U}, e) \in H^1_{loc}(\mathcal{F})$ .  $\rho(\vec{x}, t) = 0$  for a.e.  $(\vec{x}, t) \in \mathcal{V}$ .

3. the weak form of continuity equation holds for any  $\Phi \in C^1([0,T]; C^1_c(\mathbb{R}^n))$ .

4. the weak form of momentum and energy equations holds for test functions  $\Psi \in \mathcal{C}^2([0,T]; \mathcal{C}^2_c(\mathbb{R}^n))$  satisfying  $\operatorname{supp}(\Psi) \subset \mathcal{F}$ .

Given T > 0 and initial data  $(\rho_0, \vec{U}_0, e_0)(\vec{x})$  in  $\vec{x} \in \mathbb{R}^n$ , we say  $(\rho, \vec{U}, e)(\vec{x}, t)$  is a weak solution to the Cauchy Problem (CNS) and (ID) in  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$  if

1. there exists an upper semi-continuous map  $\underline{r}(t):[0,T] \to [0,\infty)$  and a constant  $C_0 = C_0(\rho_0, u_0, e_0) > 0$ , such that

 $\sup_{t\in[0,T]}\underline{r}(t)\leq C_0 \quad \text{and} \quad \lim_{t\to 0^+}\underline{r}(t)=0. \ \ \underline{r}(t) \text{ is called "vacuum radius"}.$ 

Using  $\underline{r}(t)$ , we define the fluid region  $\mathcal F$ , and the vacuum region  $\mathcal V$  as:

 $\mathcal{F} := \{ (\vec{x}, t) \in \mathbb{R}^n \times [0, T] : \underline{r}(t) < |\vec{x}| < \infty \}, \quad \mathcal{V} := \mathbb{R}^n \setminus \mathcal{F}.$ 

 $2. \ \rho \in L^{\infty}_{loc}(\mathcal{F}) \text{ and } (\vec{U},e) \in H^1_{loc}(\mathcal{F}). \ \rho(\vec{x},t) = 0 \text{ for a.e. } (\vec{x},t) \in \mathcal{V}.$ 

3. the weak form of continuity equation holds for any  $\Phi \in \mathcal{C}^1([0,T];\mathcal{C}^1_c(\mathbb{R}^n))$ .

4. the weak form of momentum and energy equations holds for test functions  $\Psi \in \mathcal{C}^2([0,T]; \mathcal{C}^2_c(\mathbb{R}^n))$  satisfying  $\operatorname{supp}(\Psi) \subset \mathcal{F}$ .

Given T > 0 and initial data  $(\rho_0, \vec{U}_0, e_0)(\vec{x})$  in  $\vec{x} \in \mathbb{R}^n$ , we say  $(\rho, \vec{U}, e)(\vec{x}, t)$  is a weak solution to the Cauchy Problem (CNS) and (ID) in  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$  if

1. there exists an upper semi-continuous map  $\underline{r}(t):[0,T] \to [0,\infty)$  and a constant  $C_0 = C_0(\rho_0, u_0, e_0) > 0$ , such that

 $\sup_{t\in[0,T]}\underline{r}(t)\leq C_0 \quad \text{and} \quad \lim_{t\to 0^+}\underline{r}(t)=0. \ \ \underline{r}(t) \text{ is called "vacuum radius"}.$ 

Using  $\underline{r}(t)$ , we define the fluid region  $\mathcal{F}$ , and the vacuum region  $\mathcal{V}$  as:

 $\mathcal{F} := \{(\vec{x},t) \in \mathbb{R}^n \times [0,T] : \underline{r}(t) < |\vec{x}| < \infty\} \text{,} \ \mathcal{V} := \mathbb{R}^n \backslash \mathcal{F}.$ 

2.  $\rho \in L^{\infty}_{loc}(\mathcal{F})$  and  $(\vec{U}, e) \in H^1_{loc}(\mathcal{F})$ .  $\rho(\vec{x}, t) = 0$  for a.e.  $(\vec{x}, t) \in \mathcal{V}$ .

3. the weak form of continuity equation holds for any  $\Phi \in C^1([0,T]; C^1_c(\mathbb{R}^n))$ .

4. the weak form of momentum and energy equations holds for test functions  $\Psi \in \mathcal{C}^2([0,T]; \mathcal{C}^2_c(\mathbb{R}^n))$  satisfying  $supp(\Psi) \subset \mathcal{F}$ .

< 一 → <

Given T > 0 and initial data  $(\rho_0, \vec{U}_0, e_0)(\vec{x})$  in  $\vec{x} \in \mathbb{R}^n$ , we say  $(\rho, \vec{U}, e)(\vec{x}, t)$  is a weak solution to the Cauchy Problem (CNS) and (ID) in  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$  if

1. there exists an upper semi-continuous map  $\underline{r}(t):[0,T] \to [0,\infty)$  and a constant  $C_0 = C_0(\rho_0, u_0, e_0) > 0$ , such that

 $\sup_{t\in[0,T]}\underline{r}(t)\leq C_0 \quad \text{and} \quad \lim_{t\to 0^+}\underline{r}(t)=0. \ \ \underline{r}(t) \text{ is called "vacuum radius"}.$ 

Using  $\underline{r}(t)$ , we define the fluid region  $\mathcal{F}$ , and the vacuum region  $\mathcal{V}$  as:

 $\mathcal{F} := \{ (\vec{x}, t) \in \mathbb{R}^n \times [0, T] : \underline{r}(t) < |\vec{x}| < \infty \} , \ \mathcal{V} := \mathbb{R}^n \backslash \mathcal{F}.$ 

 $2. \ \rho \in L^\infty_{\operatorname{\operatorname{\rm loc}}}(\mathcal{F}) \ \operatorname{\operatorname{\rm and}} \ (\vec{U},e) \in H^1_{\operatorname{\operatorname{\rm loc}}}(\mathcal{F}). \ \rho(\vec{x},t) = 0 \ \text{for a.e.} \ (\vec{x},t) \in \mathcal{V}.$ 

3. the weak form of continuity equation holds for any  $\Phi \in C^1([0,T]; C_c^1(\mathbb{R}^n))$ .

4. the weak form of momentum and energy equations holds for test functions  $\Psi \in \mathcal{C}^2([0,T]; \mathcal{C}^2_c(\mathbb{R}^n))$  satisfying  $supp(\Psi) \subset \mathcal{F}$ .

Given T > 0 and initial data  $(\rho_0, \vec{U}_0, e_0)(\vec{x})$  in  $\vec{x} \in \mathbb{R}^n$ , we say  $(\rho, \vec{U}, e)(\vec{x}, t)$  is a weak solution to the Cauchy Problem (CNS) and (ID) in  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$  if

1. there exists an upper semi-continuous map  $\underline{r}(t):[0,T] \to [0,\infty)$  and a constant  $C_0 = C_0(\rho_0, u_0, e_0) > 0$ , such that

 $\sup_{t\in[0,T]}\underline{r}(t)\leq C_0 \quad \text{and} \quad \lim_{t\to 0^+}\underline{r}(t)=0. \ \ \underline{r}(t) \text{ is called "vacuum radius"}.$ 

Using  $\underline{r}(t)$ , we define the fluid region  $\mathcal{F}$ , and the vacuum region  $\mathcal{V}$  as:

 $\mathcal{F} := \{ (\vec{x}, t) \in \mathbb{R}^n \times [0, T] : \underline{r}(t) < |\vec{x}| < \infty \} , \ \mathcal{V} := \mathbb{R}^n \backslash \mathcal{F}.$ 

- $2. \ \rho \in L^{\infty}_{loc}(\mathcal{F}) \text{ and } (\vec{U},e) \in H^1_{loc}(\mathcal{F}). \ \rho(\vec{x},t) = 0 \text{ for a.e. } (\vec{x},t) \in \mathcal{V}.$
- 3. the weak form of continuity equation holds for any  $\Phi \in C^1([0,T]; C^1_c(\mathbb{R}^n))$ .

4. the weak form of momentum and energy equations holds for test functions  $\Psi \in \mathcal{C}^2([0,T]; \mathcal{C}^2_c(\mathbb{R}^n))$  satisfying  $supp(\Psi) \subset \mathcal{F}$ .

< 一 → <

Given T > 0 and initial data  $(\rho_0, \vec{U}_0, e_0)(\vec{x})$  in  $\vec{x} \in \mathbb{R}^n$ , we say  $(\rho, \vec{U}, e)(\vec{x}, t)$  is a weak solution to the Cauchy Problem (CNS) and (ID) in  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$  if

1. there exists an upper semi-continuous map  $\underline{r}(t): [0,T] \to [0,\infty)$  and a constant  $C_0 = C_0(\rho_0, u_0, e_0) > 0$ , such that

 $\sup_{t\in[0,T]}\underline{r}(t)\leq C_0 \quad \text{and} \quad \lim_{t\to 0^+}\underline{r}(t)=0. \ \ \underline{r}(t) \text{ is called "vacuum radius"}.$ 

Using  $\underline{r}(t)$ , we define the fluid region  $\mathcal{F}$ , and the vacuum region  $\mathcal{V}$  as:

 $\mathcal{F} := \{ (\vec{x}, t) \in \mathbb{R}^n \times [0, T] : \underline{r}(t) < |\vec{x}| < \infty \} , \ \mathcal{V} := \mathbb{R}^n \backslash \mathcal{F}.$ 

 $2. \ \rho \in L^{\infty}_{loc}(\mathcal{F}) \text{ and } (\vec{U},e) \in H^1_{loc}(\mathcal{F}). \ \rho(\vec{x},t) = 0 \text{ for a.e. } (\vec{x},t) \in \mathcal{V}.$ 

- 3. the weak form of continuity equation holds for any  $\Phi \in C^1([0,T]; C^1_c(\mathbb{R}^n))$ .
- 4. the weak form of momentum and energy equations holds for test functions  $\Psi \in \mathcal{C}^2([0,T]; \mathcal{C}^2_c(\mathbb{R}^n))$  satisfying  $supp(\Psi) \subset \mathcal{F}$ .

#### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

Denote  $r = |\vec{x}|$ . Let  $(\rho_0, \vec{U}_0, e_0)(\vec{x}) = (\rho_0(r), u_0(r)\frac{\vec{x}}{r}, e_0(r))$  be a spherically symmetric initial data in  $\vec{x} \in \mathbb{R}^n$  such that, there exists  $C_0 > 0$  for which it satisfies the following conditions:

$$C_0^{-1} \le e_0(r), \quad C_0^{-1} \le \rho_0(r) \le C_0 \quad \text{for } r \in [0, \infty),$$
  
$$\int_0^\infty \{ |\rho_0 - 1|^2 + |u_0|^4 + |e_0 - 1|^2 \}(r) r^m \mathrm{d}r \le C_0,$$
  
$$\int_0^\infty \{ \frac{1}{2} \rho_0 |u_0|^2 + (\gamma - 1) G(\rho_0) + \rho_0 \psi(e_0) \}(r) r^m \mathrm{d}r \le C_0,$$

where  $G(\zeta) := 1 - \zeta + \zeta \log \zeta$  and  $\psi(\zeta) := \zeta - 1 - \log \zeta$ .

Then for any T > 0, there exists a spherically symmetric weak solution  $(\rho, \vec{U}, e)(\vec{x}, t)$  to the problem (CNS) and (ID) in the domain  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$ 

#### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

Denote  $r = |\vec{x}|$ . Let  $(\rho_0, \vec{U}_0, e_0)(\vec{x}) = (\rho_0(r), u_0(r)\frac{\vec{x}}{r}, e_0(r))$  be a spherically symmetric initial data in  $\vec{x} \in \mathbb{R}^n$  such that, there exists  $C_0 > 0$  for which it satisfies the following conditions:

$$\begin{split} C_0^{-1} &\leq e_0(r), \quad C_0^{-1} \leq \rho_0(r) \leq C_0 \qquad \text{for } r \in [0,\infty), \\ \int_0^\infty \{|\rho_0 - 1|^2 + |u_0|^4 + |e_0 - 1|^2\}(r) r^m \mathrm{d} r \leq C_0, \\ \int_0^\infty \{\frac{1}{2}\rho_0 |u_0|^2 + (\gamma - 1)G(\rho_0) + \rho_0 \psi(e_0)\}(r) r^m \mathrm{d} r \leq C_0, \end{split}$$

where  $G(\zeta) := 1 - \zeta + \zeta \log \zeta$  and  $\psi(\zeta) := \zeta - 1 - \log \zeta$ .

Then for any T > 0, there exists a spherically symmetric weak solution  $(\rho, \vec{U}, e)(\vec{x}, t)$  to the problem (CNS) and (ID) in the domain  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$ .

#### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

Denote  $r = |\vec{x}|$ . Let  $(\rho_0, \vec{U}_0, e_0)(\vec{x}) = (\rho_0(r), u_0(r)\frac{\vec{x}}{r}, e_0(r))$  be a spherically symmetric initial data in  $\vec{x} \in \mathbb{R}^n$  such that, there exists  $C_0 > 0$  for which it satisfies the following conditions:

$$\begin{split} C_0^{-1} &\leq e_0(r), \quad C_0^{-1} \leq \rho_0(r) \leq C_0 \qquad \text{for } r \in [0,\infty), \\ \int_0^\infty \{|\rho_0 - 1|^2 + |u_0|^4 + |e_0 - 1|^2\}(r) r^m \mathrm{d} r \leq C_0, \\ \int_0^\infty \left\{\frac{1}{2}\rho_0 |u_0|^2 + (\gamma - 1)G(\rho_0) + \rho_0\psi(e_0)\right\}(r) r^m \mathrm{d} r \leq C_0, \end{split}$$

where  $G(\zeta) := 1 - \zeta + \zeta \log \zeta$  and  $\psi(\zeta) := \zeta - 1 - \log \zeta$ .

Then for any T > 0, there exists a spherically symmetric weak solution  $(\rho, \vec{U}, e)(\vec{x}, t)$  to the problem (**CNS**) and (**ID**) in the domain  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$ .

#### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

Denote  $r = |\vec{x}|$ . Let  $(\rho_0, \vec{U}_0, e_0)(\vec{x}) = (\rho_0(r), u_0(r)\frac{\vec{x}}{r}, e_0(r))$  be a spherically symmetric initial data in  $\vec{x} \in \mathbb{R}^n$  such that, there exists  $C_0 > 0$  for which it satisfies the following conditions:

$$\begin{split} C_0^{-1} &\leq e_0(r), \quad C_0^{-1} \leq \rho_0(r) \leq C_0 \qquad \text{for } r \in [0,\infty), \\ \int_0^\infty \{|\rho_0 - 1|^2 + |u_0|^4 + |e_0 - 1|^2\}(r) r^m \mathrm{d} r \leq C_0, \\ \int_0^\infty \left\{\frac{1}{2}\rho_0 |u_0|^2 + (\gamma - 1)G(\rho_0) + \rho_0\psi(e_0)\right\}(r) r^m \mathrm{d} r \leq C_0, \end{split}$$

where  $G(\zeta) := 1 - \zeta + \zeta \log \zeta$  and  $\psi(\zeta) := \zeta - 1 - \log \zeta$ .

Then for any T > 0, there exists a spherically symmetric weak solution  $(\rho, \vec{U}, e)(\vec{x}, t)$  to the problem (CNS) and (ID) in the domain  $(\vec{x}, t) \in \mathbb{R}^n \times [0, T]$ .

Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094) 1. For T > 0, there exists  $C(T) = C(C_0, T) > 0$  such that

$$\operatorname{ess\,sup}_{t\in[0,T]} \int_{\mathbb{R}^n} \left\{ G(\rho) + \frac{\rho |\vec{U}|^2}{2} \right\} (\vec{x},t) \mathrm{d}\vec{x} \le C(T).$$

Moreover, there exists a positive, continuous, strictly increasing function  $g: [0, \infty) \to [0, \infty)$  with  $\lim_{y\to 0^+} g(y) = 0$  such that,

$$\operatorname{ess\,sup}_{t \in [0,T]} \int_E \rho e(\vec{x}, t) \mathrm{d}\vec{x} \le C(T) + g\left(\int_E \mathrm{d}\vec{x}\right),$$

for all bounded measurable set  $E \subset \mathbb{R}^n$ .

Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094) 1. For T > 0, there exists  $C(T) = C(C_0, T) > 0$  such that

$$\operatorname{ess\,sup}_{t\in[0,T]} \int_{\mathbb{R}^n} \left\{ G(\rho) + \frac{\rho |\vec{U}|^2}{2} \right\} (\vec{x},t) \mathrm{d}\vec{x} \le C(T).$$

Moreover, there exists a positive, continuous, strictly increasing function  $g: [0, \infty) \to [0, \infty)$  with  $\lim_{y\to 0^+} g(y) = 0$  such that,

$$\operatorname{ess\,sup}_{t\in[0,T]} \int_E \rho e(\vec{x},t) \mathrm{d}\vec{x} \le C(T) + g\left(\int_E \mathrm{d}\vec{x}\right),$$

for all bounded measurable set  $E \subset \mathbb{R}^n$ .

### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

2. There exists a continuous map  $\tilde{r}(y,t): (0,\infty) \times [0,T] \to [0,\infty)$  s.t.

2a.  $y \mapsto \tilde{r}(y,t)$  is strictly monotone increasing for all  $t \in [0, T]$ 2b.  $\underline{r}(t) = \lim_{y \to 0^+} \tilde{r}(y,t)$  for a.e.  $t \in [0,T]$ , 2c. for a.e. y > 0 and  $t \in [0,T]$ ,

 $\rho(\vec{x}, t) \mathrm{d}\vec{x} = y.$ 

Using this, one defines  $\mathcal{F}_{\varepsilon} := \{ (\vec{x}, t) \in \mathbb{R}^n \times [0, T] : |\vec{x}| \ge \tilde{r}(\varepsilon, t) \}.$ 

3. For any  $\varepsilon > 0$ , there exists  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  such that for all  $(\vec{x}, t), (\vec{y}, t), (\vec{x}, s), (\vec{x}, t) \in \mathcal{F}_{\varepsilon}$  with 0 < s < t,

$$\begin{split} t|e(\vec{x},t) - e(\vec{y},t)| + t^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{y},t)| &\leq C(\varepsilon) |\vec{x} - \vec{y}|^{\frac{1}{2}}, \\ s|e(\vec{x},t) - e(\vec{x},s)| + s^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{x},s)| &\leq C(\varepsilon) |t - s|^{\frac{1}{4}}, \\ C(\varepsilon)^{-1} &\leq \rho(\vec{x},t) \leq C(\varepsilon), \quad t^{\frac{1}{4}} |\vec{U}(\vec{x},t)| + t^{\frac{1}{2}} e(\vec{x},t) \leq C(\varepsilon). \end{split}$$

### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

2. There exists a continuous map  $\tilde{r}(y,t): (0,\infty) \times [0,T] \rightarrow [0,\infty)$  s.t. 2a.  $y \mapsto \tilde{r}(y,t)$  is strictly monotone increasing for all  $t \in [0,T]$ , 2b.  $\underline{r}(t) = \lim_{y \to 0^+} \tilde{r}(y,t)$  for a.e.  $t \in [0,T]$ , 2c. for a.e. y > 0 and  $t \in [0,T]$ ,

$$\rho(\vec{x}, t) \mathrm{d}\vec{x} = y.$$

Using this, one defines  $\mathcal{F}_{\varepsilon} := \{(\vec{x}, t) \in \mathbb{R}^n \times [0, T] : |\vec{x}| \ge \tilde{r}(\varepsilon, t)\}.$ 5. For any  $\varepsilon > 0$ , there exists  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  such that for all  $(\vec{x}, t), (\vec{y}, t), (\vec{x}, s), (\vec{x}, t) \in \mathcal{F}_{\varepsilon}$  with 0 < s < t.

$$\begin{split} t|e(\vec{x},t) - e(\vec{y},t)| + t^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{y},t)| &\leq C(\varepsilon) |\vec{x} - \vec{y}|^{\frac{1}{2}}, \\ s|e(\vec{x},t) - e(\vec{x},s)| + s^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{x},s)| &\leq C(\varepsilon) |t - s|^{\frac{1}{4}}, \\ C(\varepsilon)^{-1} &\leq \rho(\vec{x},t) \leq C(\varepsilon), \quad t^{\frac{1}{4}} |\vec{U}(\vec{x},t)| + t^{\frac{1}{2}} e(\vec{x},t) \leq C(\varepsilon). \end{split}$$

### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

2. There exists a continuous map  $\tilde{r}(y,t): (0,\infty) \times [0,T] \rightarrow [0,\infty)$  s.t. 2a.  $y \mapsto \tilde{r}(y,t)$  is strictly monotone increasing for all  $t \in [0,T]$ , 2b.  $\underline{r}(t) = \lim_{y \to 0^+} \tilde{r}(y,t)$  for a.e.  $t \in [0,T]$ , 2c. for a.e. y > 0 and  $t \in [0,T]$ ,



Using this, one defines  $\mathcal{F}_{\varepsilon} := \{(\vec{x}, t) \in \mathbb{R}^n \times [0, T] : |\vec{x}| \ge \tilde{r}(\varepsilon, t)\}.$ 5. For any  $\varepsilon > 0$ , there exists  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  such that for all  $(\vec{x}, t), (\vec{y}, t), (\vec{x}, s), (\vec{x}, t) \in \mathcal{F}_{\varepsilon}$  with 0 < s < t.

$$\begin{split} t|e(\vec{x},t) - e(\vec{y},t)| + t^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{y},t)| &\leq C(\varepsilon) |\vec{x} - \vec{y}|^{\frac{1}{2}}, \\ s|e(\vec{x},t) - e(\vec{x},s)| + s^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{x},s)| &\leq C(\varepsilon) |t - s|^{\frac{1}{4}}, \\ C(\varepsilon)^{-1} &\leq \rho(\vec{x},t) \leq C(\varepsilon), \quad t^{\frac{1}{4}} |\vec{U}(\vec{x},t)| + t^{\frac{1}{2}} e(\vec{x},t) \leq C(\varepsilon). \end{split}$$

#### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

- 2. There exists a continuous map  $\tilde{r}(y,t): (0,\infty) \times [0,T] \to [0,\infty)$  s.t.
  - 2a.  $y \mapsto \tilde{r}(y,t)$  is strictly monotone increasing for all  $t \in [0,T]$ , 2b.  $\underline{r}(t) = \lim_{y \to 0^+} \tilde{r}(y,t)$  for a.e.  $t \in [0,T]$ , 2c. for a.e. y > 0 and  $t \in [0,T]$ ,

$$\int_{\underline{r}(t) < |\vec{x}| \le \tilde{r}(y,t)} \rho(\vec{x},t) \mathrm{d}\vec{x} = y.$$

Using this, one defines  $\mathcal{F}_{\varepsilon} := \{(\vec{x}, t) \in \mathbb{R}^n \times [0, T] : |\vec{x}| \ge \tilde{r}(\varepsilon, t)\}.$ 3. For any  $\varepsilon > 0$ , there exists  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  such that for all  $(\vec{x}, t), (\vec{y}, t), (\vec{x}, s), (\vec{x}, t) \in \mathcal{F}_{\varepsilon}$  with 0 < s < t,

 $\begin{aligned} t|e(\vec{x},t) - e(\vec{y},t)| + t^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{y},t)| &\leq C(\varepsilon) |\vec{x} - \vec{y}|^{\frac{1}{2}}, \\ s|e(\vec{x},t) - e(\vec{x},s)| + s^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{x},s)| &\leq C(\varepsilon) |t - s|^{\frac{1}{4}}, \\ c(\varepsilon)^{-1} &\leq c(\vec{x},t) \leq C(\varepsilon) |t - s|^{\frac{1}{4}}, \end{aligned}$ 

#### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

- 2. There exists a continuous map  $\tilde{r}(y,t):(0,\infty)\times[0,T]\to[0,\infty)$  s.t.
  - 2a.  $y \mapsto \tilde{r}(y,t)$  is strictly monotone increasing for all  $t \in [0,T]$ , 2b.  $\underline{r}(t) = \lim_{y \to 0^+} \tilde{r}(y,t)$  for a.e.  $t \in [0,T]$ , 2c. for a.e. y > 0 and  $t \in [0,T]$ ,

$$\int_{\underline{r}(t) < |\vec{x}| \le \tilde{r}(y,t)} \rho(\vec{x},t) \mathrm{d}\vec{x} = y.$$

Using this, one defines  $\mathcal{F}_{\varepsilon} := \{(\vec{x}, t) \in \mathbb{R}^n \times [0, T] : |\vec{x}| \ge \tilde{r}(\varepsilon, t)\}.$ 

3. For any  $\varepsilon > 0$ , there exists  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  such that for all  $(\vec{x}, t), (\vec{y}, t), (\vec{x}, s), (\vec{x}, t) \in \mathcal{F}_{\varepsilon}$  with 0 < s < t,

 $\begin{aligned} t|e(\vec{x},t) - e(\vec{y},t)| + t^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{y},t)| &\leq C(\varepsilon) |\vec{x} - \vec{y}|^{\frac{1}{2}}, \\ s|e(\vec{x},t) - e(\vec{x},s)| + s^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{x},s)| &\leq C(\varepsilon) |t - s|^{\frac{1}{4}}, \end{aligned}$ 

 $C(\varepsilon)^{-1} \le \rho(\vec{x}, t) \le C(\varepsilon), \quad t^{\frac{1}{4}} |\vec{U}(\vec{x}, t)| + t^{\frac{1}{2}} e(\vec{x}, t) \le C(\varepsilon).$ 

### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

- 2. There exists a continuous map  $\tilde{r}(y,t): (0,\infty) \times [0,T] \to [0,\infty)$  s.t.
  - 2a.  $y \mapsto \tilde{r}(y,t)$  is strictly monotone increasing for all  $t \in [0,T]$ , 2b.  $\underline{r}(t) = \lim_{y \to 0^+} \tilde{r}(y,t)$  for a.e.  $t \in [0,T]$ , 2c. for a.e. y > 0 and  $t \in [0,T]$ ,

$$\int_{\underline{r}(t) < |\vec{x}| \le \tilde{r}(y,t)} \rho(\vec{x},t) \mathrm{d}\vec{x} = y.$$

Using this, one defines  $\mathcal{F}_{\varepsilon} := \{(\vec{x},t) \in \mathbb{R}^n \times [0,T] : |\vec{x}| \geq \tilde{r}(\varepsilon,t)\}.$ 

3. For any  $\varepsilon > 0$ , there exists  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  such that for all  $(\vec{x}, t), (\vec{y}, t), (\vec{x}, s), (\vec{x}, t) \in \mathcal{F}_{\varepsilon}$  with 0 < s < t,

$$\begin{split} t|e(\vec{x},t) - e(\vec{y},t)| + t^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{y},t)| &\leq C(\varepsilon) |\vec{x} - \vec{y}|^{\frac{1}{2}}, \\ s|e(\vec{x},t) - e(\vec{x},s)| + s^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{x},s)| &\leq C(\varepsilon) |t - s|^{\frac{1}{4}} \end{split}$$

 $C(\varepsilon)^{-1} \le \rho(\vec{x}, t) \le C(\varepsilon), \quad t^{\frac{1}{4}} |\vec{U}(\vec{x}, t)| + t^{\frac{1}{2}} e(\vec{x}, t) \le C(\varepsilon).$ 

#### Theorem 1.1 (G.-Q. Chen, S. Zhu, Y. H., 2022, arXiv:2208.05094)

- 2. There exists a continuous map  $\tilde{r}(y,t): (0,\infty) \times [0,T] \rightarrow [0,\infty)$  s.t.
  - 2a.  $y \mapsto \tilde{r}(y,t)$  is strictly monotone increasing for all  $t \in [0,T]$ , 2b.  $\underline{r}(t) = \lim_{y \to 0^+} \tilde{r}(y,t)$  for a.e.  $t \in [0,T]$ , 2c. for a.e. y > 0 and  $t \in [0,T]$ ,

$$\int_{\underline{r}(t) < |\vec{x}| \le \tilde{r}(y,t)} \rho(\vec{x},t) \mathrm{d}\vec{x} = y.$$

Using this, one defines  $\mathcal{F}_{\varepsilon} := \{(\vec{x}, t) \in \mathbb{R}^n \times [0, T] : |\vec{x}| \ge \tilde{r}(\varepsilon, t)\}.$ 

3. For any  $\varepsilon > 0$ , there exists  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  such that for all  $(\vec{x}, t), (\vec{y}, t), (\vec{x}, s), (\vec{x}, t) \in \mathcal{F}_{\varepsilon}$  with 0 < s < t,

$$\begin{split} t|e(\vec{x},t) - e(\vec{y},t)| + t^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{y},t)| &\leq C(\varepsilon) |\vec{x} - \vec{y}|^{\frac{1}{2}}, \\ s|e(\vec{x},t) - e(\vec{x},s)| + s^{\frac{1}{2}} |\vec{U}(\vec{x},t) - \vec{U}(\vec{x},s)| &\leq C(\varepsilon) |t - s|^{\frac{1}{4}}, \\ C(\varepsilon)^{-1} &\leq \rho(\vec{x},t) \leq C(\varepsilon), \quad t^{\frac{1}{4}} |\vec{U}(\vec{x},t)| + t^{\frac{1}{2}} e(\vec{x},t) \leq C(\varepsilon). \end{split}$$

### 2.2 Vacuum Radius and y-Mass Radius



14/30

# 3. Main Strategy

Huang, Yucong (Oxford/Edinburgh) Compressible Navier-Stokes Equations

포 제 표

If one supposes that the map  $\vec{x} \mapsto (\vec{U}, \nabla e)(\vec{x}, t)$  is continuous at the origin  $\vec{x} = \vec{0}$ . Then the spherically symmetric condition implies that

$$u(0,t) = \partial_r e(0,t) = 0 \text{ for all } t \in [0,\infty).$$

The main difficulty is the singular terms such as  $meta\partial_r\left(r^{-1}u
ight)$  and  $\kappa r^{-1}\partial_r e$  in the equations.

Motivated by  $(\mathcal{O})$ , one introduces the **Exterior Problem** with parameter  $a \in (0, 1)$ , by imposing the boundary condition:

 $u(a,t) = \partial_r e(a,t) = 0$  for  $t \in [0,\infty)$  at r = a.

Note that the above condition corresponds to a physical model where there is an insulating solid ball of radius  $a \in (0, 1)$  centred at the origin, and we call it the **Exterior Boundary Condition**.

If one supposes that the map  $\vec{x} \mapsto (\vec{U}, \nabla e)(\vec{x}, t)$  is continuous at the origin  $\vec{x} = \vec{0}$ . Then the spherically symmetric condition implies that

$$u(0,t) = \partial_r e(0,t) = 0 \text{ for all } t \in [0,\infty).$$

The main difficulty is the singular terms such as  $m\beta\partial_r(r^{-1}u)$  and  $\kappa r^{-1}\partial_r e$  in the equations.

Motivated by ( $\mathcal{O}$ ), one introduces the **Exterior Problem** with parameter  $a \in (0, 1)$ , by imposing the boundary condition:

 $u(a,t) = \partial_r e(a,t) = 0$  for  $t \in [0,\infty)$  at r = a.

Note that the above condition corresponds to a physical model where there is an insulating solid ball of radius  $a \in (0, 1)$  centred at the origin, and we call it the **Exterior Boundary Condition**.

If one supposes that the map  $\vec{x} \mapsto (\vec{U}, \nabla e)(\vec{x}, t)$  is continuous at the origin  $\vec{x} = \vec{0}$ . Then the spherically symmetric condition implies that

$$u(0,t) = \partial_r e(0,t) = 0 \text{ for all } t \in [0,\infty).$$
 (O)

The main difficulty is the singular terms such as  $m\beta\partial_r(r^{-1}u)$  and  $\kappa r^{-1}\partial_r e$  in the equations.

Motivated by  $(\mathcal{O})$ , one introduces the **Exterior Problem** with parameter  $a \in (0, 1)$ , by imposing the boundary condition:

$$u(a,t) = \partial_r e(a,t) = 0$$
 for  $t \in [0,\infty)$  at  $r = a$ .

Note that the above condition corresponds to a physical model where there is an insulating solid ball of radius  $a \in (0, 1)$  centred at the origin, and we call it the **Exterior Boundary Condition**.

If one supposes that the map  $\vec{x} \mapsto (\vec{U}, \nabla e)(\vec{x}, t)$  is continuous at the origin  $\vec{x} = \vec{0}$ . Then the spherically symmetric condition implies that

$$u(0,t) = \partial_r e(0,t) = 0 \text{ for all } t \in [0,\infty).$$
 (O)

The main difficulty is the singular terms such as  $m\beta\partial_r(r^{-1}u)$  and  $\kappa r^{-1}\partial_r e$  in the equations.

Motivated by ( $\mathcal{O}$ ), one introduces the **Exterior Problem** with parameter  $a \in (0, 1)$ , by imposing the boundary condition:

$$u(a,t) = \partial_r e(a,t) = 0$$
 for  $t \in [0,\infty)$  at  $r = a$ .

Note that the above condition corresponds to a physical model where there is an insulating solid ball of radius  $a \in (0, 1)$  centred at the origin, and we call it the **Exterior Boundary Condition**.

Furthermore, we impose the condition near far-field region  $|\vec{x}| \rightarrow \infty$ :

$$\lim_{r \to \infty} \left( \rho, u, e, \partial_r e \right) (r, t) = (1, 0, 1, 0) \quad \text{for all} \quad t \in [0, \infty) \, .$$

Combining with the previously mentioned exterior boundary condition, we define the **Eulerian (Spherically Symmetric) Exterior Problem** with radius  $a \in (0, 1)$  as

$$\begin{cases} (SNS) & \text{ in } [a, \infty) \times [0, \infty), \\ u(a, t) = \partial_r e(a, t) = 0 \\ \lim_{r \to \infty} (\rho, u, e, \partial_r e)(r, t) = (1, 0, 1, 0) \\ (\rho, u, e)(r, 0) = (\rho_a^0, u_a^0, e_a^0)(r) & \text{ for all } r \in [a, \infty). \end{cases}$$

where  $(
ho_a^0, u_a^0, e_a^0)(r)$  is the modified initial data from  $(
ho_0, u_0, e_0)(r)$ .

Furthermore, we impose the condition near far-field region  $|\vec{x}| \rightarrow \infty$ :

$$\lim_{r\to\infty}\left(\rho,u,e,\partial_r e\right)(r,t)=(1,0,1,0)\quad\text{for all}\quad t\in\left[0,\infty\right).$$

Combining with the previously mentioned exterior boundary condition, we define the **Eulerian (Spherically Symmetric) Exterior Problem** with radius  $a \in (0, 1)$  as

$$\begin{cases} ({\rm SNS}) & \text{ in } [a,\infty)\times[0,\infty), \\ u(a,t) = \partial_r e(a,t) = 0 \\ \lim_{r \to \infty} (\rho, u, e, \partial_r e)(r,t) = (1,0,1,0) \\ (\rho, u, e)(r,0) = (\rho_a^0, u_a^0, e_a^0)(r) & \text{ for all } r \in [a,\infty). \end{cases}$$
(EE)<sub>a</sub>

where  $(\rho_a^0, u_a^0, e_a^0)(r)$  is the modified initial data from  $(\rho_0, u_0, e_0)(r)$ .

# 3.2 Lagrangian Coordinate: General MD Case

Let  $(\rho, \vec{U}, e)(\vec{y}, t)$  in  $(\vec{y}, t) \in \mathbb{R}^n \times [0, \infty)$  be a solution to **(CNS)** such that  $C^{-1} \leq \rho \leq C$  for some C > 0.

For general multi-dimensional flow, Let  $\vec{X}: \mathbb{R}^n \times [0,\infty) \to \mathbb{R}^n$  be the characteristic curve satisfying:

$$\begin{cases} \frac{\mathrm{d}\vec{X}}{\mathrm{d}t}(\vec{z},t) = \vec{U}(\vec{X}(\vec{z},t),t) & \text{for } t \in [0,\infty), \\ \vec{X}(\vec{z},0) = \varphi_0(\vec{z}) & \text{for } \vec{z} \in \mathbb{R}^n, \end{cases}$$
(Char

where  $\varphi_0 : \mathbb{R}^n \to \mathbb{R}^n$  is a given diffeomorphism.

Then the **Eulerian** coordinate variables  $(\vec{y}, t) \in \mathbb{R}^n \times [0, \infty)$  and **Lagrangian** coordinate variables  $(\vec{z}, t) \in \mathbb{R}^n \times [0, \infty)$  satisfy:

$$(\vec{y},t)=(\vec{X}(\vec{z},t),t)$$

## 3.2 Lagrangian Coordinate: General MD Case

Let  $(\rho, \vec{U}, e)(\vec{y}, t)$  in  $(\vec{y}, t) \in \mathbb{R}^n \times [0, \infty)$  be a solution to **(CNS)** such that  $C^{-1} \leq \rho \leq C$  for some C > 0.

For general multi-dimensional flow, Let  $\vec{X} : \mathbb{R}^n \times [0, \infty) \to \mathbb{R}^n$  be the characteristic curve satisfying:

$$\begin{cases} \frac{\mathrm{d}\vec{X}}{\mathrm{d}t}(\vec{z},t) = \vec{U}(\vec{X}(\vec{z},t),t) & \text{for } t \in [0,\infty), \\ \vec{X}(\vec{z},0) = \varphi_0(\vec{z}) & \text{for } \vec{z} \in \mathbb{R}^n, \end{cases}$$
(Char)

where  $\varphi_0 : \mathbb{R}^n \to \mathbb{R}^n$  is a given diffeomorphism.

Then the **Eulerian** coordinate variables  $(\vec{y}, t) \in \mathbb{R}^n \times [0, \infty)$  and **Lagrangian** coordinate variables  $(\vec{z}, t) \in \mathbb{R}^n \times [0, \infty)$  satisfy:

$$(\vec{y},t)=(\vec{X}(\vec{z},t),t)$$

# 3.2 Lagrangian Coordinate: General MD Case

Let  $(\rho, \vec{U}, e)(\vec{y}, t)$  in  $(\vec{y}, t) \in \mathbb{R}^n \times [0, \infty)$  be a solution to **(CNS)** such that  $C^{-1} \leq \rho \leq C$  for some C > 0.

For general multi-dimensional flow, Let  $\vec{X} : \mathbb{R}^n \times [0, \infty) \to \mathbb{R}^n$  be the characteristic curve satisfying:

$$\begin{cases} \frac{\mathrm{d}\vec{X}}{\mathrm{d}t}(\vec{z},t) = \vec{U}(\vec{X}(\vec{z},t),t) & \text{for } t \in [0,\infty), \\ \vec{X}(\vec{z},0) = \varphi_0(\vec{z}) & \text{for } \vec{z} \in \mathbb{R}^n, \end{cases}$$
(Char)

where  $\varphi_0 : \mathbb{R}^n \to \mathbb{R}^n$  is a given diffeomorphism.

Then the **Eulerian** coordinate variables  $(\vec{y}, t) \in \mathbb{R}^n \times [0, \infty)$  and **Lagrangian** coordinate variables  $(\vec{z}, t) \in \mathbb{R}^n \times [0, \infty)$  satisfy:

$$(\vec{y},t) = (\vec{X}(\vec{z},t),t)$$

Let  $(\rho_a, \vec{U}_a, e_a)(\vec{y}, t) = (\rho_a(|\vec{y}|, t), u_a(|\vec{y}|, t) \frac{\vec{y}}{|\vec{y}|}, e(|\vec{y}|, t))$  be a symmetric solution to the Exterior Problem in  $\{|\vec{y}| \ge a\}$ . We denote  $r \equiv |\vec{y}|$  and  $x \equiv |\vec{z}|$ .

Set  $\varphi_0(\vec{z})$  as the spherically symmetric map:

$$\varphi_0(\vec{z}) = \tilde{r}_a^0(|\vec{z}|) \frac{\vec{z}}{|\vec{z}|} \quad \text{where} \quad x = \int_a^{\tilde{r}_a^0(x)} \rho_a^0(r) r^m \mathrm{d}r \quad \text{for all } x \ge 0.$$

The choice of  $\varphi_0$  physically means that  $x \ge 0$  amount of initial mass is contained in the annular domain between r = a and  $r = \tilde{r}_a^0(x)$ .

$$\begin{cases} \partial_t \tilde{r}_a(x,t) = u_a(\tilde{r}_a(x,t),t) & \text{for } t \in [0,T], \\ \tilde{r}_a(x,0) = \tilde{r}_a^0(x) & \text{for } x \ge 0. \end{cases}$$

Let  $(\rho_a, \vec{U}_a, e_a)(\vec{y}, t) = (\rho_a(|\vec{y}|, t), u_a(|\vec{y}|, t)) \frac{\vec{y}}{|\vec{y}|}, e(|\vec{y}|, t))$  be a symmetric solution to the Exterior Problem in  $\{|\vec{y}| \ge a\}$ . We denote  $r \equiv |\vec{y}|$  and  $x \equiv |\vec{z}|$ .

Set  $\varphi_0(\vec{z})$  as the spherically symmetric map:

$$\varphi_0(\vec{z}) = \tilde{r}_a^0(|\vec{z}|) \frac{\vec{z}}{|\vec{z}|} \quad \text{where} \quad x = \int_a^{\tilde{r}_a^0(x)} \rho_a^0(r) r^m \mathrm{d}r \quad \text{for all } x \ge 0.$$

The choice of  $\varphi_0$  physically means that  $x \ge 0$  amount of initial mass is contained in the annular domain between r = a and  $r = \tilde{r}_a^0(x)$ .

$$\begin{cases} \partial_t \tilde{r}_a(x,t) = u_a(\tilde{r}_a(x,t),t) & \text{for } t \in [0,T], \\ \tilde{r}_a(x,0) = \tilde{r}_a^0(x) & \text{for } x \ge 0. \end{cases}$$

Let  $(\rho_a, \vec{U}_a, e_a)(\vec{y}, t) = (\rho_a(|\vec{y}|, t), u_a(|\vec{y}|, t))\frac{\vec{y}}{|\vec{y}|}, e(|\vec{y}|, t))$  be a symmetric solution to the Exterior Problem in  $\{|\vec{y}| \ge a\}$ . We denote  $r \equiv |\vec{y}|$  and  $x \equiv |\vec{z}|$ .

Set  $\varphi_0(\vec{z})$  as the spherically symmetric map:

$$\varphi_0(\vec{z}) = \tilde{r}_a^0(|\vec{z}|) \frac{\vec{z}}{|\vec{z}|} \quad \text{where} \quad x = \int_a^{\tilde{r}_a^0(x)} \rho_a^0(r) r^m \mathrm{d}r \quad \text{for all } x \ge 0.$$

The choice of  $\varphi_0$  physically means that  $x \ge 0$  amount of initial mass is contained in the annular domain between r = a and  $r = \tilde{r}_a^0(x)$ .

$$\begin{cases} \partial_t \tilde{r}_a(x,t) = u_a(\tilde{r}_a(x,t),t) & \text{for } t \in [0,T], \\ \tilde{r}_a(x,0) = \tilde{r}_a^0(x) & \text{for } x \ge 0. \end{cases}$$

Let  $(\rho_a, \vec{U}_a, e_a)(\vec{y}, t) = (\rho_a(|\vec{y}|, t), u_a(|\vec{y}|, t))\frac{\vec{y}}{|\vec{y}|}, e(|\vec{y}|, t))$  be a symmetric solution to the Exterior Problem in  $\{|\vec{y}| \ge a\}$ . We denote  $r \equiv |\vec{y}|$  and  $x \equiv |\vec{z}|$ .

Set  $\varphi_0(\vec{z})$  as the spherically symmetric map:

$$\varphi_0(\vec{z}) = \tilde{r}_a^0(|\vec{z}|) \frac{\vec{z}}{|\vec{z}|} \quad \text{where} \quad x = \int_a^{\tilde{r}_a^0(x)} \rho_a^0(r) r^m \mathrm{d}r \quad \text{for all } x \ge 0.$$

The choice of  $\varphi_0$  physically means that  $x \ge 0$  amount of initial mass is contained in the annular domain between r = a and  $r = \tilde{r}_a^0(x)$ .

$$\begin{cases} \partial_t \tilde{r}_a(x,t) = u_a(\tilde{r}_a(x,t),t) & \text{ for } t \in [0,T], \\ \tilde{r}_a(x,0) = \tilde{r}_a^0(x) & \text{ for } x \ge 0. \end{cases}$$

# 3.2 Lagrangian Reformulation

Under spherical symmetry, the Lagrangian variables (x, t) is related to the Eulerian variables (r, t) via the relation:  $r = \tilde{r}_a(x, t)$ .

Denote  $\tilde{v}(x,t) := 1/\rho_a(\tilde{r}_a(x,t),t)$ ,  $(\tilde{u},\tilde{e})(x,t) := (u_a,e_a)(\tilde{r}_a(x,t),t)$ , and  $\tilde{r}(x,t) := \tilde{r}_a(x,t)$ . Then equations **(SNS)** can be reformulated as

$$\begin{cases} D_t \tilde{v} = D_x (\tilde{r}^m \tilde{u}) \\ D_t \tilde{u} + \tilde{r}^m D_x p(\tilde{v}, \tilde{e}) = \beta \tilde{r}^m D_x \left(\frac{D_x (\tilde{r}^m \tilde{u})}{\tilde{v}}\right) & \text{in } (x, t) \in [0, \infty)^2, \\ D_t \tilde{e} - \kappa D_x \left(\frac{\tilde{r}^{2m}}{\tilde{v}} D_x \tilde{e}\right) = \mathcal{G}(\tilde{r}, \tilde{v}, \tilde{u}, \tilde{e}) \end{cases}$$
(LNS)

where  $\mathcal{G}(r, v, u, e) = \beta \frac{|D_x(r^m u)|^2}{v} - p(v, e)D_x(r^m u) - 2m\mu D_x(r^{m-1}u^2),$ 

and  $p(v,e) := (\gamma - 1)e/v$ . Moreover (**LNS**) is supplemented with the non-linear coefficient  $\tilde{r} = \tilde{r}(x,t)$  defined by:

$$\tilde{r}(x,t) := \left(a^n + n \int_0^x \tilde{v}(z,t) \mathrm{d}z\right)^{\frac{1}{n}}$$

# 3.2 Lagrangian Reformulation

Under spherical symmetry, the Lagrangian variables (x, t) is related to the Eulerian variables (r, t) via the relation:  $r = \tilde{r}_a(x, t)$ .

Denote  $\tilde{v}(x,t) := 1/\rho_a(\tilde{r}_a(x,t),t)$ ,  $(\tilde{u},\tilde{e})(x,t) := (u_a,e_a)(\tilde{r}_a(x,t),t)$ , and  $\tilde{r}(x,t) := \tilde{r}_a(x,t)$ . Then equations (SNS) can be reformulated as

$$\begin{cases} D_t \tilde{v} = D_x(\tilde{r}^m \tilde{u}) \\ D_t \tilde{u} + \tilde{r}^m D_x p(\tilde{v}, \tilde{e}) = \beta \tilde{r}^m D_x \left(\frac{D_x(\tilde{r}^m \tilde{u})}{\tilde{v}}\right) & \text{in } (x, t) \in [0, \infty)^2, \\ D_t \tilde{e} - \kappa D_x \left(\frac{\tilde{r}^{2m}}{\tilde{v}} D_x \tilde{e}\right) = \mathcal{G}(\tilde{r}, \tilde{v}, \tilde{u}, \tilde{e}) \end{cases}$$
(LNS)

where 
$$\mathcal{G}(r, v, u, e) = \beta \frac{|D_x(r^m u)|^2}{v} - p(v, e)D_x(r^m u) - 2m\mu D_x(r^{m-1}u^2),$$

and  $p(v,e) := (\gamma - 1)e/v$ . Moreover **(LNS)** is supplemented with the non-linear coefficient  $\tilde{r} = \tilde{r}(x,t)$  defined by:

$$\tilde{r}(x,t) := \left(a^n + n \int_0^x \tilde{v}(z,t) \mathrm{d}z\right)^{\frac{1}{n}}$$
### 3.2 Lagrangian Reformulation

Under spherical symmetry, the Lagrangian variables (x, t) is related to the Eulerian variables (r, t) via the relation:  $r = \tilde{r}_a(x, t)$ .

Denote  $\tilde{v}(x,t) := 1/\rho_a(\tilde{r}_a(x,t),t)$ ,  $(\tilde{u},\tilde{e})(x,t) := (u_a,e_a)(\tilde{r}_a(x,t),t)$ , and  $\tilde{r}(x,t) := \tilde{r}_a(x,t)$ . Then equations (SNS) can be reformulated as

$$\begin{cases} D_t \tilde{v} = D_x(\tilde{r}^m \tilde{u}) \\ D_t \tilde{u} + \tilde{r}^m D_x p(\tilde{v}, \tilde{e}) = \beta \tilde{r}^m D_x \left(\frac{D_x(\tilde{r}^m \tilde{u})}{\tilde{v}}\right) & \text{in } (x, t) \in [0, \infty)^2, \quad (LNS) \\ D_t \tilde{e} - \kappa D_x \left(\frac{\tilde{r}^{2m}}{\tilde{v}} D_x \tilde{e}\right) = \mathcal{G}(\tilde{r}, \tilde{v}, \tilde{u}, \tilde{e}) \end{cases}$$

where 
$$\mathcal{G}(r, v, u, e) = \beta \frac{|D_x(r^m u)|^2}{v} - p(v, e)D_x(r^m u) - 2m\mu D_x(r^{m-1}u^2),$$

and  $p(v,e) := (\gamma - 1)e/v$ . Moreover (LNS) is supplemented with the non-linear coefficient  $\tilde{r} = \tilde{r}(x,t)$  defined by:

$$\tilde{r}(x,t) := \left(a^n + n \int_0^x \tilde{v}(z,t) \mathrm{d}z\right)^{\frac{1}{n}}$$

### 3.2 Lagrangian Reformulation

Under spherical symmetry, the Lagrangian variables (x, t) is related to the Eulerian variables (r, t) via the relation:  $r = \tilde{r}_a(x, t)$ .

Denote  $\tilde{v}(x,t) := 1/\rho_a(\tilde{r}_a(x,t),t)$ ,  $(\tilde{u},\tilde{e})(x,t) := (u_a,e_a)(\tilde{r}_a(x,t),t)$ , and  $\tilde{r}(x,t) := \tilde{r}_a(x,t)$ . Then equations (SNS) can be reformulated as

$$\begin{cases} D_t \tilde{v} = D_x(\tilde{r}^m \tilde{u}) \\ D_t \tilde{u} + \tilde{r}^m D_x p(\tilde{v}, \tilde{e}) = \beta \tilde{r}^m D_x \left(\frac{D_x(\tilde{r}^m \tilde{u})}{\tilde{v}}\right) & \text{in } (x, t) \in [0, \infty)^2, \\ D_t \tilde{e} - \kappa D_x \left(\frac{\tilde{r}^{2m}}{\tilde{v}} D_x \tilde{e}\right) = \mathcal{G}(\tilde{r}, \tilde{v}, \tilde{u}, \tilde{e}) \end{cases}$$
(LNS)

where 
$$\mathcal{G}(r, v, u, e) = \beta \frac{|D_x(r^m u)|^2}{v} - p(v, e)D_x(r^m u) - 2m\mu D_x(r^{m-1}u^2),$$

and  $p(v,e) := (\gamma - 1)e/v$ . Moreover **(LNS)** is supplemented with the non-linear coefficient  $\tilde{r} = \tilde{r}(x,t)$  defined by:

$$\tilde{r}(x,t) := \left(a^n + n \int_0^x \tilde{v}(z,t) \mathrm{d}z\right)^{\frac{1}{n}}.$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ ● ● ●

·· · · · · ·

(1) Construct  $(v_{a,k}, u_{a,k}, e_{a,k})$  to the approximation Lagrangian problem:

$$\begin{cases} (LNS) \\ r_{a,k}(x,t) = \left(a^n + n \int_0^x v_{a,k}(y,t) dy\right)^{\frac{1}{n}} & \text{ in } [0,k] \times [0,\infty), \\ u_{a,k}(0,t) = D_x e_{a,k}(0,t) = 0 \\ u_{a,k}(k,t) = D_x e_{a,k}(k,t) = 0 \\ (v_{a,k}, u_{a,k}, e_{a,k})|_{t=0} = (v_{a,k}^0, u_{a,k}^0, e_{a,k}^0) & \text{ for } x \in [0,k]. \end{cases}$$

$$(LE)_{a,k}$$

(2) Convert the approximate solutions into Eulerian coordinate:

 $(\bar{\rho}_{a,k}, \bar{u}_{a,k}, \bar{e}_{a,k})(r,t) = (v_{a,k}^{-1}, u_{a,k}, e_{a,k})(x_{a,k}(r,t), t)$ 

where  $r \mapsto x_{a,k}(r,t)$  is the inverse of  $x \mapsto r_{a,k}(x,t)$ .

(3) Extend  $(\bar{\rho}_{a,k}, \bar{u}_{a,k}, \bar{e}_{a,k})(r, t)$  into  $r \in [0, \infty)$  by cut-off function  $\varphi_{a,k}(r)$ :

 $\tilde{\rho}_{a,k}=\bar{\rho}_{a,k}\varphi_{a,k}+(1-\varphi_{a,k}), \ \ \tilde{e}_{a,k}=\bar{e}_{a,k}\varphi_{a,k}+(1-\varphi_{a,k}), \ \ \tilde{u}_{a,k}=\bar{u}_{a,k}\varphi_{a,k}.$ 

(1) Construct  $(v_{a,k}, u_{a,k}, e_{a,k})$  to the approximation Lagrangian problem:

$$\begin{cases} (LNS) \\ r_{a,k}(x,t) = \left(a^n + n \int_0^x v_{a,k}(y,t) dy\right)^{\frac{1}{n}} & \text{ in } [0,k] \times [0,\infty), \\ u_{a,k}(0,t) = D_x e_{a,k}(0,t) = 0 & \\ u_{a,k}(k,t) = D_x e_{a,k}(k,t) = 0 & \text{ for } t \in [0,\infty), \\ (v_{a,k}, u_{a,k}, e_{a,k})|_{t=0} = (v_{a,k}^0, u_{a,k}^0, e_{a,k}^0) & \text{ for } x \in [0,k]. \end{cases}$$

(2) Convert the approximate solutions into Eulerian coordinate:

 $(\bar{\rho}_{a,k}, \bar{u}_{a,k}, \bar{e}_{a,k})(r,t) = (v_{a,k}^{-1}, u_{a,k}, e_{a,k})(x_{a,k}(r,t), t)$ 

where  $r \mapsto x_{a,k}(r,t)$  is the inverse of  $x \mapsto r_{a,k}(x,t)$ .

(3) Extend  $(\bar{\rho}_{a,k}, \bar{u}_{a,k}, \bar{e}_{a,k})(r, t)$  into  $r \in [0, \infty)$  by cut-off function  $\varphi_{a,k}(r)$ :  $\tilde{\rho}_{a,k} = \bar{\rho}_{a,k}\varphi_{a,k} + (1-\varphi_{a,k}), \quad \tilde{e}_{a,k} = \bar{e}_{a,k}\varphi_{a,k} + (1-\varphi_{a,k}), \quad \tilde{u}_{a,k} = \bar{u}_{a,k}\varphi_{a,k}$ 

. .....

(1) Construct  $(v_{a,k}, u_{a,k}, e_{a,k})$  to the approximation Lagrangian problem:

$$\begin{cases} (LNS) \\ r_{a,k}(x,t) = \left(a^n + n \int_0^x v_{a,k}(y,t) \mathrm{d}y\right)^{\frac{1}{n}} & \text{ in } [0,k] \times [0,\infty), \\ u_{a,k}(0,t) = D_x e_{a,k}(0,t) = 0 \\ u_{a,k}(k,t) = D_x e_{a,k}(k,t) = 0 \\ (v_{a,k}, u_{a,k}, e_{a,k})|_{t=0} = (v_{a,k}^0, u_{a,k}^0, e_{a,k}^0) & \text{ for } x \in [0,k]. \end{cases}$$

$$(LE)_{a,k}$$

(2) Convert the approximate solutions into Eulerian coordinate:

$$(\bar{\rho}_{a,k}, \bar{u}_{a,k}, \bar{e}_{a,k})(r,t) = (v_{a,k}^{-1}, u_{a,k}, e_{a,k})(x_{a,k}(r,t), t)$$

where  $r \mapsto x_{a,k}(r,t)$  is the inverse of  $x \mapsto r_{a,k}(x,t)$ .

(3) Extend  $(\bar{\rho}_{a,k}, \bar{u}_{a,k}, \bar{e}_{a,k})(r, t)$  into  $r \in [0, \infty)$  by cut-off function  $\varphi_{a,k}(r)$ :

$$\tilde{\rho}_{a,k}=\bar{\rho}_{a,k}\varphi_{a,k}+(1-\varphi_{a,k}), \quad \tilde{e}_{a,k}=\bar{e}_{a,k}\varphi_{a,k}+(1-\varphi_{a,k}), \quad \tilde{u}_{a,k}=\bar{u}_{a,k}\varphi_{a,k}.$$

·· · · · · ·

(1) Construct  $(v_{a,k}, u_{a,k}, e_{a,k})$  to the approximation Lagrangian problem:

$$\begin{cases} (LNS) \\ r_{a,k}(x,t) = \left(a^n + n \int_0^x v_{a,k}(y,t) dy\right)^{\frac{1}{n}} & \text{ in } [0,k] \times [0,\infty), \\ u_{a,k}(0,t) = D_x e_{a,k}(0,t) = 0 \\ u_{a,k}(k,t) = D_x e_{a,k}(k,t) = 0 \\ (v_{a,k}, u_{a,k}, e_{a,k})|_{t=0} = (v_{a,k}^0, u_{a,k}^0, e_{a,k}^0) & \text{ for } x \in [0,k]. \end{cases}$$

$$(LE)_{a,k}$$

(2) Convert the approximate solutions into Eulerian coordinate:

$$(\bar{\rho}_{a,k}, \bar{u}_{a,k}, \bar{e}_{a,k})(r,t) = (v_{a,k}^{-1}, u_{a,k}, e_{a,k})(x_{a,k}(r,t), t)$$

where  $r \mapsto x_{a,k}(r,t)$  is the inverse of  $x \mapsto r_{a,k}(x,t)$ .

(3) Extend  $(\bar{\rho}_{a,k}, \bar{u}_{a,k}, \bar{e}_{a,k})(r, t)$  into  $r \in [0, \infty)$  by cut-off function  $\varphi_{a,k}(r)$ :

$$\tilde{\rho}_{a,k} = \bar{\rho}_{a,k}\varphi_{a,k} + (1-\varphi_{a,k}), \quad \tilde{e}_{a,k} = \bar{e}_{a,k}\varphi_{a,k} + (1-\varphi_{a,k}), \quad \tilde{u}_{a,k} = \bar{u}_{a,k}\varphi_{a,k}.$$

To take limit  $k \to \infty$  and  $a \to 0^+$ , some uniform estimates on  $(v_{a,k}, u_{a,k}, e_{a,k})$  are required. This is achieved by first obtaining the **uniform point-wise upper** and lower bounds on density.

#### Lemma 2.1 (Entropy Estimate)

Set  $\psi(\zeta) := \zeta - \log \zeta - 1$ , and define  $S := (\gamma - 1)\psi(v) + \psi(e) + \frac{|u|^2}{2}$  to be the entropy. If (v, u, e) is a solution to the approximation Lagrangian Exterior Problem  $(\mathsf{LE})_{a,k}$  then

$$\int_0^k \mathcal{S}(x,t) dx + \int_0^t \int_0^k \left\{ \left(\frac{2\mu}{n} + \lambda\right) \frac{|D_x(r^m u)|^2}{ve} + \kappa \frac{r^{2m} |D_x e|^2}{ve^2} \right\} dx dt$$
$$= \int_0^k \mathcal{S}(x,0) dx.$$

To take limit  $k \to \infty$  and  $a \to 0^+$ , some uniform estimates on  $(v_{a,k}, u_{a,k}, e_{a,k})$  are required. This is achieved by first obtaining the **uniform point-wise upper** and lower bounds on density.

#### Lemma 2.1 (Entropy Estimate)

Set  $\psi(\zeta) := \zeta - \log \zeta - 1$ , and define  $S := (\gamma - 1)\psi(v) + \psi(e) + \frac{|u|^2}{2}$  to be the entropy. If (v, u, e) is a solution to the approximation Lagrangian Exterior Problem  $(\mathsf{LE})_{a,k}$  then

$$\begin{split} &\int_0^k \mathcal{S}(x,t) \mathrm{d}x + \int_0^t \int_0^k \left\{ \left(\frac{2\mu}{n} + \lambda\right) \frac{|D_x(r^m u)|^2}{ve} + \kappa \frac{r^{2m} |D_x e|^2}{ve^2} \right\} \mathrm{d}x \mathrm{d}t \\ &= \int_0^k \mathcal{S}(x,0) \mathrm{d}x. \end{split}$$

Substitute the continuity equation  $D_t v = D_x(r^m u)$  into the momentum equation:

$$D_t u + r^m D_x p = \beta r^m D_x \Big( rac{D_x(r^m u)}{v} \Big), \ \ \text{where} \ \ \beta = 2\mu + \lambda > 0,$$

then multiply both sides by  $r^{-m}$ , and since  $D_t r(x,t) = u(x,t)$ , we have

$$D_t\left(\frac{u}{r^m}\right) + m\frac{|u|^2}{r^n} + D_x p = \beta D_t D_x \log v.$$

Integrating the above equation in the region  $(y, s) \in [x_1, x_2] \times [0, t]$  and then take exponential on both sides, we get the **representation formula for density** 

$$\begin{aligned} &\frac{v_0(x_2)v(x_1,t)}{v_0(x_1)v(x_2,t)} \\ &= \exp\left(\int_{x_1}^{x_2} \frac{u}{\beta r^m} \mathrm{d}y \Big|_{s=t}^{s=0} + \int_0^t \frac{\gamma-1}{\beta} \frac{e}{v} \mathrm{d}s \Big|_{y=x_2}^{y=x_1} - \int_0^t \int_{x_1}^{x_2} \frac{m|u|^2}{\beta r^n} \mathrm{d}y \mathrm{d}s \right) \equiv \mathcal{I}. \end{aligned}$$

Substitute the continuity equation  $D_t v = D_x(r^m u)$  into the momentum equation:

$$D_t u + r^m D_x p = \beta r^m D_x \Big( rac{D_x(r^m u)}{v} \Big), \ \ \text{where} \ \ \beta = 2\mu + \lambda > 0,$$

then multiply both sides by  $r^{-m}$ , and since  $D_t r(x,t) = u(x,t)$ , we have

$$D_t\left(\frac{u}{r^m}\right) + m\frac{|u|^2}{r^n} + D_x p = \beta D_t D_x \log v.$$

Integrating the above equation in the region  $(y,s) \in [x_1, x_2] \times [0,t]$  and then take exponential on both sides, we get the **representation formula for density** 

$$\begin{aligned} &\frac{v_0(x_2)v(x_1,t)}{v_0(x_1)v(x_2,t)} \\ &= \exp\left(\int_{x_1}^{x_2} \frac{u}{\beta r^m} \mathrm{d}y\Big|_{s=t}^{s=0} + \int_0^t \frac{\gamma-1}{\beta} \frac{e}{v} \mathrm{d}s\Big|_{y=x_2}^{y=x_1} - \int_0^t \int_{x_1}^{x_2} \frac{m|u|^2}{\beta r^n} \mathrm{d}y \mathrm{d}s\right) \equiv \mathcal{I}. \end{aligned}$$

23 / 30

$$\begin{aligned} &\frac{v_0(x_2)v(x_1,t)}{v_0(x_1)v(x_2,t)} \\ &= \exp\left(\int_{x_1}^{x_2} \frac{u}{\beta r^m} \mathrm{d}y\Big|_{s=t}^{s=0} + \int_0^t \frac{\gamma-1}{\beta} \frac{e}{v} \mathrm{d}s\Big|_{y=x_2}^{y=x_1} - \int_0^t \int_{x_1}^{x_2} \frac{m|u|^2}{\beta r^n} \mathrm{d}y \mathrm{d}s\right) \equiv \mathcal{I}. \end{aligned}$$

 ${\mathcal I}$  can be bounded by Grönwall's inequality and the entropy estimate, Lemma 2.1.

From this formula for density, we can determine two **explicit** functions  $\overline{v}(x,t), \underline{v}(x,t) : [0,k] \times [0,\infty] \to (0,\infty)$ , which are independent of (a,k) so that

 $\underline{v}(\varepsilon,T) \leq v(x,t) \leq \overline{v}(\varepsilon,T) \ \, \text{for all} \ \, (x,t) \in [\varepsilon,k] \times [0,T] \text{, for each } \varepsilon > 0.$ 

The restriction  $x \in [\varepsilon, k]$  comes from the lower bound of r(x, t). By entropy estimate  $\int_{0}^{k} \psi(v) dx \leq C_{0}$ , and Jensen's inequality, one has for each  $\varepsilon > 0$ ,

$$\left(n\varepsilon\psi_{-}^{-1}\left(\frac{C_{0}}{\varepsilon}\right)\right)^{\frac{1}{n}} \leq r(x,t) \text{ in } (x,t) \in [\varepsilon,k] \times [0,\infty).$$

where  $\psi_{-}^{-1}(\cdot): [0,\infty) \to (0,1]$  is the left branch inverse of  $\psi(\zeta) = \zeta - 1 - \log \zeta$ .

< ロ > < 同 > < 回 > < 回 >

$$\begin{aligned} &\frac{v_0(x_2)v(x_1,t)}{v_0(x_1)v(x_2,t)} \\ &= \exp\left(\int_{x_1}^{x_2} \frac{u}{\beta r^m} \mathrm{d}y\Big|_{s=t}^{s=0} + \int_0^t \frac{\gamma-1}{\beta} \frac{e}{v} \mathrm{d}s\Big|_{y=x_2}^{y=x_1} - \int_0^t \int_{x_1}^{x_2} \frac{m|u|^2}{\beta r^n} \mathrm{d}y \mathrm{d}s\right) \equiv \mathcal{I}. \end{aligned}$$

 ${\cal I}$  can be bounded by Grönwall's inequality and the entropy estimate, Lemma 2.1.

From this formula for density, we can determine two **explicit** functions  $\overline{v}(x,t), \underline{v}(x,t) : [0,k] \times [0,\infty] \to (0,\infty)$ , which are independent of (a,k) so that

 $\underline{v}(\varepsilon,T) \leq v(x,t) \leq \overline{v}(\varepsilon,T) \ \, \text{for all} \ \, (x,t) \in [\varepsilon,k] \times [0,T] \text{, for each } \varepsilon > 0.$ 

The restriction  $x \in [\varepsilon, k]$  comes from the lower bound of r(x, t). By entropy estimate  $\int_{0}^{k} \psi(v) dx \leq C_{0}$ , and Jensen's inequality, one has for each  $\varepsilon > 0$ ,

$$\left(n\varepsilon\psi_{-}^{-1}\left(\frac{C_{0}}{\varepsilon}\right)\right)^{\frac{1}{n}} \leq r(x,t) \text{ in } (x,t) \in [\varepsilon,k] \times [0,\infty).$$

where  $\psi_{-}^{-1}(\cdot): [0,\infty) \to (0,1]$  is the left branch inverse of  $\psi(\zeta) = \zeta - 1 - \log \zeta$ .

$$\frac{v_0(x_2)v(x_1,t)}{v_0(x_1)v(x_2,t)} = \exp\left(\int_{x_1}^{x_2} \frac{u}{\beta r^m} \mathrm{d}y\Big|_{s=t}^{s=0} + \int_0^t \frac{\gamma-1}{\beta} \frac{e}{v} \mathrm{d}s\Big|_{y=x_2}^{y=x_1} - \int_0^t \int_{x_1}^{x_2} \frac{m|u|^2}{\beta r^n} \mathrm{d}y \mathrm{d}s\right) \equiv \mathcal{I}.$$

 ${\cal I}$  can be bounded by Grönwall's inequality and the entropy estimate, Lemma 2.1.

From this formula for density, we can determine two **explicit** functions  $\overline{v}(x,t), \underline{v}(x,t) : [0,k] \times [0,\infty] \to (0,\infty)$ , which are independent of (a,k) so that

$$\underline{v}(\varepsilon,T) \leq v(x,t) \leq \overline{v}(\varepsilon,T) \ \, \text{for all} \ \, (x,t) \in [\varepsilon,k] \times [0,T] \text{, for each } \varepsilon > 0.$$

The restriction  $x \in [\varepsilon, k]$  comes from the lower bound of r(x, t). By entropy estimate  $\int_0^k \psi(v) dx \leq C_0$ , and Jensen's inequality, one has for each  $\varepsilon > 0$ ,

$$\left(n\varepsilon\psi_{-}^{-1}\left(\frac{C_{0}}{\varepsilon}\right)\right)^{\frac{1}{n}} \leq r(x,t) \text{ in } (x,t) \in [\varepsilon,k] \times [0,\infty).$$

where  $\psi_{-}^{-1}(\cdot): [0,\infty) \to (0,1]$  is the left branch inverse of  $\psi(\zeta) = \zeta - 1 - \log \zeta$ .

$$\begin{aligned} &\frac{v_0(x_2)v(x_1,t)}{v_0(x_1)v(x_2,t)} \\ &= \exp\left(\int_{x_1}^{x_2} \frac{u}{\beta r^m} \mathrm{d}y\Big|_{s=t}^{s=0} + \int_0^t \frac{\gamma-1}{\beta} \frac{e}{v} \mathrm{d}s\Big|_{y=x_2}^{y=x_1} - \int_0^t \int_{x_1}^{x_2} \frac{m|u|^2}{\beta r^n} \mathrm{d}y \mathrm{d}s\right) \equiv \mathcal{I}. \end{aligned}$$

 ${\cal I}$  can be bounded by Grönwall's inequality and the entropy estimate, Lemma 2.1.

From this formula for density, we can determine two **explicit** functions  $\overline{v}(x,t), \underline{v}(x,t) : [0,k] \times [0,\infty] \to (0,\infty)$ , which are independent of (a,k) so that

 $\underline{v}(\varepsilon,T) \leq v(x,t) \leq \overline{v}(\varepsilon,T) \ \, \text{for all} \ \, (x,t) \in [\varepsilon,k] \times [0,T] \text{, for each } \varepsilon > 0.$ 

The restriction  $x \in [\varepsilon, k]$  comes from the lower bound of r(x, t). By entropy estimate  $\int_0^k \psi(v) dx \le C_0$ , and Jensen's inequality, one has for each  $\varepsilon > 0$ ,  $\left(n\varepsilon\psi_-^{-1}\left(\frac{C_0}{\varepsilon}\right)\right)^{\frac{1}{n}} \le r(x, t)$  in  $(x, t) \in [\varepsilon, k] \times [0, \infty)$ .

where  $\psi_{-}^{-1}(\cdot):[0,\infty)\to(0,1]$  is the left branch inverse of  $\psi(\zeta)=\zeta-1-\log\zeta$ .

$$\frac{v_0(x_2)v(x_1,t)}{v_0(x_1)v(x_2,t)} = \exp\left(\int_{x_1}^{x_2} \frac{u}{\beta r^m} \mathrm{d}y\Big|_{s=t}^{s=0} + \int_0^t \frac{\gamma-1}{\beta} \frac{e}{v} \mathrm{d}s\Big|_{y=x_2}^{y=x_1} - \int_0^t \int_{x_1}^{x_2} \frac{m|u|^2}{\beta r^n} \mathrm{d}y \mathrm{d}s\right) \equiv \mathcal{I}.$$

 ${\cal I}$  can be bounded by Grönwall's inequality and the entropy estimate, Lemma 2.1.

From this formula for density, we can determine two **explicit** functions  $\overline{v}(x,t), \underline{v}(x,t) : [0,k] \times [0,\infty] \to (0,\infty)$ , which are independent of (a,k) so that

$$\underline{v}(\varepsilon,T) \leq v(x,t) \leq \overline{v}(\varepsilon,T) \ \, \text{for all} \ \, (x,t) \in [\varepsilon,k] \times [0,T] \text{, for each } \varepsilon > 0.$$

The restriction  $x \in [\varepsilon, k]$  comes from the lower bound of r(x, t). By entropy estimate  $\int_0^k \psi(v) dx \leq C_0$ , and Jensen's inequality, one has for each  $\varepsilon > 0$ ,

$$\left(n\varepsilon\psi_-^{-1}\bigl(\frac{C_0}{\varepsilon}\bigr)\right)^{\frac{1}{n}} \leq r(x,t) \ \ \text{in} \ \ (x,t)\in [\varepsilon,k]\times [0,\infty).$$

where  $\psi_{-}^{-1}(\cdot):[0,\infty)\to (0,1]$  is the left branch inverse of  $\psi(\zeta)=\zeta-1-\log\zeta$ .

Once the point-wise upper and lower bounds of v(x,t) and r(x,t) are obtained, one can utilise the parabolic structure:

$$D_t u - \beta r^m D_x \left( \frac{D_x(r^m u)}{v} \right) = \{ \cdots \}, \qquad D_t e - \kappa D_x \left( \frac{r^{2m}}{v} D_x e \right) = \{ \cdots \},$$

to derive the **uniform a-priori estimates** on u(x,t) and e(x,t).

#### Lemma 2.2

Assume (v, u, e)(x, t) solves  $(\mathsf{LE})_{a,k}$ . Then, for each  $\varepsilon \in (0, 1]$  there exists a constant  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  independent of (a, k) such that  $\mathcal{L}_{\varepsilon}[v, u, e](T) \leq C(\varepsilon)$ , where  $\sigma(t) := \min\{1, t\}$  and

$$\begin{aligned} \mathcal{L}_{\varepsilon}[v, u, e](T) &\coloneqq \sup_{t \in [0, T]} \int_{\varepsilon}^{k} |(v - 1, u^2, e - 1, \sqrt{\sigma(t)} r^m D_x u, \sigma(t) r^m D_x e)|^2 \mathrm{d}x \\ &+ \int_{0}^{T} \int_{\varepsilon}^{k} |(r^m D_x u, r^m D_x e, \sqrt{\sigma(t)} D_t u, \sigma(t) D_t e)|^2 \mathrm{d}x \mathrm{d}t. \end{aligned}$$

Once the point-wise upper and lower bounds of v(x,t) and r(x,t) are obtained, one can utilise the parabolic structure:

$$D_t u - \beta r^m D_x \left( \frac{D_x(r^m u)}{v} \right) = \{ \cdots \}, \qquad D_t e - \kappa D_x \left( \frac{r^{2m}}{v} D_x e \right) = \{ \cdots \},$$

to derive the **uniform a-priori estimates** on u(x,t) and e(x,t).

#### Lemma 2.2

Assume (v, u, e)(x, t) solves  $(\mathsf{LE})_{a,k}$ . Then, for each  $\varepsilon \in (0, 1]$  there exists a constant  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  independent of (a, k) such that  $\mathcal{L}_{\varepsilon}[v, u, e](T) \leq C(\varepsilon)$ , where  $\sigma(t) := \min\{1, t\}$  and

$$\mathcal{L}_{\varepsilon}[v, u, e](T) \coloneqq \sup_{t \in [0, T]} \int_{\varepsilon}^{k} |(v - 1, u^2, e - 1, \sqrt{\sigma(t)} r^m D_x u, \sigma(t) r^m D_x e)|^2 \mathrm{d}x + \int_{0}^{T} \int_{\varepsilon}^{k} |(r^m D_x u, r^m D_x e, \sqrt{\sigma(t)} D_t u, \sigma(t) D_t e)|^2 \mathrm{d}x \mathrm{d}t.$$

3 🕨 🖌 3 🕨

э

Once the point-wise upper and lower bounds of v(x,t) and r(x,t) are obtained, one can utilise the parabolic structure:

$$D_t u - \beta r^m D_x \left( \frac{D_x(r^m u)}{v} \right) = \{ \cdots \}, \qquad D_t e - \kappa D_x \left( \frac{r^{2m}}{v} D_x e \right) = \{ \cdots \},$$

to derive the **uniform a-priori estimates** on u(x,t) and e(x,t).

#### Lemma 2.2

Assume (v, u, e)(x, t) solves  $(\mathsf{LE})_{a,k}$ . Then, for each  $\varepsilon \in (0, 1]$  there exists a constant  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  independent of (a, k) such that  $\mathcal{L}_{\varepsilon}[v, u, e](T) \leq C(\varepsilon)$ , where  $\sigma(t) := \min\{1, t\}$  and

$$\mathcal{L}_{\varepsilon}[v, u, e](T) := \sup_{t \in [0, T]} \int_{\varepsilon}^{k} |(v - 1, u^2, e - 1, \sqrt{\sigma(t)} r^m D_x u, \sigma(t) r^m D_x e)|^2 \mathrm{d}x + \int_{0}^{T} \int_{\varepsilon}^{k} |(r^m D_x u, r^m D_x e, \sqrt{\sigma(t)} D_t u, \sigma(t) D_t e)|^2 \mathrm{d}x \mathrm{d}t.$$

くロ と く 同 と く ヨ と 一

3

Once the point-wise upper and lower bounds of v(x,t) and r(x,t) are obtained, one can utilise the parabolic structure:

$$D_t u - \beta r^m D_x \left( \frac{D_x(r^m u)}{v} \right) = \{ \cdots \}, \qquad D_t e - \kappa D_x \left( \frac{r^{2m}}{v} D_x e \right) = \{ \cdots \},$$

to derive the **uniform a-priori estimates** on u(x,t) and e(x,t).

#### Lemma 2.2

Assume (v, u, e)(x, t) solves  $(\mathsf{LE})_{a,k}$ . Then, for each  $\varepsilon \in (0, 1]$  there exists a constant  $C(\varepsilon) = C(\varepsilon, T, C_0) > 0$  independent of (a, k) such that  $\mathcal{L}_{\varepsilon}[v, u, e](T) \leq C(\varepsilon)$ , where  $\sigma(t) := \min\{1, t\}$  and

$$\begin{aligned} \mathcal{L}_{\varepsilon}[v, u, e](T) &\coloneqq \sup_{t \in [0, T]} \int_{\varepsilon}^{k} |(v - 1, u^2, e - 1, \sqrt{\sigma(t)} r^m D_x u, \sigma(t) r^m D_x e)|^2 \mathrm{d}x \\ &+ \int_{0}^{T} \int_{\varepsilon}^{k} |(r^m D_x u, r^m D_x e, \sqrt{\sigma(t)} D_t u, \sigma(t) D_t e)|^2 \mathrm{d}x \mathrm{d}t. \end{aligned}$$

- ₹ 🖬 🕨

(1) Since  $C(\varepsilon)^{-1} \leq v(x,t) \leq C(\varepsilon)$  is restricted in  $x \in [\varepsilon,k]$ , it is necessary to incorporate a cut-off function  $g_{\varepsilon} \in C^1([0,\infty])$  such that  $\operatorname{supp}(g_{\varepsilon}) \subseteq [\varepsilon,\infty)$ .

However, integration by parts with  $g_{\varepsilon}$  leads to a problematic boundary term:

$$\int_0^T\!\!\int_{\varepsilon}^{2\varepsilon} \{e+|u|^2\}(x,t)\,\mathrm{d}x\mathrm{d}t,$$

which cannot be bounded with the standard parabolic estimate. This can be resolved by using **dissipation terms** in the entropy estimate:

$$\int_0^T \!\! \int_0^k \left\{ \left(\frac{2\mu}{n} + \lambda\right) \frac{|D_x(r^m u)|^2}{ve} + \kappa \frac{r^{2m}|D_x e|^2}{ve^2} \right\} \mathrm{d}x \mathrm{d}t \le \int_0^k \mathcal{S}(x, 0) \mathrm{d}x.$$

(2) The gain of regularity on (u, e), indicated by the weight  $\sigma(t) = \min\{1, t\}$ , is due to not only parabolic operators, but also the **Effective Viscosity Flux:** 

$$F := (2\mu + \lambda) \operatorname{div} \vec{U} - (P(\rho, e) - 1) = (2\mu + \lambda) \frac{D_x(r^m u)}{v} - (p(v, e) - 1).$$

(1) Since  $C(\varepsilon)^{-1} \leq v(x,t) \leq C(\varepsilon)$  is restricted in  $x \in [\varepsilon,k]$ , it is necessary to incorporate a cut-off function  $g_{\varepsilon} \in C^1([0,\infty])$  such that  $\operatorname{supp}(g_{\varepsilon}) \subseteq [\varepsilon,\infty)$ . However, integration by parts with  $g_{\varepsilon}$  leads to a problematic boundary term:

$$\int_0^T \int_{\varepsilon}^{2\varepsilon} \{e + |u|^2\}(x,t) \,\mathrm{d}x \mathrm{d}t,$$

which cannot be bounded with the standard parabolic estimate. This can be resolved by using **dissipation terms** in the entropy estimate:

$$\int_0^T \!\! \int_0^k \left\{ \left(\frac{2\mu}{n} + \lambda\right) \frac{|D_x(r^m u)|^2}{ve} + \kappa \frac{r^{2m}|D_x e|^2}{ve^2} \right\} \mathrm{d}x \mathrm{d}t \le \int_0^k \mathcal{S}(x, 0) \mathrm{d}x.$$

(2) The gain of regularity on (u, e), indicated by the weight  $\sigma(t) = \min\{1, t\}$ , is due to not only parabolic operators, but also the **Effective Viscosity Flux**:

$$F := (2\mu + \lambda) \operatorname{div} \vec{U} - (P(\rho, e) - 1) = (2\mu + \lambda) \frac{D_x(r^m u)}{v} - (p(v, e) - 1).$$

(1) Since  $C(\varepsilon)^{-1} \leq v(x,t) \leq C(\varepsilon)$  is restricted in  $x \in [\varepsilon,k]$ , it is necessary to incorporate a cut-off function  $g_{\varepsilon} \in C^1([0,\infty])$  such that  $\operatorname{supp}(g_{\varepsilon}) \subseteq [\varepsilon,\infty)$ . However, integration by parts with  $g_{\varepsilon}$  leads to a problematic boundary term:

$$\int_0^T\!\!\int_{\varepsilon}^{2\varepsilon} \{e+|u|^2\}(x,t)\,\mathrm{d}x\mathrm{d}t,$$

which cannot be bounded with the standard parabolic estimate. This can be resolved by using **dissipation terms** in the entropy estimate:

$$\int_0^T \!\!\int_0^k \left\{ \big(\frac{2\mu}{n} + \lambda\big) \frac{|D_x(r^m u)|^2}{ve} + \kappa \frac{r^{2m}|D_x e|^2}{ve^2} \right\} \mathrm{d}x \mathrm{d}t \le \int_0^k \mathcal{S}(x, 0) \mathrm{d}x.$$

(2) The gain of regularity on (u, e), indicated by the weight  $\sigma(t) = \min\{1, t\}$ , is due to not only parabolic operators, but also the **Effective Viscosity Flux**:

$$F := (2\mu + \lambda) \operatorname{div} \vec{U} - (P(\rho, e) - 1) = (2\mu + \lambda) \frac{D_x(r^m u)}{v} - (p(v, e) - 1).$$

(1) Since  $C(\varepsilon)^{-1} \leq v(x,t) \leq C(\varepsilon)$  is restricted in  $x \in [\varepsilon,k]$ , it is necessary to incorporate a cut-off function  $g_{\varepsilon} \in C^1([0,\infty])$  such that  $\operatorname{supp}(g_{\varepsilon}) \subseteq [\varepsilon,\infty)$ . However, integration by parts with  $g_{\varepsilon}$  leads to a problematic boundary term:

$$\int_0^T \int_{\varepsilon}^{2\varepsilon} \{e + |u|^2\}(x,t) \,\mathrm{d}x \mathrm{d}t,$$

which cannot be bounded with the standard parabolic estimate. This can be resolved by using **dissipation terms** in the entropy estimate:

$$\int_0^T \!\! \int_0^k \left\{ \left(\frac{2\mu}{n} + \lambda\right) \frac{|D_x(r^m u)|^2}{ve} + \kappa \frac{r^{2m}|D_x e|^2}{ve^2} \right\} \mathrm{d}x \mathrm{d}t \le \int_0^k \mathcal{S}(x, 0) \mathrm{d}x.$$

(2) The gain of regularity on (u, e), indicated by the weight  $\sigma(t) = \min\{1, t\}$ , is due to not only parabolic operators, but also the **Effective Viscosity Flux**:

$$F := (2\mu + \lambda) \operatorname{div} \vec{U} - (P(\rho, e) - 1) = (2\mu + \lambda) \frac{D_x(r^m u)}{v} - (p(v, e) - 1).$$

(1) Since  $C(\varepsilon)^{-1} \leq v(x,t) \leq C(\varepsilon)$  is restricted in  $x \in [\varepsilon,k]$ , it is necessary to incorporate a cut-off function  $g_{\varepsilon} \in C^1([0,\infty])$  such that  $\operatorname{supp}(g_{\varepsilon}) \subseteq [\varepsilon,\infty)$ . However, integration by parts with  $g_{\varepsilon}$  leads to a problematic boundary term:

$$\int_0^T \int_{\varepsilon}^{2\varepsilon} \{e + |u|^2\}(x,t) \,\mathrm{d}x \mathrm{d}t,$$

which cannot be bounded with the standard parabolic estimate. This can be resolved by using **dissipation terms** in the entropy estimate:

$$\int_0^T \!\! \int_0^k \left\{ \left(\frac{2\mu}{n} + \lambda\right) \frac{|D_x(r^m u)|^2}{ve} + \kappa \frac{r^{2m}|D_x e|^2}{ve^2} \right\} \mathrm{d}x \mathrm{d}t \le \int_0^k \mathcal{S}(x, 0) \mathrm{d}x.$$

(2) The gain of regularity on (u, e), indicated by the weight  $\sigma(t) = \min\{1, t\}$ , is due to not only parabolic operators, but also the **Effective Viscosity Flux**:

$$F := (2\mu + \lambda) \operatorname{div} \vec{U} - (P(\rho, e) - 1) = (2\mu + \lambda) \frac{D_x(r^m u)}{v} - (p(v, e) - 1).$$

(1) Since  $C(\varepsilon)^{-1} \leq v(x,t) \leq C(\varepsilon)$  is restricted in  $x \in [\varepsilon,k]$ , it is necessary to incorporate a cut-off function  $g_{\varepsilon} \in C^1([0,\infty])$  such that  $\operatorname{supp}(g_{\varepsilon}) \subseteq [\varepsilon,\infty)$ . However, integration by parts with  $g_{\varepsilon}$  leads to a problematic boundary term:

$$\int_0^T \int_{\varepsilon}^{2\varepsilon} \{e + |u|^2\}(x,t) \,\mathrm{d}x \mathrm{d}t,$$

which cannot be bounded with the standard parabolic estimate. This can be resolved by using **dissipation terms** in the entropy estimate:

$$\int_0^T \!\! \int_0^k \left\{ \left(\frac{2\mu}{n} + \lambda\right) \frac{|D_x(r^m u)|^2}{ve} + \kappa \frac{r^{2m}|D_x e|^2}{ve^2} \right\} \mathrm{d}x \mathrm{d}t \le \int_0^k \mathcal{S}(x, 0) \mathrm{d}x.$$

(2) The gain of regularity on (u, e), indicated by the weight  $\sigma(t) = \min\{1, t\}$ , is due to not only parabolic operators, but also the **Effective Viscosity Flux**:

$$F := (2\mu + \lambda) \operatorname{div} \vec{U} - (P(\rho, e) - 1) = (2\mu + \lambda) \frac{D_x(r^m u)}{v} - (p(v, e) - 1).$$

### 4. References

< □ > <

∃ ► < ∃ ►</p>

æ

# 4.1 References: 1D and MD Spherically Symmetric

- A. V. Kazhikhov and V. V. Shelukhin (1977). "Unique global solution with respect to time of initial-boundary value problems for one-dimensional equations of a viscous gas". In: *Prikl. Mat. Meh.* 41.2, pp. 282–291
- Shuichi Kawashima and Takaaki Nishida (1981). "Global solutions to the initial value problem for the equations of one-dimensional motion of viscous polytropic gases". In: J. Math. Kyoto Univ. 21.4, pp. 825–837
- David Hoff and Helge Kristian Jenssen (2004). "Symmetric nonbarotropic flows with large data and forces". In: Arch. Ration. Mech. Anal. 173.3, pp. 297–343
- Song Jiang (1996). "Global spherically symmetric solutions to the equations of a viscous polytropic ideal gas in an exterior domain". In: *Comm. Math. Phys.* 178.2, pp. 339–374

- J. Nash (1962). "The Cauchy problem for differential equations of a general fluid". In: *Bull. Soc. Math. Fr.* 90, pp. 487–497
- P.-L. Lions (1993). "Compacité des solutions des équations de Navier-Stokes compressibles isentropiques". In: C. R. Acad. Sci. Paris Sér. I Math. 317.1, pp. 115–120

### THANK YOU FOR YOUR ATTENTION!

▶ ∢ ⊒ ▶

< (17) < (17)

э