# Harmonic Analysis

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#### Contents

- 1. First lecture: a general frame for Fourier Analysis
- 2. Second lecture: Fourier analysis in the torus.
- 3. Third lecture: Fourier analysis in  ${\ensuremath{\mathsf{R}}}^{\ensuremath{\mathsf{d}}}$
- 4. Fourth lecture: Distributions

## First lecture: A general frame for Fourier Analysis

- Origins of Fourier analysis: Fourier, Euler, D'Alembert.
- ► Four different settings:  $R^d$ ,  $T^d$ , Z,  $Z_N$
- Why sines and cosines? The characters in a group, the Fourier transform.
- Translation invariant operators. Convolutions, multipliers, regularization, Young's inequality.
- Approximations of the identity. Density of test functions

# Origins of Fourier Analysis

Solving the vibrating string, the heath diffusion problems with the separation of variable method and *the statement* that an arbitrary function in an interval can be expressed as a superposition of sines and cosines

$$f(x) = \sum_{n=0}^{+\infty} c_n(f) e^{2\pi i n x}$$

with

$$c_n(f)=\int_0^1 f(x)e^{-2\pi i n x}dx.$$

A *a*- periodic function is superposition of the sines and cosines having period *a*. For (non-periodic) arbitrary functions, making  $a \rightarrow +\infty$ 

$$f(x) = \int_{\mathbf{R}} c_{\xi}(f) e^{2\pi i x \cdot \xi} d\xi, c_{\xi}(f) = \int_{\mathbf{R}} f(x) e^{-2\pi i \xi \cdot x} dx.$$

## Locally compact abelian groups

- Discrete:  $\mathbf{Z}^{\mathbf{d}}$ ,  $Z_N = N$ -th roots of unity.
- Continuous: R<sup>d</sup>, T<sup>d</sup>
- Haar Measure: Lebesgue L<sup>p</sup>(G) spaces
- ► Translation operator:  $\tau_x, x \in G, \tau_x f)(y) = f(y x)$ .
- ► Translation-invariant spaces: spaces E such that \(\tau\_x f \in E\) whenever f \(\in E\), and \(\tau\_x f\) is continuous in x. For instance, all \(L^p\) spaces are.
- ►  $T: E \to E$  is said to be a *translation invariant operator (tip)* if  $\tau_x(Tf) = T(\tau_x f), x \in G$ .
- ► a differential operator *T* is time-invariant iff it has constant coefficients.

- We look for functions f such that the smallest translation-invariant space containing f has dimension one.
- ► This means that for  $x \in G$ ,  $\tau_x f$  must be a scalar multiple of f;  $\tau_x f = \chi(-x)f$ ,  $f(y - x) = \chi(-x)f(y)$ ,  $x, y \in G$ .
- χ is continuous and so is f. Since τ<sub>x</sub>τ<sub>y</sub> = τ<sub>x+y</sub>, χ must satisfy χ(x + y) = χ(x)χ(y), x, y ∈ G.
- Specializing to y = 0 yields  $f(-x) = \chi(-x)f(0)$ .
- Therefore f is a scalar multiple of  $\chi$ .
- A *character* of *G* is a continuous non-zero homomorphism  $\chi: G \to \mathbf{C}$ .
- Bounded:  $\chi : G \rightarrow \mathbf{T}$ .
- ► The set of bounded characters of *G* has a natural group structure and constitute the so-called *dual group*  $\widehat{G}$ .

## Why are characters useful?

- χ a character, T a translation invariant operator acting on a space containing χ,
- $\chi$  satisfies  $\tau_x \chi = \chi(-x)\chi, x \in G$ , as function of y
- If T commutes with translations

$$\tau_x(T\chi) = T(\tau_x\chi) = T(\chi(-x)\chi) = \chi(-x)T(\chi)$$

- $(T\chi)(y-x) = \chi(-x)T(\chi)(y), x, y \in G.$
- If we set y = 0,  $T\chi = \lambda\chi$  with  $\lambda = T(\chi)(0)$ ,
- The characters of a group are eigenvectors of all translation invariant operators

# The group of characters in $\mathbf{R}^{\mathbf{d}}$ and $\mathbf{T}^{\mathbf{d}}$

▶ In **R**, 
$$\int_{x}^{x+h} \chi(z) dz = \int_{0}^{h} \chi(x+y) dy = \chi(x) \int_{0}^{h} \chi(y) dy$$
.

• This implies that  $\chi$  is differentiable.

$$\chi'(x) = \lim_{y \to 0} \frac{\chi(x+y) - \chi(x)}{y} = \chi'(0)\chi(x).$$

• Hence 
$$\chi(x) = e^{\alpha x}$$
 for some  $\alpha \in \mathbf{C}$ .

- $\blacktriangleright \ \ln \mathbf{R}^{\mathbf{d}}, \alpha \in \mathbf{C}^{\mathbf{d}}, \alpha \cdot \mathbf{x} = \alpha_{1}\mathbf{x}_{1} + \dots + \alpha_{\mathbf{d}}\mathbf{x}_{\mathbf{d}}.$
- ► Bounded:  $\alpha = 2\pi i \xi$ ,  $e_{\xi}(x) = e^{2\pi i \xi \cdot x}$ ,  $\xi \in \mathbf{R}^{\mathbf{d}}$ .
- ▶ In  $\mathbf{T}^{\mathbf{d}} = \mathbf{R}^{\mathbf{d}} / \mathbf{Z}^{\mathbf{d}}$ : those of the above that are  $\mathbf{Z}^{\mathbf{d}}$ -periodic,  $\alpha = 2\pi i n$  for  $n \in \mathbf{Z}^{\mathbf{d}}$ .
- Thus the dual group of R<sup>d</sup> is identified with R<sup>d</sup> and the dual group of T<sup>d</sup> is identified with Z<sup>d</sup>.

# The group of characters in $\mathbf{Z}^{\mathbf{d}}$ and $Z_N$

▶ In  $Z^d$ ,  $\mathbf{n} \mapsto \mathbf{z}^n$ ,  $\mathbf{z} \in \mathbf{C}^d$ , bounded characters correspond to  $|z_j| = 1$ ,  $\mathbf{x}_j = \mathbf{z}_j^n = \mathbf{z}_j^{2\pi i t \cdot n}$ 

$$\chi_z(n)=z^n=e^{2\pi it\cdot n}.$$

Thus the dual group of  $Z^d$  is identified with  $T^d$ .

- We identify the cyclic group Z<sub>N</sub> with {0, 1, ..., N − 1} and functions there with N- periodic sequences x = (x<sub>n</sub>) indexed by n ∈ Z.
- If ω<sub>N</sub> = e<sup>2πi/N</sup> denotes the primitive root of unity, it is immediate to check that the dual group is Z<sub>N</sub> itself through

$$\psi_m(n) = \omega_N^{nm}, n \in \mathbf{Z}, \mathbf{m} = \mathbf{0}, \mathbf{1}, \dots, \mathbf{N} - \mathbf{1}.$$

## The Fourier transform

- ► In linear algebra, to deal with a linear operator T on C<sup>d</sup> (look at vectors as functions defined on 1, 2, ... n) we try to diagonalize it in a basis of eigenvectors.
- Characters are eigenvectors of T.
- If the characters of G constitute a basis of some sort in E then we will have that all translation-invariant operators on E diagonalize simultaneously in a basis of characters.
- Complex exponentials are linearly independent

$$\sum_{k} c_k e^{2\pi i \xi_k \cdot x} = 0 \implies c_k = 0$$

• The Fourier transform of a function  $f \in L^1(G)$  is the function  $\hat{f}$  on  $\hat{G}$  defined by correlating with bounded characters

$$\widehat{f}(\chi) = \langle f, \chi \rangle = \int_{\mathcal{G}} f \overline{\chi} d\mu, f \in L^1(\mathcal{G})$$

The map f ∈ L<sup>1</sup>(G) → f̂ ∈ L<sup>∞</sup>(Ĝ) is called the Fourier transform in G.

## Multiplier of a translation invariant operator

- $\widehat{G}$  has a natural structure of group and a Haar measure  $d\nu$ .
- Hope the  $\chi$  behave like an orthonormal basis

$$f = \int_{\widehat{G}} \widehat{f}(\chi) \chi \, d\nu(\chi) = \int_{\widehat{G}} \langle f, \chi \rangle \chi \, d\nu(\chi)$$

that is (inversion formula)

$$f(x) = \int_{\widehat{G}} \widehat{f}(\chi) \chi(x) \, d\nu(\chi), x \in G.$$

Since T commutes with infinite sums and χ is a eigenvector of T, say T(χ) = m(χ)χ,

$$Tf = \int_{\widehat{G}} \widehat{f}(\chi) T(\chi) \, d\nu(\chi) = \int_{\widehat{G}} \widehat{f}(\chi) m(\chi) \chi \, d\nu(\chi).$$

•  $Tf(x) = \int_{\widehat{G}} \widehat{f}(\chi) m(\chi) \chi(x) d\nu(\chi)$ . *m* is the *multiplier* of *T*.

Another way to look at t.i.o.'s: convolution, impulse function

• Kernel of a linear operator  $T: L^p(G) \to L^q(G)$ 

$$f = \int_{G} \delta_{x} f(x) d\mu(x) \implies Tf = \int_{G} T(\delta_{x}) f(x) d\mu(x),$$
$$Tf(y) = \int_{G} K_{x}(y) f(x) d\mu(x), K(x, y) = T(\delta_{x})(y)$$

- ► K(x, y) is the continuous version of a matrix.
- If T commutes with translations, set  $g(y) = K_0(y) = T(\delta_0)(y)$ . Then  $\delta_x = \tau_x(\delta_0) \implies K_x = T(\delta_x) = T(\tau_x \delta_0) = \tau_x T(\delta_0) = \tau_x g, K(x, y) = g(y - x)$ .
- Formally, all translations invariant operators are given by convolution

$$Tf(y) = (f * g)(y) = \int_G g(y - x)f(x)d\mu(x),$$

with a fixed "object" g, the impulse response.

By now, g a function or a measure.

#### Relationship between both views

- There is a relation between g and m.
- This follows from the fact the Fourier transform of a convolution is the product of Fourier transforms

$$\widehat{f * g}(\chi) = \int_{G} (f * g)(y)\overline{\chi(y)}d\mu(y) =$$
$$= \int_{G} \int_{G} g(y - x)f(x)\overline{\chi(y - x)}\chi(x)d\mu(x)d\mu(y) =$$
$$= \widehat{f}(\chi)\widehat{g}(\chi)$$

• Hence, formally  $m = \hat{g}$ .

$$Tf = f * g \equiv \widehat{Tf} = m\widehat{f}, m = \widehat{g}.$$

#### Convolution as a mean

f \* g is an (infinite) linear combination of translates of g,

$$f * g = \int_G \tau_x(g) f(x) d\mu(x).$$

*f* \* *g* = *g* \* *f*, *f* \* (*g* \* *h*) = (*f* \* *g*) \* *h*.
 In case *g* ∈ *L*<sup>1</sup>(*G*), *g* ≥ 0, 
$$\int_{G} gd\mu = 1$$
,

$$(f * g)(y) = \int_G f(y - x)g(x)d\mu(x)$$
 weighted average of  $f$ .

g = 1/(B) 1<sub>B</sub>, (f ∗ g)(y) = mean value of f in the ball y + B.
 Think g as density of a random variable X, then

$$f * g(y) = E(f(y - X)).$$

# When is f \* g well defined? Properties of f \* g

Schur's criteria for boundedness of operators  $T : L^p(G) \rightarrow L^q(G)$ 

$$Tf(y) = \int_G K(x, y)f(x)d\mu(x).$$

► Assume  $1 \le p, q, r \le +\infty, \frac{1}{p} + \frac{1}{r} = 1 + \frac{1}{q}$  and

$$\sup_x (\int_Y |\mathcal{K}(x,y)|^r d\nu(y))^{\frac{1}{r}} \leq C, \sup_y (\int_X |\mathcal{K}(x,y)|^r d\mu(x))^{\frac{1}{r}} \leq C.$$

- ► Then T is bounded from  $L^{p}(X)$  to  $L^{p}(Y)$  with constant  $||T|| \leq C$ .
- q = +∞ it follows from Holder's inequality (p, r conjugate exponents).

• 
$$r = +\infty(p = q)$$
 is trivial:  $|Tf| \le C|f|$ 

• 
$$p = +\infty$$
 ( $r = 1, q = +\infty$  trivial;

▶ p = 1, r = q Continuous Minkowski inequality:

$$\|\int f(x)K(x,\cdot)d\mu(x)\|_q\leq \int |f(x)|\|K(x,\cdot)\|_q d\mu(x)$$

### Proof of Schur's lemma

Assume all indexes are finite, positive  $K, f \in L^{p}(X), g \in L^{q'}(Y)$ . The hypothesis imply that

$$\frac{1}{r'} + \frac{1}{q} + \frac{1}{p'} = 1, \frac{p}{q} + \frac{p}{q'} = 1, \frac{r}{q} + \frac{r}{p'} = 1.$$

Using Holder's inequality with r', q, p',

$$\begin{split} |Tf(y)| &\leq \int_{X} |f(x)|^{\frac{p}{r'}} |f(x)|^{\frac{p}{q}} |K(x,y)|^{\frac{r}{q}} |K(x,y)|^{\frac{r}{p'}} d\mu(x) \leq \\ &\leq \|f\|_{p}^{\frac{p}{r'}} \left( \int_{X} |f(x)|^{p} |K(x,y)|^{r} d\mu(x) \right)^{\frac{1}{q}} \left( \int_{X} |K(x,y)|^{r} d\mu(x) \right)^{\frac{1}{p'}} \leq \\ &\leq C^{\frac{r}{p'}} \|f\|_{p}^{\frac{p}{r'}} \left( \int_{X} |f(x)|^{p} |K(x,y)|^{r} d\mu(x) \right)^{\frac{1}{q}} \end{split}$$

## Continuation of Schur's proof. Young's inequality

Raising to q and integrating in y gives

$$\|Tf\|_{q} \leq C^{\frac{r}{p'}} \|f\|_{p}^{\frac{p}{r'}} \left( \int_{X} \int_{Y} |f(x)|^{p} |K(x,y)|^{r} d\mu(x) \right)^{\frac{1}{q}} = C^{\frac{r}{p'}} \|f\|_{p}^{\frac{p}{r'}} C^{\frac{r}{q}} \|f\|_{p}^{\frac{p}{q}} = C \|f\|_{p}$$

$$K(x,y) = g(x-y) \rightarrow$$
Young's inequality:

Suppose

$$1 \leq p,q,r \leq +\infty, rac{1}{p}+rac{1}{r}=1+rac{1}{q}, f \in L^p(G), g \in L^r(G).$$

Then

$$(f * g)(y) = \int_G g(y - x)f(x)d\mu(x),$$

converges absolutely for a.e y,  $f * g \in L^q(G)$  and  $||f * g||_q \le ||f||_p ||g||_r$ .

## Local version of Young's inequality

In case  $G = \mathbf{R}^{\mathbf{d}}$  we can state a local version of Young's inequality, in which one of the functions has compact support while the other is locally in the corresponding  $L^{p}$ -space.

Suppose 1 ≤ p, q, r ≤ +∞,  $\frac{1}{p} + \frac{1}{r} = 1 + \frac{1}{q}$ , f ∈ L<sup>p</sup><sub>loc</sub>(G), g ∈ L<sup>r</sup><sub>c</sub>(G).
Then

$$f * g(y) = \int_G g(y-x)f(x)d\mu(x),$$

converges absolutely for a.e y, and  $f * g \in L^q_{loc}(G)$ .

#### Convolution as regularization

 $G = \mathbf{R}^{\mathbf{d}}, \mathbf{G} = \mathbf{T}^{\mathbf{d}}$ , look at the regularity properties of f \* g.

► Suppose 
$$1 \le p, r \le +\infty, \frac{1}{p} + \frac{1}{r} = 1$$

- Either  $f \in L^p(G), g \in L^r(G), f \in L^p_{loc}(G), g \in L^r_c(G)$  or  $f \in L^p_c(G), g \in L^r_{loc}(G)$ .
- Then f \* g is a continuous function.
- ▶ Assume that f (resp. g) is differentiable at every point and that its partial derivatives  $\frac{\partial f}{\partial x_i}$  (respectively  $\frac{\partial g}{\partial x_i}$ ) satisfy the same hypothesis of f (resp. g). Then f \* g is differentiable and

$$\frac{\partial}{\partial x_i}(f * g) = \frac{\partial f}{\partial x_i} * g, (\text{respectively} = f * \frac{\partial g}{\partial x_i}).$$

• f \* g inherits the regularity properties of both f, g.

$$D^{\alpha}(f * g) = (D^{\alpha}f) * g$$
, (respectively  $= f * D^{\alpha}g$ ),

holds whenever one the the right terms makes sense.

## Approximate identities. Regularization

- Consider the group Z. We will describe all translation invariant operators T : I<sup>1</sup>(Z) → I<sup>q</sup>(Z).
- ► Easy because the formal argument is OK: δ<sub>0</sub> ∈ l<sup>1</sup>(Z). Define g = T(δ<sub>0</sub>) = (g<sub>n</sub>) ∈ l<sup>q</sup>(Z).
- If  $x = (x_n) \in l^1(\mathsf{Z}), \mathsf{x} = \sum \mathsf{x}_n \tau_n(\delta_0)$  is convergent in  $l^1(\mathsf{Z})$

$$Tx = \sum_n x_n \tau_n g, (Tx)_m = \sum_n x_n g_{m-n}, Tx = x * g$$

►  $T : l^1(Z) \rightarrow l^q(Z)t.i.o. \equiv Tx = x * g, g \in l^q(Z)$ , by continuous Minkowsky inequality.

## Approximations of the identity

- ▶ Non discrete groups G = T<sup>d</sup> or G = R<sup>d</sup>, the delta mass is not a function but a measure, so it does not belong to any L<sup>p</sup> space.
- ► However there is a good replacement for it. Note that δ is the formal unit for convolution, f \* δ = f.
- In what follows G = T<sup>d</sup> or G = R<sup>d</sup> with additive notation and dx Lebesgue measure.
- An approximate identity (or approximate kernel) is a family (k<sub>ε</sub>) of functions in L<sup>1</sup>(G) satisfying

1. 
$$\int_{G} k_{\varepsilon} dx = 1.$$
  
2. 
$$\int_{G} |k_{\varepsilon}| dx \leq C, \text{ for some constant } C > 0.$$
  
3. For any  $\delta > 0, \int_{|x| > \delta} |k_{\varepsilon}(x)| dx \to 0 \text{ as } \varepsilon \to 0$ 

## Examples

- If  $k \in L^1(G)$ ,  $\int_g k = 1$ , set  $k_{\varepsilon}(x) = \varepsilon^{-d} k(x/\varepsilon)$ .
- The first two conditions are obvious, while for the third one

$$\int_{|x|>\delta}|k_{arepsilon}(x)|dx=\int_{|x|>rac{\delta}{arepsilon}}|k(x)|dx
ightarrow 0.$$

(rests of an absolutely convergent integral).

- ► The simplest example is to take as k the normalized characteristic function of the unit ball, k(x) = 1/|B| if x ∈ B and zero otherwise.
- ► Then f \* k<sub>ε</sub>(x) is simply the mean of f in x + B<sub>ε</sub>, the ball centered at x of radious ε.

#### The Poisson and Gauss kernels

▶ The *Poisson family* in **R**<sup>d</sup> that corresponds to

$$k(x) = c_d \frac{1}{(|x|^2 + 1)^{\frac{d+1}{2}}}, c_d = \frac{\Gamma(\frac{d+1}{2})}{\pi^{\frac{d+1}{2}}},$$

The Gaussian kernel is given by

$$k(x) = \frac{1}{(\sqrt{2\pi})^d} e^{-\frac{1}{2}|x|^2}.$$

On the torus T<sup>d</sup> we will see later that natural examples appear when dealing with convergence of the Fourier series, namely the Fejer kernel. We may consider as well approximations of the identity indexed by n ∈ N with obvious modifications.

### They do approximate $\delta_0$

- If  $(k_{\varepsilon})$  is an approximation of the identity and  $f \in L^{p}(G), 1 \leq p < +\infty$ , then  $f * k_{\varepsilon} \to f$  in  $L^{p}(G)$  as  $\varepsilon \to 0$ .
- If  $f \in C_0(G)$ , then  $f * k_{\varepsilon} \to f$  uniformly on G.
- If  $f \in L^1(G)$  and f is continuous at a point  $x_0$ , then  $(f * k_{\varepsilon})(x_0) \to f(x_0)$ .

We can write

$$f - f * k_{\varepsilon} = f - \int_{G} \tau_{x}(f)k_{\varepsilon}(x)d\mu(x) = \int_{G} (f - \tau_{x}(f))k_{\varepsilon}(x)d\mu(x),$$

and hence, by the continuous Minkowski inequality

$$\|f-f*k_{\varepsilon}\|_{p}\leq\int_{\mathcal{G}}\|f- au_{x}(f))\|_{p}|k_{\varepsilon}(x)|d\mu(x).$$

## Continuation of proof. Consequences

To estimate it we break the above in two parts, corresponding to small x, say ||x|| ≤ δ, and ||x|| > δ. The first one is estimated by

$$C\sup_{\|x\|\leq\delta}\|f-\tau_x(f)\|_p,$$

and hence can be made arbitrarily small if  $\delta$  is small enough, uniformly in  $\varepsilon$ , due to the continuity of translations in  $L^{p}(G)$ , while the second is estimated by

$$2\|f\|_p\int_{|x|>\delta}|k_{\varepsilon}(x)|dx.$$

A bounded operator T from L<sup>p</sup>(R<sup>d</sup>) to L<sup>q</sup>(R<sup>d</sup>), 1 ≤ p, q < +∞ is a t.i.o. if and only if commutes with convolution with L<sup>1</sup> functions, that is,

$$T(f * g) = f * Tg, f \in L^1(\mathbf{R}^d), \mathbf{g} \in \mathbf{L}^{\mathbf{p}}(\mathbf{R}^d).$$

By Minkowski's continuous inequality, the right hand side of

$$f * g = \int_G (\tau_x g) f(x) d\mu(x),$$

is convergent in  $L^{p}$ , hence if T commutes with translations,

$$T(f*g) = \int_G f(x)T(\tau_x g) d\mu(x) = \int_G f(x)\tau_x Tg d\mu(x) = f*Tg.$$

If T commutes with convolutions, we consider an approximation of the identity k<sub>ε</sub> so that

$$T(\tau_{x}g) = \lim_{\varepsilon} T((\tau_{x}g) * k_{\varepsilon}) = \lim_{\varepsilon} T(g * (\tau_{x}k_{\varepsilon}))$$
$$= \lim_{\varepsilon} (Tg) * (\tau_{x}k_{\varepsilon}) = \tau_{x}(\lim_{\varepsilon} (Tg) * k_{\varepsilon}) = \tau_{x}(Tg).$$

## Density of test functions

- The space of infinitely differentiable functions C<sup>∞</sup>(T<sup>d</sup>) is dense in all L<sup>p</sup>(T<sup>d</sup>) spaces, 1 ≤ p < ∞. The space C<sup>∞</sup><sub>c</sub>(R<sup>d</sup>) of infinitely differentiable functions with compact support is dense in all L<sup>p</sup>(R<sup>d</sup>) spaces, 1 ≤ p < +∞.</p>
- Proof: the space of continuous functions with compact support is dense. If f is in this space, and we take an approximation of the identity k<sub>ε</sub>(x) = ε<sup>-d</sup>k(x/ε), with k a C<sup>∞</sup> function with compact support, then k<sub>ε</sub> \* f ∈ C<sup>∞</sup><sub>c</sub>(ℝ<sup>d</sup>) and tends to f in L<sup>p</sup>.
- ▶ The same proof shows that for an open set  $U \subset \mathbf{R}^{\mathbf{d}}$  the space  $C_{c}^{\infty}(U)$  is dense in all  $L^{p}(U)$  spaces as well.

## Path to distributions

If 
$$f \in L^1_{loc}(U)$$
 and  $\int_U f(x) arphi(x) \, dx = 0$ 

for all  $\varphi \in C^\infty_c(U)$ , then f = 0 a.e.

The same is true if

$$\int_B f(x) dx = 0$$

for all balls  $B \subset U$ .

*Remark*: for most of the approximations of the identity of type above, for f ∈ L<sup>1</sup><sub>loc</sub>(U), not only the means f \* k<sub>ε</sub> → f in L<sup>1</sup><sub>loc</sub>(U), but in fact we will see later that f \* k<sub>ε</sub> → f pointwise a.e. (Lebesgue theorem)

# T.i.p's from $L^1(G)$

- ► The general form of a t.i.o.  $T : L^1(\mathbf{R}^d) \to \mathbf{L}^1(\mathbf{R}^d)$  is convolution with a finite complex Borel measure  $d\mu$ .
- Proof: Given such *T*, the idea is of course that *dµ* should be *T*(δ<sub>0</sub>), we replace δ<sub>0</sub> by an approximation of the identity *k<sub>ε</sub>*. Since they are bounded in *L*<sup>1</sup>, *T*(*k<sub>ε</sub>*) will be also bounded in *L*<sup>1</sup>. By the Banach-Alaoglu theorem there exists a finite complex valued measure *dµ* and a sequence ε<sub>n</sub> → 0 such that

$$\lim_n \int g(y)T(k_{\varepsilon_n})(y)dy = \int g(y)d\mu(y), g \in C_c.$$

Now, since  $g = \lim_{n \to \infty} g * k_{\varepsilon_n}$  and T is t.i.o. one has  $Tg = \lim_{n \to \infty} g * T(k_{\varepsilon_n})$ . But

$$(g*Tk_{\varepsilon_n})(x) = \int g(x-y)T(k_{\varepsilon_n})(y)dy = \int g(x-y)d\mu(y) = (g*\mu)d\mu(y)$$

Hence T is convolution with µ on all functions with compact support and hence on all functions.

## Second lecture: Fourier analysis in the torus

- The Fourier series of a periodic function.
- The Dirichlet, Fejer and Poisson means.
- Convergence in norm.
- Pointwise convergence.
- The rotation invariant operators in  $L^1(T)$  and  $L^2(T)$ .
- ► The Fourier transform in **T<sup>d</sup>**

## The Fourier series of a periodic function.

Assume that the period is 1, we deal with functions on T, parametrized by e<sup>2πit</sup>.

$$(f*g)(t)=\int_{|t|\leq \frac{1}{2}}f(t-x)g(x)dx.$$

► Elementary blocks:  $e_n(x) = e^{i2\pi nt}$ ,  $n \in \mathbb{Z}$ . The expression  $\sum_n \langle f, e_n \rangle e_n$  is usually written

$$\sum_n c_n(f) e^{2\pi i n t},$$

with  $c_n(f) = \int_0^1 f(t) e^{-2\pi i n t} dt, f \in L^1(\mathbf{T}).$ 

 c<sub>n</sub>(f) is called the n-th Fourier coefficient of f and the formal series

$$S(f) = \sum_{n \in \mathbf{Z}} c_n(f) e^{2\pi i n x},$$

is called the *Fourier series* of f. Question: in what sense f = S(f)?

## The Fourier basis

The e<sub>n</sub> constitute an orthonormal basis of L<sup>2</sup>(T): pairwise orthogonal,

$$\langle e_n, e_m \rangle = \int_0^1 e^{2\pi i (n-m)t} dt = 0$$

and their finite linear combinations are dense (Weierstrass theorem).

- ► This can be restated by saying that the map f → (c<sub>n</sub>(f))<sub>n</sub> is a bijection from L<sup>2</sup>(T) to l<sup>2</sup>(Z) satisfying
- $f(x) = \sum_{n} c_n(f) e^{2\pi i n x}$  in  $L^2(\mathbf{T})$
- $f(x) = \sum_{n} c_n e^{2\pi i n x}, (c_n) \in l^2(\mathbf{Z})$ , general expression.
- Plancherel's identity

$$\sum_{n} |c_{n}(f)|^{2} = \int_{0}^{1} |f(t)|^{2} dt,$$

polarized version Parseval's relation

$$\sum_{n} c_n(f) \overline{c_n(g)} = \int_0^1 f(t) \overline{g(t)} \, dt.$$

## Properties of Fourier coefficients

• 
$$c_n(f * g) = c_n(f)c_n(g)$$
.

• 
$$c_n(\tau_x f) = e^{-2\pi i n x} c_n(f).$$

- If f is of class  $C^k$  and  $2\pi$  periodic, then  $c_n(f^{(k)}) = (2\pi i n)^k c_n(f)$  and  $c_n(f) = o(|n|^{-k})$ .
- ► (The Riemann-Lebesgue lemma).  $|c_n(f)| \le ||f||_1$  and  $c_n(f) \to 0$  as  $|n| \to \infty$ .
- Proof: from the second it follows that

$$c_n(f-\tau_x f) = (1-e^{-2\pi i n x}c_n(f))$$

Choose  $x = \frac{1}{2n}$ :  $2|c_n(f)| \le ||f - \tau_{2/n}||_1$ , so the result is a consequence of the continuity of translations.

 Nothing more general can be said regarding the speed of convergence.

#### The Dirichlet kernel

▶ To study *S*(*f*) it is natural to consider the partial sums

$$S_N(f)(x) = \sum_{-N}^{N} c_n(f) e^{2\pi i n x} =$$
  
=  $\int_0^1 f(t) \sum_{-N}^{N} e^{2\pi i n (x-t)} dx = (f * D_N)(x),$   
 $D_N(x) = \sum_{n=-N}^{N} e^{2\pi i n t} = \frac{\sin(2N+1)\pi x}{\sin \pi x}.$ 

- ► (D<sub>N</sub>) is the Dirichlet kernel. It is NOT an approximation of the identity because ||D<sub>N</sub>|| behaves like log N.
- However, we know  $S_N f \to f$  in  $L^2$  if  $f \in L^2$ .

The Fejer kernel

D

• 
$$\sigma_N(f) = \frac{1}{N+1}(S_0(f) + \dots + S_N(f)) = (f * \sigma_N),$$
  
 $\sigma_N(x) = \frac{1}{N+1}(D_0(x) + \dots + D_N(x)) = \sum_{j=-N}^N \left(1 - \frac{|j|}{N+1}\right) e^{2\pi i n x}$   
 $= \frac{1}{N+1} \left(\frac{\sin(N+1)\pi x}{\sin \pi x}\right)^2$ 

- $\sigma_N$  is positive, has integral one and if  $|x| > \delta$  then  $|\sigma_N(x)| \le c_\delta \frac{1}{N}$ , so it is an approximation of the identity.
- ▶ If  $f \in L^p(\mathbf{T})$ ,  $\mathbf{p} < +\infty$ . then  $\sigma_N(f) \to f$  in  $L^p(\mathbf{T})$ .
- If f is continuous at  $t_0$ , then  $\sigma_N(f)(t_0) \rightarrow f(t_0)$ .
- ▶ If f is continuous then  $\sigma_N(f) \rightarrow f$  uniformly (Weierstrass thm)
- Uniqueness theorem: If  $c_n(f) = 0$  for all *n* then f = 0.
- If f is continuous at x₀ and S(f)(x₀) converges, sum must be f(t₀)

## The Poisson kernel

- ▶ Dirichlet problem in the unit disc **D**, that is, given  $f \in C(\mathbf{T})$  to find u s.t.  $\Delta u = 0, u \in C(\overline{D}), u = f$  on T.
- We solve this problem exploiting its invariance by rotations.
- For each 0 < r < 1 we pose u<sub>r</sub>(t) = u(re<sup>2πit</sup>); the operator f → u<sub>r</sub> is rotation invariant (because Δ is) hence it must be given by a circular convolution with some P<sub>r</sub>, u<sub>r</sub> = f \* P<sub>r</sub>,
- ▶ and must diagonalize in the Fourier basis, i.e.  $c_n(u_r) = m_n c_n(f), m_n = c_n(P_r).$
- ▶ the solution of the Dirichlet problem for  $f(t) = e^{2\pi i n x}$  is  $u(re^{2\pi i t}) = z^n$  if *n* is positive and  $\overline{z}^n$  if *n* is negative,  $z = re^{2\pi i t}$ , so  $m_n = r^{|n|}$ .

Since

$$P_r(x) = \sum_n r^{|n|} e^{2\pi i n x} = \frac{1 - r^2}{|1 - r e^{2\pi i x}|^2} = \frac{1 - r^2}{1 + r^2 - 2r \cos(2\pi x)},$$

we guess that the solution should be
• 
$$u(re^{2\pi it}) = (f * P_r)(t) = \int_0^1 f(x) \frac{1-r^2}{1+r^2-2r\cos(2\pi(t-x))} dx.$$

▶ The kernel  $P_r$  is called the *Poisson kernel*. It is positive with integral one; if  $|t| > \delta$ , then  $|1 - re^{2\pi i t}| \ge c - \delta$ , whence

$$P_r(t) \leq c_\delta(1-r^2).$$

 $-(P_r)$  is an approximation of the identity as  $r \rightarrow 1$ .

For f ∈ L<sup>1</sup>(T), the function u defined on the unit disc by () above is an harmonic function in D satisfying u<sub>r</sub> → f in L<sup>1</sup>(T). In case f ∈ C(T), u is continuous in the closed disc with boundary values equal to f and is thus the solution of Dirichlet's problem.

#### Pointwise convergence

- Pointwise convergence of the Fourier series of f: when  $f(x) = \sum_{n} c_n(f)e^{2\pi i n x}$  a.e. or at a given point?
- ▶ Using sumability "a la Fejer" o " a la Poisson" the situation is quite good. Indeed, as both the Fejer and Poisson kernels are approximate identities one can prove that for  $f \in L^1(\mathbf{T})$  both  $F_N(f)(t)$  and  $u_r(t)$  have limit f(t) a.e. We will see this later as an application of the maximal function of Hardy-Littlewood.
- ► The a.e. pointwise convergence of S<sub>N</sub>(f)(x) to f(x) is a extremely hard question.
- ► Kolmogorov constructed an f ∈ L<sup>1</sup>(T) such that S(f) diverges a.e.

- The poinwise convergence of S(f) for f ∈ L<sup>p</sup>(T) was a very hard open problem in Fourier analysis till Carleson proved that S(f)(t) converges to f(t) for a.e. t for f ∈ L<sup>2</sup>(T) in a celebrated breakthrough, and this was generalized to L<sup>p</sup>(T), 1
- ► Convergence of S(f) at a point x<sub>0</sub> where f is continuous is not guaranteed. But if the modulus of continuity of f at x<sub>0</sub> satisfies a Dini type condition then S(f)(x<sub>0</sub>) converges to f(x<sub>0</sub>).
- In particular this is the case if f satisfies a Lipschitz condition or if it is differentiable at x<sub>0</sub>.

### Convergence in norm

- ▶ Regarding convergence in  $L^{p}(\mathbf{T}), \mathbf{1} \leq \mathbf{p} < +\infty$ , we have seen that  $\sigma_{N}(f)$  and  $u_{r}$  have limit f in  $L^{p}(\mathbf{T})$  while we trivially know that  $S_{N}(f) \rightarrow f$  in  $L^{2}(\mathbf{T})$  if  $f \in L^{2}(\mathbf{T})$ .
- We will see later, as an application of the CZ theory, that this holds true for 1
- Uniform convergence of S(f) when f is continuous.
- ► du Bois-Reymond constructed a continuous f such that S(f) diverges at some point (in fact examples can be constructed where S(f) diverges on a dense set).
- Sufficient conditions can be given. For instance, if f is continuous and of bounded variation then S(f) converges to f uniformly.

# Rotation invariant operators in $L^{p}(\mathbf{T})$

For a bounded operator  $\mathcal{T}: \mathit{L^p}(\mathsf{T}) \to \mathsf{L^p}(\mathsf{T}), 1 \leq \mathsf{p}$  , the following are equivalent:

- It commutes with rotations.
- It commutes with convolution with  $L^1(\mathbf{T})$  functions.

▶ It diagonalizes in the Fourier basis:  $c_n(Tf) = m_n c_n(f), n \in \mathbb{Z}$ . Moreover, the general form of T is given

- In case p = 1, by Tf = f \* μ, with a finite complex Borel measure μ, in which case m<sub>n</sub> = c<sub>n</sub>(μ).
- In case p = 2, by c<sub>n</sub>(Tf) = m<sub>n</sub>c<sub>n</sub>(f) with m<sub>n</sub> an arbitrary bounded sequence, in which case the norm of T as an operator in L<sup>2</sup>(T) equals sup<sub>n</sub> |m<sub>n</sub>|.
- In both cases T is convolution with  $g = \sum_n m_m e^{2\pi i n x}$ .
- p = 1: g is a measure, but not able to describe the  $m_n$ .
- p = 2: not able to describe g, describe exactly its coefficients.
- Note that Young inequalities would not prove the result for p = 2 because g ∉ L<sup>1</sup>(T).

## The Fourier transform in $T^d$

▶ If f is a-periodic in **R** the Fourier series becomes

$$f(x) = \sum_{n} c_{n}(f) e^{2\pi i \frac{n}{a}x}, c_{n}(f) = \frac{1}{a} \int_{0}^{a} f(x) e^{-2\pi i \frac{n}{a}x} dx.$$

Frequencies located at the integer multiples of  $\frac{1}{a}$ . The Fourier series of a function on **T**<sup>d</sup> is

$$Sf(t) = \sum_{k \in \mathbf{Z}^{\mathbf{d}}} c_k(f) e^{2\pi i k \cdot t}, k \cdot t = k_1 t_1 + \cdots + k_d t_d,$$

with

$$c_k(f) = \int_0^1 \ldots \int_0^1 f(t) e^{-2\pi i k \cdot t} dt_1 \ldots dt_d.$$

g non trivial periodic function in  $\mathbf{R}^{\mathbf{d}}, \mathbf{d} > 1$ ; its group of periods is a lattice  $\Lambda = A(\mathbf{Z}^{\mathbf{d}}), \mathbf{A} \in \mathbf{GL}(\mathbf{d})$  with fundamental region  $I = A([0, 1]^n)$ .

If f(t) = g(At), f is **Z**<sup>d</sup> periodic and has a Fourier series expansion Rewriting it in terms of g one obtains, with

$$\Lambda^* = (A^*)^{-1}(\mathsf{Z}^\mathsf{d})$$

being the dual lattice

$$g(t) = \sum_{
ho \in \Lambda^*} c_
ho(g) e^{2\pi i 
ho \cdot t},$$

where

$$c_{
ho} = rac{1}{|detA|} \int_{I} g(t) e^{-2\pi i 
ho \cdot t} dt.$$

The frequencies are then located at  $\Lambda^*$ .

- Much of the analysis done in the previous section goes over to N > 1, provided that appropriate definitions are given, namely that of S<sub>N</sub>f(t).
- If rectangulars sums are used, that is,

$$S_N^r(f)(t) = \sum_{|k_i| \leq N} c_k(f) e^{2\pi i k \cdot t},$$

and correspondingly for  $\sigma_N(f)$ , then the results for  $S_N(f)$  and  $\sigma_N(f)$  hold as well.

However, if spherical sums are considered

$$S_N^e(f)(t) = \sum_{|k| \le N} c_k(f) e^{2\pi i k \cdot t}, |k|^2 = k_1^2 + \cdots + k_d^2,$$

then the situation becomes more complicated.

# Third lecture: Fourier analysis in R<sup>d</sup>

- ► The Fourier transform in L<sup>1</sup>(R<sup>d</sup>), uniqueness theorem, the inversion formula
- The Fourier transform in  $L^2(\mathbf{R}^d)$ .
- Translation invariant operators in L<sup>1</sup>(R<sup>d</sup>) and L<sup>2</sup>(R<sup>d</sup>).

# The Fourier transform in $L^1(\mathbf{R}^d)$

$$\hat{f}(\xi) = \langle f, e_{\xi} \rangle = \int_{\mathbf{R}^{\mathbf{d}}} f(x) e^{-2\pi i \xi \cdot x} dx, \xi \in \mathbf{R}^{\mathbf{d}}, \mathbf{f} \in \mathbf{L}^{1}(\mathbf{R}^{\mathbf{d}})$$
  
 $\hat{\mu}(\xi) = \int_{\mathbf{R}^{\mathbf{d}}} e^{-2\pi i \xi \cdot x} dx, \mu$ measure.

• 
$$\widehat{\tau_x f}(\xi) = e^{-2\pi i \xi \cdot x} \widehat{f}(\xi)$$

• If 
$$g(x) = e^{2\pi i \eta \cdot x} f(x)$$
, then  $\hat{g}(\xi) = \tau_{\eta}(\xi)$ .

• 
$$\widehat{D_{\lambda}f}(\xi) = \lambda^{-d}\widehat{f}(\frac{\xi}{\lambda}).$$

• 
$$\widehat{D^{\alpha}f}(\xi) = (2\pi i\xi)^{\alpha}\widehat{f}(\xi).$$

$$\blacktriangleright (D^{\alpha}\hat{f})(\xi) = ((-2\pi i x)^{\alpha} f(x))(\xi).$$

$$\blacktriangleright \ \widehat{f \ast g} = \widehat{f}\widehat{g}.$$

• If A is an invertible matrix and  $f_A(x) = f(Ax)$ , then

$$\widehat{f}_{\mathcal{A}}(\xi) = rac{1}{|det\mathcal{A}|}\widehat{f}(\mathcal{A}^{-1})^*\xi).$$

• (The Riemann-Lebesgue lemma).  $\hat{f}$  is a continuous function vanishing at  $\infty$ .

- Fourier transform commutes with composition with orthogonal matrices A.
- f(x) is radial  $\implies \hat{f}$  radial.
- f,g radial  $\implies f * g$  radial.
- P(D) = ∑<sub>α∈N<sup>d</sup></sub> c<sub>α</sub>D<sup>α</sup> is a differential operator with constant coefficients (and so translation invariant)

$$\widehat{P(D)f}(\xi) = P(2\pi i\xi)\widehat{f}(\xi), (P(D)\widehat{f})(\xi) = (P(-2\pi i x)\widehat{f})(\xi),$$

A translation- invariant operator T has a multiplier, for instance that of P(D) is m(ξ) = P(2πiξ). We say that T is invariant by rigid motions if moreover T(f<sub>A</sub>) = (Tf)<sub>A</sub> for all orthogonal matrices. Then, its multiplier must be radial. For instance, the Laplace operator

$$\Delta = \frac{\partial^2}{\partial x_1^2} + \dots + \frac{\partial^2}{\partial x_d^2},$$

is radial and has multiplier  $m(\xi) = -4\pi^2 |\xi|^2$ .

- If a differential operator P(D) is invariant by rigid motions, then its multiplier is a radial polynomial, that is a polynomial in |ξ|<sup>2</sup>, and hence we have
- A differential operator P(D) is invariant by rigid motions if and only if it is a polynomial in Δ.

# The Dirichlet, Fejer and Poisson kernels in R<sup>d</sup>

$$f = \int_{\mathbf{R}^{\mathbf{d}}} \langle f, e_{\xi} \rangle e_{\xi} d\xi, f(x) = \int_{\mathbf{R}^{\mathbf{d}}} \hat{f}(\xi) e^{2\pi i x \cdot \xi} d\xi,$$

Dirichlet means with cubes or balls. Quite different behavior.

$$(S_R^c f)(x) = \int_{|\xi_i| \le R} \hat{f}(\xi) e^{2\pi i x \cdot \xi} d\xi$$
$$(S_R^b f)(x) = \int_{|\xi| \le R} \hat{f}(\xi) e^{2\pi i x \cdot \xi} d\xi$$

$$(S_R^c f)(x) = (f * D_R)(x), D_R(x) = \prod_{j=1}^d \frac{\sin 2\pi R x_j}{\pi x_j}.$$

 D<sub>R</sub> is strictly speaking not integrable ( a typical example of a conditionally convergent integral) and is NOT an approximation of the identity. But their means are an approximation of the identity

$$(\sigma_R f)(x) = \frac{1}{R} \int_0^R (S_r^c f)(x) dr = (f * F_R)(x),$$

 $F_R(x)=R^dF(Rx),$ 

$$F(x) = \prod_{i=1}^{d} \frac{1 - \cos 2\pi x_j}{2\pi^2 x_j^2}.$$

F has integral one and hence  $F_R$  is an approximation of the identity.

### Poisson and Gauss means

• The general scheme: continuous integrable function  $\Phi, \Phi(0) = 1$ 

$$f_{\Phi}(\varepsilon, x) = \int_{\mathbf{R}^{\mathbf{d}}} \hat{f}(\xi) e^{2\pi i x \cdot \xi} \Phi(\varepsilon \xi) d\xi.$$

Fubini's theorem implies that

$$\int_{\mathbf{R}^{\mathbf{d}}} \hat{f}(\xi)g(\xi)d\xi = \int_{\mathbf{R}^{\mathbf{d}}} f(y)\hat{g}(y)dy, f,g \in L^{1}(\mathbf{R}^{\mathbf{d}}).$$

The Fourier transform of Φ(εξ) is (ε)<sup>-d</sup>Φ̂(<sup>y</sup>/<sub>ε</sub>) = Φ̂<sub>ε</sub>(y), whence the Fourier transform of e<sup>2πix·ξ</sup>Φ(εξ) is Φ̂<sub>ε</sub>(y − x) and so

$$f_{\Phi}(\varepsilon, x) = (f * \widehat{\Phi}_{\varepsilon})(x).$$

• Choose  $\Phi$  so that  $\int \widehat{\Phi} = 1 \rightarrow$  approximation of the identity.

# Heath diffusion

- Choose  $\Phi(x) = e^{-\pi |x|^2}$ ,  $\widehat{\Phi}(\xi) = e^{-\pi |\xi|^2}$ ,  $\widehat{\Phi} = \Phi$ .  $f_{\Phi}(\varepsilon, x) = \int_{\mathbf{R}^d} \widehat{f}(\xi) e^{-\pi \varepsilon^2 |\xi|^2} e^{2\pi i x \cdot \xi} d\xi = (f * \Phi_{\varepsilon})(x)$ ,
- ▶ But  $\int_{\mathbf{R}^{\mathbf{d}}} \Phi(x) dx = \widehat{\Phi}(0) = \Phi(0) = 1$ , therefore  $\Phi_{\varepsilon}$  is an approximation of the identity so  $f_{\phi}(\varepsilon, x) \to f(x)$  in  $L^{1}(\mathbf{R}^{\mathbf{d}})$ .
- Unicity theorem: if  $\hat{f} = 0$ , then f = 0. It also implies
- ▶ Inversion theorem: If  $f \in L^1(\mathbf{R}^d)$  and  $f \in L^1(\mathbf{R}^d)$  then

$$f(x) = \int_{\mathbf{R}^d} \hat{f}(\xi) e^{2\pi i x \cdot \xi} \, d\xi, \, a.e. x$$

and in particular f is a.e. equal to a continuous function vanishing at infinity.

- If we put  $\mathcal{F}$  for the Fourier transform, this means  $\mathcal{F}^{-1}f(x) = \mathcal{F}f(-x)$ , that we call the *Fourier cotransform*.
- ► Connection with heath diffusion: u(t,x) = f<sub>φ</sub>(√t,x) is the solution of the heath equation

$$\frac{\partial u}{\partial t}=\frac{1}{4}\Delta_{x}u(x,t),u(0,x)=f(x).$$

#### Harmonic extension

- More generally, choose any continuous function  $\Phi \in L^1$  such that  $\Phi(0) = 1$  and  $\widehat{\Phi}$  is integrable. Then by the above the integral of  $\widehat{\Phi}$  equals  $\Phi(0) = 1$  and we can repeat the same argument.
- Another choice is  $\Phi(x) = e^{-2\pi|x|}$  (Abel means). In this case

$$\widehat{\Phi}(\xi) = c_d rac{1}{(1+|\xi|^2)^{(d+1)/2}}, c_d = rac{\Gamma[rac{d+1}{2}]}{\pi^{(d+1)/2}}.$$

• In this case  $u(t,x) = f_{\phi}(t,x)$  satisfies

$$\frac{\partial^2 u}{\partial t^2} + \Delta_x u(t, x) = 0, u(0, x) = f(x),$$

that is, is the solution of the Dirichlet problem in the half-space.

# The Fourier transform in $L^2(\mathbf{R}^d)$

Schwarz class  $S(\mathbf{R}^{\mathbf{d}})$  of  $C^{\infty}$  functions f such that

$$\lim_{|x|\to+\infty}|x^{\beta}D^{\alpha}f(x)|=0,\alpha,\beta\in\mathsf{N}^{\mathsf{d}}.$$

Dense in all  $L^p$  spaces,  $1 \le p < +\infty$ , contains  $C_c^{\infty}(\mathbf{R}^d)$ .

- ► The Fourier transform is a bijection from S(R<sup>d</sup>) to itself that transforms convolutions into multiplication and conversely.
- Applying  $\int f\hat{g} = \int \hat{f}g$  to  $f \in S$ , we find

$$||f||_2 = ||\hat{f}||_2, f \in \mathcal{S}$$

Thus we have that the Fourier transform is an isometry between S and itself, so extends to an isometry of the whole of L<sup>2</sup>,

$$\hat{f}(\xi) = \lim_{R \to +\infty} \int_{|x| \le R} f(x) e^{-2\pi i \xi \cdot x} dx,$$
  
exists in  $L^2(\mathbf{R}^d)$ , defines  $\hat{f}$ , and  
 $\|\hat{f}\|_2 = \|f\|_2$ , *Plancherel'sidentity*

# A miracle?

$$f=\int_{\mathbf{R}^{\mathbf{d}}}\langle f,e_{\xi}\rangle e_{\xi}d\xi.$$

- The e<sub>ξ</sub> ∉ L<sup>2</sup>(R<sup>d</sup>) yet they behave as if they were an orthonormal basis of L<sup>2</sup>(R<sup>d</sup>). True bases: the wavelet bases.
- Kernel K(x, ξ) = e<sup>2πix·ξ</sup> of modulus one; ensures L<sup>1</sup>(R<sup>d</sup>) to L<sup>∞</sup>(R<sup>d</sup>), but its boundedness in L<sup>2</sup> depends on much more than size, depends on cancelations.

$$\int_{\mathbf{R}^{\mathsf{d}}} |\hat{f}(\xi)|^2 d\xi = \int_{\mathbf{R}^{\mathsf{d}}} \int_{\mathbf{R}^{\mathsf{d}}} \int_{\mathbf{R}^{\mathsf{d}}} f(x) \overline{f(y)} e^{2\pi i \xi(y-x)} dx dy d\xi.$$

• This being equal to  $\int_{\mathbf{R}^d} |f(x)|^2 dx$  means formally that

$$\int_{\mathbf{R}^{\mathbf{d}}} e^{2\pi i \xi x} \, d\xi = \delta_0(x).$$

 The above says that superposition of all frequencies is zero outside zero.

## Translation invariant operators in $L^{p}(\mathbf{R}^{d})$

- ▶ For a bounded operator  $T : L^p(\mathbf{R}^d) \to \mathbf{L}^p(\mathbf{R}^d), \mathbf{p} = \mathbf{1}, \mathbf{2}$ , the following are equivalent:
  - 1. It commutes with translations.
  - 2. It commutes with convolution with  $L^1(\mathbf{R}^d)$  functions.
  - 3. It diagonalizes in the Fourier basis:  $\widehat{Tf}(\xi) = m(\xi)\widehat{f}(\xi)$ .
- Moreover, the general form of T is given by
  - 1. in case p = 1,  $Tf = f * \mu$ , with a finite complex Borel measure  $\mu$ , in which case  $m(\xi) = \hat{\mu}(\xi)$ .
  - 2. in case p = 2,  $\widehat{Tf}(\xi) = m(\xi)\widehat{f}(\xi)$  with *m* an arbitrary bounded function.
- The t.i.p on S(R<sup>d</sup>), by Fourier transform correspond to multiplication operators acting on S(R<sup>d</sup>), Tf = mf, with m a C<sup>∞</sup>(R<sup>d</sup>) of *slow growth* meaning that for every α ∈ N<sup>d</sup> there exists k ∈ N such that |D<sup>alpha</sup>m(x) = O(|x|<sup>k</sup>).
- ▶ Do not know exactly *m* when *p* = 1, we do not know exactly what is

$$\int_{\mathbf{R}^{\mathbf{d}}} m(\xi) e^{2\pi i x \cdot \xi} d\xi, m \in L^{\infty}(\mathbf{R}^{\mathbf{d}}).$$

# Translation invariant subspaces of $L^2(\mathbf{R}^d)$

- ► The last result serves to describe all closed translations invariant subspaces E of L<sup>2</sup>(R<sup>d</sup>).
- Associate to E the projection operator P onto E, that is, Pf ∈ E and f − Pf is orthogonal to E, P<sup>2</sup> = P.
- If E is invariant by translations so is P, hence it has a bounded multiplier m ∈ L<sup>∞</sup>(R<sup>d</sup>).
- Now,  $P^2 = P$  translates to  $m^2 = m$ , whence m = 0 or m = 1.
- Let A be the set where m = 0. A given  $f \in E$  if and only if Pf = f, that is  $m\hat{f} = \hat{f}$ , whence it follows that  $\hat{f} \in E$  if and only if  $\hat{f}$  vanishes a.e. on A.
- ▶ This is the general form of a closed translation invariant subspace in  $L^2(\mathbf{R}^d)$ . In particular, the translates of a a given function  $f \in L^2(\mathbf{R}^d)$  span the whole of  $L^2(\mathbf{R}^d)$  if and only if  $\hat{f} \neq 0$  a.e. (Beurling's theorem)

# Fourth lecture: Distributions in Harmonic Analysis

- The notion of distribution. Operations with distributions.
- Convergence of distributions
- Distributions with compact support and tempered distributions.
- Fourier transform of tempered distributions.
- Convolution of distributions
- Translation invariant operators in test spaces and in spaces of distributions.
- Fundamental solutions of linear constant coefficient PDE's.
- Poisson's summation formula. An unified language

# What is a distribution in an open set $U \subset \mathbf{R}^{d}$ ?

- Basic idea is to consider that functions f are not given by their values at points but by their action on other functions by integration.
- ▶  $\mathcal{D}(\mathbf{U})$  dense in all  $L^{p}(U)$  spaces. Hence, if  $f, g \in L^{1}_{loc}(U)$

$$\int_U f(x)\varphi(x)dx = \int_U g(x)\varphi(x)dx, \forall \varphi \in \mathcal{D}(\mathbf{U}) \implies \mathbf{f} = \mathbf{g} \ \mathbf{a.e.}$$

This means that f is completely known as soon as one knows

$$u_f(\varphi) = \int_U f(x)\varphi(x)\,dx,$$

- A distribution on U is a continuous linear map  $u : \mathcal{D}(\mathbf{U}) \to \mathbf{C}$ .
- Continuity: if φ<sub>n</sub> ∈ tends to zero (meaning that they have their supports in a fixed compact set K of U and D<sup>α</sup>(φ<sub>n</sub>) → 0 uniformly in K for all α), then u(φ<sub>n</sub>) → 0.
- It is customary to write u(φ) = ⟨u, φ⟩. The space of distributions on U is denoted D'(U)

# Examples

- Functions  $f \in L^1_{loc}$  are distributions.
- A locally finite measure  $d\nu$  on U is also a distribution.
- The Dirac measure at a will be denoted  $\delta_a$ .
- If  $\Lambda$  is a discrete set in U (hence countable), the comb

$$\sum_{\mathbf{a}\in\Lambda}\delta_{\mathbf{a}},$$

is also a distribution.

• Example of a distribution that is not a function nor a measure.

$$\langle p.v.\frac{1}{x}, \varphi \rangle = \lim_{\varepsilon \to 0} \int_{|x| > \varepsilon} \frac{\varphi(x)}{x} dx.$$

Note that the limit exists because it equals

$$\lim_{\varepsilon\to 0}\int_{\varepsilon}^{\infty}\frac{\varphi(x)-\varphi(-x)}{x}\,dx.$$

#### Operations with distributions

- When defining an operation on distributions we look for consistency
- Definition of  $\tau_x u$  should be so that  $\tau_x u_f = u_{\tau_x f}$  for  $f \in L^1_{loc}$ .

$$\int_{\mathbf{R}^{\mathbf{d}}} \tau_{x} f(y) \varphi(y) dy = \int_{\mathbf{R}^{\mathbf{d}}} f(y-x) \varphi(y) dy =$$
$$= \int_{\mathbf{R}^{\mathbf{d}}} f(z) \varphi(z+x) dz = \int_{\mathbf{R}^{\mathbf{d}}} f(z) \tau_{-x} \varphi(z) dz,$$

Must define

$$\langle \tau_{\mathbf{x}} \mathbf{u}, \varphi \rangle = \langle \mathbf{u}, \tau_{-\mathbf{x}} \varphi \rangle.$$

- u ∈ D'(R<sup>d</sup>) a- periodic if τ<sub>a</sub>u = u. All a-periodic functions are, and also the Dirac comb Δ<sub>a</sub> = Σ<sub>n∈Z</sub> δ<sub>na</sub>.
- ▶ Product of  $u \in \mathcal{D}'(\mathcal{U})$  with  $g \in C^{\infty}(U)$ :  $\langle gu, \varphi \rangle = \langle u, g\varphi \rangle$ .  $g\delta_a = g(a)\delta_a, g\Delta_a = \sum_n g(na)\delta_{na}, x v.p.\frac{1}{x} = 1.$

#### Derivatives of distributions

- Derivative D<sup>α</sup>u : ⟨D<sup>α</sup>u, φ⟩ = (-1)<sup>|α|</sup>⟨u, D<sup>α</sup>φ⟩.
   In R, ∫ f'φ = -∫ f(φ)' holds for all locally absolutely continuous functions ( undefinite integrals of integrable functions), so that (u<sub>f</sub>)' = u<sub>f'</sub> for those.
- Unit step of Heaviside function *H*, 1 for positive *x* and zero for negative *x*. Then *H*' = δ<sub>0</sub> because:

$$\langle H', \varphi \rangle = - \langle H, \varphi' \rangle = - \int_0^\infty \varphi'(x) dx = \varphi(0),$$

- A function f which is continuously differentiable in the closed intervals determined by some points a<sub>1</sub>,..., a<sub>N</sub> where it has some jump discontinuities with jumps s<sub>i</sub>. Then (u<sub>f</sub>)' = u<sub>f'</sub> + ∑<sub>i</sub> s<sub>i</sub>δ<sub>a<sub>i</sub></sub>.
- The a- periodic function which in each interval [na, (n + 1)a] is linear from 0 to 1 has derivative <sup>1</sup>/<sub>a</sub> − Δ<sub>a</sub>.

• Derivative of log |x| is  $p.v.\frac{1}{x}$ .

$$-\int_{\mathbf{R}} \log |x| \varphi'(x) \, dx = -\lim_{\varepsilon} \left( \int_{-\infty}^{-\varepsilon} + \int_{\varepsilon}^{+\infty} \right) \log |x| \varphi'(x) \, dx$$
$$\lim_{\varepsilon} (\varphi(\varepsilon) - \varphi(-\varepsilon)) \log \varepsilon + \lim_{\varepsilon} \int_{|x| > \varepsilon} \frac{\varphi(x)}{x} \, dx,$$

One can prove, in **R**, that if u' = 0 then u is constant and that every distribution has a primitive.

# Convergence of distributions

- $u_n \to u$  means simply  $\langle u_n, \varphi \rangle \to 0$  for all  $\varphi$ .
- With this definition all operations are continuous, in particular the differentiation.
- In particular we can consider series of distributions. We will be interested in trigonometric series

$$\sum_{n\in\mathbf{Z}}c_ne^{2\pi i\frac{n}{a}x}.$$

Partial sums act as

$$\langle \sum_{n=-N}^{N} c_n e^{2\pi i \frac{n}{a} x}, \varphi \rangle = \sum_{n=-N}^{N} c_n \hat{\varphi}(-\frac{n}{a}).$$

 $\hat{\varphi} \in \mathcal{S}(\mathsf{R}^{\mathsf{d}}), \ \hat{\varphi}(-\frac{n}{a}) = O(|n|^{-k}) \text{ for all } k.$ 

If c<sub>n</sub> = O(|n|<sup>k</sup>) for some k then the series indeed defines a distribution. This is not necessarily the Fourier series of a periodic function.

# Distributions with compact support

- A distribution with compact support is a continuous linear map T : C<sup>∞</sup>(R<sup>d</sup>) → C
- Continuity means here that if φ<sub>n</sub> ∈ C<sup>∞</sup>(R<sup>d</sup>) tend to zero (meaning that D<sup>α</sup>φ<sub>n</sub>(x) → 0 uniformly on compacts) then ⟨T, φ<sub>n</sub>⟩ → 0.
- ► Again, we may think that T has compact support if it is capable to act against all C<sup>∞</sup>(R<sup>d</sup>) functions. The space of distributions with compact support is denoted E'(R<sup>d</sup>)

► Consider the *a*- periodic function *f* equal to <sup>x</sup>/<sub>a</sub> in [0, *a*]. By direct computation

$$f(x) = \frac{1}{2} + \frac{i}{2\pi} \sum_{n \neq 0} \frac{1}{n} e^{2\pi i \frac{n}{a} x}.$$

• Convergent in  $L^2(\mathbf{T}) \implies$  convergent as distributions,

$$f'(x) = -\frac{1}{a} \sum_{n \neq 0} e^{2\pi i \frac{n}{a} x}.$$

• Shaw before that  $f' = \frac{1}{a} - \Delta_a$ , so

$$\Delta_{a} = \sum_{n \in \mathbf{Z}} \delta_{na} = \frac{1}{a} \sum_{n \in \mathbf{Z}} e^{2\pi i \frac{n}{a} x}$$

# Tempered distributions

- Would like to define the Fourier transform of a distribution.
- ► For  $f \in L^1(\mathbf{R}^d)$ ,  $\int_{\mathbf{R}^d} \hat{\mathbf{f}}(\mathbf{x}) \varphi(\mathbf{x}) d\mathbf{x} = \int_{\mathbf{R}^d} \mathbf{f}(\mathbf{x}) \hat{\varphi}(\mathbf{x}) d\mathbf{x}$ , so should define  $\langle \hat{u}, \varphi \rangle = \langle u, \hat{\varphi} \rangle$ .
- ▶ Problem is that \$\hftilde{\varphi}\$ is no longer in \$\mathcal{D}(\mathbf{R}^d)\$. Must restrict to a particular class of distributions. The Schwarz space is invariant by the Fourier transform, so the above would work if \$\mathcal{S}(\mathbf{R}^d)\$ were used instead of \$\mathcal{D}(\mathbf{R}^d)\$
- A tempered distribution is a continuous linear map *u* : S(R<sup>d</sup>) → C
- Continuity means:  $\varphi_n \to 0$  in  $\mathcal{S}(\mathbf{R}^d)$  (meaning that  $\sup_x |x|^{|\beta|} |D^{\alpha} \varphi_n(x)| \to 0$  as  $n \to +\infty$  for all  $\alpha, \beta \in \mathbf{N}^d$ ) then  $\langle u, \varphi_n \rangle \to 0$ .
- ► The restriction of u to D(R<sup>d</sup>) is then a distribution (and in fact u is completely determined by this restriction since D(R<sup>d</sup>) is dense in S(R<sup>d</sup>)).

## Examples

- Tempered distributions as those capable to act on S(R<sup>d</sup>). Denote by S'(R<sup>d</sup>) the space of tempered distributions.
- ► All distributions with compact support are in S'(R<sup>d</sup>).
- Among the  $f \in L^1_{loc}$ , those with slow growth, meaning that  $|f(x)| = O(|x|^k)$  for some integer k are in  $\mathcal{S}'(\mathbf{R}^d)$ .
- All  $L^p$ -functions,  $1 \le p \le +\infty$  are as well.
- All  $L^1_{loc}$  periodic functions are in  $S'(\mathbf{R}^d)$ .
- Easy to see that gu ∈ S'(R<sup>d</sup>) if u ∈ S'(R<sup>d</sup>) and g ∈ C<sup>∞</sup>(R<sup>d</sup>) and its derivatives have slow growth, that is, for all α ∈ N<sup>d</sup>, |D<sup>α</sup>g(x)| = O(|x|<sup>k</sup>) for some k because in this case gφ ∈ S(R<sup>d</sup>) for all φ ∈ S(R<sup>d</sup>).
- We denote by  $\mathcal{B}(\mathbf{R}^{\mathbf{d}})$  the class of these g

# Fourier transform of tempered distributions

- ► The Fourier transform T̂ of a tempered distribution is thus defined by ⟨û, φ⟩ = ⟨u, φ̂⟩.
- ► Since the Fourier transform in S(R<sup>d</sup>) is an isomorphism the same happens with S'(R<sup>d</sup>).
- Properties of the Fourier transform regarding translations vs multiplication by exponentials and derivatives vs multiplication by polynomials go over to S'(R<sup>d</sup>).

# Examples

• 
$$\hat{\delta}_a(\xi) = -e^{2\pi i a\xi}, e^{2\pi i a \chi} = \delta_a$$
. In particular,  $\hat{\delta}_0 = 1, \hat{1} = \delta_0$ .

• In particular 
$$\hat{\Delta}_a = \sum_n \hat{\delta}_{na} = \sum_n e^{2\pi i n a \xi} = \frac{1}{a} \Delta_{\frac{1}{a}}$$
.

- In particular,  $\Delta_1$  is its own Fourier transform.
- Let us compute the Fourier transform of  $p.v.\frac{1}{x}$ . Its action on  $\varphi$  is

$$\lim_{\varepsilon} \int_{\varepsilon < |xi| < 1/\varepsilon} \frac{\hat{\varphi}(\xi)}{\xi} d\xi =$$
$$\lim_{\varepsilon} \int_{\mathbf{R}} \varphi(x) \left( \int_{\varepsilon < |xi| < 1/\varepsilon} e^{-2\pi i x \xi} \frac{d\xi}{\xi} \right) dx =$$
$$= -i \lim_{\varepsilon} \int_{\mathbf{R}} \varphi(x) \left( \int_{\varepsilon < |xi| < 1/\varepsilon} \sin 2\pi x \xi \frac{d\xi}{\xi} \right) dx =$$

Last inner integral is known to be uniformly bounded in  $\varepsilon, x$ and has limit  $\pi \operatorname{sign}(x)$ , so the Fourier transform of  $p.v.\frac{1}{x}$  is  $-i\pi \operatorname{sign}(\xi)$ . The Fourier transform of a distribution with compact support

- If f ∈ D(R<sup>d</sup>), then f̂ ∈ S(R<sup>d</sup>). In fact something much more precise can be said.
- Note that  $\hat{f}(\xi)$  makes sense for  $z \in \mathbf{C^d}$ ,

$$\hat{f}(z) = \int_{\mathbf{R}^d} f(x) e^{-2\pi i z \cdot x} \, dx.$$

and it is an entire function in  $C^d$  (in particular it cannot have compact support in  $R^d).$ 

*u* ∈ *E*'(**R**<sup>d</sup>), as it is capable to act on *C*<sup>∞</sup>- functions not necessarily with compact support, may consider the entire function

$$h(z) = \langle u_x, e^{-2\pi i z \cdot x} \rangle,$$

which is formally  $\hat{u}(x)$  for  $x \in \mathbf{R}^{\mathbf{d}}$ .

► One can check that the two definitions of û, u ∈ E'(R<sup>d</sup>) agree, that is,

$$\langle u,\hat{\varphi}\rangle = \int_{\mathbf{R}^{\mathbf{d}}} h(x)\varphi(x).$$

- ▶ This means that for  $u \in \mathcal{E}'(\mathbf{R}^d)$ ,  $\hat{u}$  is in fact the restriction to  $\mathbf{R}^d$  of an entire function. Moreover, it is easy to see that  $\hat{u} \in \mathcal{B}(\mathbf{R}^d)$ .
- ► Two Paley-Wiener theorems characterize exactly the class of entire functions that are Fourier transforms of D(R<sup>d</sup>) and E'(R<sup>d</sup>).
## Convolution of a function with a distribution

- Want to define convolutions,  $g * f(x) = \int g(x y)f(y)dy$ .
- ▶ Want to replace *f* by a general distribution *u* we should define

$$(g * u)(x) = \langle u_y, g(x - y) \rangle,$$

- ► This makes sense in three cases, the resulting function being  $\mathcal{D}(\mathsf{R}^d) * \mathcal{D}'(\mathsf{R}^d) \subset \mathsf{C}^{\infty}(\mathsf{R}^d), \mathcal{S}(\mathsf{R}^d) * \mathcal{S}'(\mathsf{R}^d) \subset \mathsf{C}^{\infty}(\mathsf{R}^d)$  $\mathcal{C}^{\infty}(\mathsf{R}^d) * \mathcal{E}'(\mathsf{R}^d) \subset \mathsf{C}^{\infty}(\mathsf{R}^d), \mathcal{D}(\mathsf{R}^d) * \mathcal{E}'(\mathsf{R}^d) \subset \mathcal{D}(\mathsf{R}^d)$
- In fact in the second case,  $\varphi * u \in \mathcal{B}(\mathbf{R}^{\mathbf{d}})$ .
- All rules that make sense hold:
  - 1. Convolution is continuous in both variables.

2. 
$$D^{\alpha}(g * u) = (D^{\alpha}g) * u = g * D^{\alpha}u$$

- 3.  $\widehat{\varphi * u} = \hat{\varphi} \hat{u}, \varphi \in \mathcal{S}(\mathsf{R}^{\mathsf{d}}), \mathsf{u} \in \mathcal{S}'(\mathsf{R}^{\mathsf{d}})$
- 4.  $\widehat{\varphi u} = \hat{\varphi} * \hat{u}, \varphi \in \mathcal{S}(\mathsf{R}^{\mathsf{d}}), \mathsf{u} \in \mathcal{S}'(\mathsf{R}^{\mathsf{d}})$

### Convolution of two distributions

From

$$\langle g * f, \varphi \rangle = \int \int g(x - y) f(y) \varphi(x) dx \, dy =$$
$$= \int (\int g(z) \varphi(y + z) dz) f(y) dy = \int (\int f(y) \varphi(y + z) dy) g(z) dz$$

- ► Should define  $\langle u * v, \varphi \rangle = \langle u_z, \langle v_y, \varphi(y+z) \rangle \rangle$ , or  $\langle u * v, \varphi \rangle = \langle v_y, \langle u_z, \varphi(y+z) \rangle \rangle$ .
- ► To make sense, one of the distributions must have compact support. Fortunately the two definitions agree and defines u \* v ∈ D'(R<sup>d</sup>).
- $\delta * u = u$  for all distributions u,

$$\blacktriangleright D^{\alpha}(u * v) = (D^{\alpha}u) * v = u * D^{\alpha}v.$$

•  $\mathcal{E}'(\mathbf{R}^d) * \mathcal{S}'(\mathbf{R}^d) \subset \mathcal{S}'(\mathbf{R}^d)$  and  $\widehat{u * v} = \hat{u}\hat{v}$ .

### Translation invariant operators in test spaces

- With the language of distributions and tempered distributions one can state a number of representation theorems for continuous operators in spaces of distributions invariant by translations.
- Assume that T : D(R<sup>d</sup>) → C(R<sup>d</sup>) is t.i.o. Then φ → T(φ)(0) is a distribution, and using translation invariance we find that T(φ) = φ \* u for u ∈ D'(R<sup>d</sup>).
- ▶ It will take values in  $\mathcal{D}(\mathbf{R}^d)$  iff  $u \in \mathcal{E}'(\mathbf{R}^d)$ , Thus, convolution by  $u \in \mathcal{E}'(\mathbf{R}^d)$  is the general form of a continuous t.i.o. from  $\mathcal{D}(\mathbf{R}^d)$  to itself.
- Convolution by  $u \in \mathcal{E}'(\mathbf{R}^d)$  is the general form of a t.i.o. from  $C^{\infty}(\mathbf{R}^d)$  to itself.
- ▶ Convolution by  $u \in S'(\mathbb{R}^d)$  is the general form of a t.i.o. from  $S(\mathbb{R}^d)$  to  $C^{\infty}(\mathbb{R}^d)$ . It will take  $S(\mathbb{R}^d)$  to itself iff  $\hat{u} \in B(\mathbb{R}^d)$ .

## Translation invariant operators in spaces of distributions

- ► A basic fact of the spaces C<sup>∞</sup>(R<sup>d</sup>), D(R<sup>d</sup>) and S(R<sup>d</sup>) is that they are *reflexive*. This means that they equal their second dual.
- In other words, if ω : D'(R<sup>d</sup>) :→ C is a continuous linear functional, then there exists φ ∈ D(R<sup>d</sup>) such that ω(u) = ⟨u, φ⟩.
- Analogously, every continuous linear functional on *E'*(**R**<sup>d</sup>) is given by testing on some *φ* ∈ *S*(**R**<sup>d</sup>) and every continuous linear functional on *S'*(**R**<sup>d</sup>) is given by testing on some *φ* ∈ *S*(**R**<sup>d</sup>).
- Using this it is easy to prove that the general form of a continuous t.i.o. T : D'(R<sup>d</sup>) → D'(R<sup>d</sup>) or T : E'(R<sup>d</sup>) → E'(R<sup>d</sup>) is convolution by some uE'(R<sup>d</sup>).
- ► Convolution by  $u \in S'(\mathbf{R}^d)$  with  $\hat{u} \in \mathcal{B}(\mathbf{R}^d)$  is the general form of a continuous t.i.o. from  $S'(\mathbf{R}^d)$  to  $S'(\mathbf{R}^d)$ .

#### Hormander's theorem

- If X, Y are some spaces of tempered distributions in which  $S(\mathbf{R}^d)$  is dense, like all  $L^p(\mathbf{R}^d)$  spaces, every continuous t.i.p T from X to Y is given by convolution with some  $u \in S'(\mathbf{R}^d)$ .
- ► Indeed it will commute with convolution with  $L^1$  functions so  $T(\varphi * \psi) = \varphi * T(\psi) = T(\varphi) * \psi$ , hence

$$\hat{\varphi} * \widehat{T\psi} = \hat{\psi} \widehat{T\varphi}$$

hence  $\widehat{T\psi} = m\hat{\psi}, m = \frac{\widehat{T\varphi}}{\hat{\varphi}}.$ 

Choosing φ(x) = e<sup>-|x|</sup>, φ̂(ξ) is the Poisson kernel whose inverse has slow growth. Then m ∈ S'(R<sup>d</sup>)

### Fundamental solutions

- ▶ If  $T : D'(\mathbf{R}^d) : \to D'(\mathbf{R}^d)$  is t.i.o. we say that  $E \in D'(\mathbf{R}^d)$  is a fundamental solution if  $T(E) = \delta_0$ .
- In this case T(E \* f) = T(E) \* f = δ \* f = f whenever E \* f makes sense.
- Malgrange-Ehrenpreis theorem: every linear constant coefficient operator P(D) has a fundamental solution.
- Note that if T is a t.i.o. operator in S'(R<sup>d</sup>), then is convolution with u ∈ S'(R<sup>d</sup>) with û = m ∈ B(R<sup>d</sup>), so 1 = mÊ. If 1/m ∈ S'(R<sup>d</sup>), then the tempered distribution with Ê = 1/m is the fundamental solution.
- For the laplacian  $\Delta$ ,  $m(\xi) = -4\pi^2 |\xi|^2$  and  $E(x) = c_d |x|^{2-d}$ when d > 2 and  $E(x) = c_2 \log |x|$  when d = 2.
- It then follows that Δ(E \* f) = f in the sense of distributions for every f ∈ S(R<sup>d</sup>).
- Weyl's lemma: if f ∈ C<sup>∞</sup>(R<sup>d</sup>) and Δu = f in the sense of distributions, then u ∈ C<sup>∞</sup>(R<sup>d</sup>) and Δu = f in the classical sense.

The Poisson summation formula. An unified language for the Fourier transform

•  $\frac{1}{a}\widehat{\Delta_{\frac{1}{a}}} = \Delta_a$  as tempered distributions. This means exactly that

$$\sum_{n} \varphi(na) = \frac{1}{a} \sum_{n} \widehat{\varphi}(\frac{n}{a}), \varphi \in \mathcal{S}(\mathsf{R}^{\mathsf{d}}).$$

• Replacing  $\varphi$  by  $\tau_{-x}\varphi$  we get

$$\sum_{n} \varphi(x - na) = \frac{1}{a} \sum_{n} \widehat{\varphi}(\frac{n}{a}) e^{2\pi i x \frac{n}{a}},$$

or interchanging  $\varphi$  and  $\hat{\varphi}$ ,

$$\sum_{n} \hat{\varphi}(x - na) = \frac{1}{a} \sum_{n} \varphi(na) e^{-2\pi i x \frac{n}{a}}.$$

This is known as Poisson's summation formula and if fact holds for a much larger class of functions.

# A unified language

- Assume that f is a *a*-periodic function integrable in one period. It has a formal series  $\sum_{n} c_n(f) e^{2\pi i \frac{n}{a} \times}$ , not converge in general to f.
- Let us look at f as a tempered distribution and let us compute its Fourier transform.

$$\langle \hat{f}, \varphi \rangle = \langle f, \hat{\varphi} \rangle = \int_{\mathbf{R}} f(x)\hat{\varphi}(x) \, dx = \int_{0}^{a} f(x) \sum_{n} \hat{\varphi}(x - na) dx =$$
$$= \frac{1}{a} \int_{0}^{a} f(x) \sum_{n} \varphi(\frac{n}{a}) e^{-2\pi i x \frac{n}{a}} = \sum_{n} c_{n}(f)\varphi(\frac{n}{a})$$

This means that as a tempered distribution

$$\hat{f} = \sum_{n} c_n \delta_{\frac{n}{a}}$$

the sum being convergent in  $\mathcal{S}'(\mathbf{R}^d)$ .

By applying the inverse Fourier transform we find that

$$f = \sum_{n} c_{n}(f) e^{2\pi i \frac{n}{a} \times} \text{ in } \mathcal{S}'(\mathbf{R}^{\mathbf{d}}).$$